

Configuration Manual: An Optimised Deepfake Detection System Using Vision Transformers And FFT

MSc Research Project
MSc Data Analytics

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MSc Project Submission Sheet
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Programme: Msc Data Analytics
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An Optimised Deepfake Detection System Using Vision Transformers And FFT

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1) System Requirements

Component	Requirement
OS	Windows 10+, macOS 11+, or Ubuntu 20.04+
Python	3.9–3.11
GPU	CUDA GPU (≥ 12 GB VRAM recommended). CPU OK for inference, GPU strongly recommended for training
RAM	16GB min (32GB recommended)
Disk	~120GB for full FF++ videos; ~10–30GB for frames + checkpoints

2) Python Dependencies

Core:

```
pip install torch torchvision torchaudio --index-url https://download.pytorch.org/whl/cu121
```

```
pip install timm==1.0.9 opencv-python numpy scipy scikit-learn matplotlib tqdm pandas pillow
```

Optional / Tooling:

```
pip install jupyter ipywidgets rich tensorboard onnx onnxruntime
```

3) Model I/O Configuration

Task: Binary classification (Real vs Fake)

Branch	Input	Size	Normalization	Backbone	Output
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Branch	Input	Size	Normalization	Backbone	Output
Spatial (RGB)	RGB frame	224×224×3	ImageNet mean/std	Swin-Tiny (swin_tiny_patch4_window7_224)	768-d
Frequency (FFT)	FFT log-magnitude (gray→3ch)	224×224×3	mean=0.5 std=0.5	EfficientNet-B0	1280-d

Fusion & Head: concat → Dropout(0.3) → Linear(2048→1) → BCEWithLogits

Frame sampling: every 10th frame; max 10 frames/video

Output: frame-level logit → sigmoid(prob FAKE)

4) Data Pipeline

- **Dataset:** FaceForensics++ (c23 compression)
- **Sampling:** Every 10th frame, cap 10 per video
- **Transforms:**
 - RGB: resize 224, RandomHorizontalFlip(0.5), ToTensor, Normalize(ImageNet)
 - FFT: grayscale → fft2 → fftshift → $\log(1+|F|)$ → min-max [0,1] → replicate to 3ch → Normalize(mean=0.5, std=0.5)

5) Training Configuration

Parameter	Value
Epochs	20
Batch size	32 (adjust for VRAM)
Optimizer	AdamW (lr=1e-4, weight_decay=1e-2)
Loss	BCEWithLogitsLoss
Scheduler	StepLR(step_size=5, gamma=0.1)

Parameter	Value
AMP	Enabled (torch.cuda.amp)
Checkpoint	Save best by validation accuracy
Early stopping	Optional (patience 5)

6) Evaluation Metrics

- Accuracy (primary)
 - Precision, Recall, F1
 - ROC-AUC
 - Confusion matrix
 - (Optional) per-manipulation breakdown
-

7) Baseline Results

- **Best Val Acc:** ~85.86% (~epoch 15)
 - **Final Train Acc:** ~99.47% (epoch 20)
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8) Execution Instructions

As the full pipeline is coded in a single Jupyter Notebook (deepfake-detection.ipynb), the actual execution consists of simply going through the cells of the Notebook in order.

A) Open the Notebook:

1. Run file deepfake-detection.ipynb on Kaggle, Jupyter Lab, vscode.
2. Turning on GPU acceleration prior to run.

B) Execution Flow:

- 1.Setting up and Imports**-Compose dependencies; set constants (path, hyperparameters).
- 2. Dataset Preparation** - Read FF++ C23 dataset, sample frames, create FFT images and store it under real/ and fake/.
- 3.Transforms & Dataloaders** - Define RGB/FFT stream preprocessing, do train/validation split.

4.Model Definition = Build Hybrid Swin Transformer + EfficientNet model with fusion head.

5.Training Loop - Train specified epochs with mixed precision and saving the best checkpoint.

6.Test - Load the best checkpoint, calculate the metrics, draw the confusion matrix.

7.Inference -Predict on one image.

C) Run:

- Run all cells.
 - Change corresponding hyperparameters in the configuration cell on top of the notebook.
 - Make sure that paths to datasets are right in relation to your environment
-

9) Example Config (Notebook Variables)

seed: 42

data:

rgb_dir: data/frames_rgb

fft_dir: data/frames_fft

img_size: 224

every_n: 10

max_per_video: 10

train:

epochs: 20

batch_size: 32

amp: true

optimizer:

name: adamw

lr: 1.0e-4

weight_decay: 1.0e-2

scheduler:

name: step1r

step_size: 5
gamma: 0.1
model:
 spatial_backbone: swin_tiny_patch4_window7_224
 freq_backbone: efficientnet_b0
 dropout: 0.3
 fusion_dim: 2048
paths:
 out_dir: outputs
 ckpt_dir: outputs/checkpoints
logging:
 tensorboard: true