

Configuration Manual

MSc Research Project
M.Sc. Data Analytics

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Virtual Coach: Personalized Training Recommendations for Football Players Using Machine Learning and enhance the players performance

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1. Introduction

Football has in the recent past been transformed by the advanced technology both in the identification of talents and improving on the strategies used in the game. Today, it is not about just having a gadget, but about a gadget that makes a monumental difference to the gameplay and its precision. It is valid to talk about non-substitutions as goal-line technology and Video Assistant Referee (VAR) system has affected decision-making mechanisms. In this project we are trying to build the same and similar kind of assistant system. This config file will help you how to run the code and understand the code.

2. System Requirements

Notebook: Jupyter Notebook

RAM: 16GB

GPU: 12GB NVIDIA RTX 3010

Processor: Intel i9 12th Generation

Environment: Google and Anaconda

3. Setting Up the Environment

The first step in starting the implementation is to create the environment that includes installing the prerequisite software including Python, OpenCV, PyTorch and YOLOv5. After preparing the environment, download the Islamic Azad University Football Dataset (IAUFD) and make necessary changes in order to use it for training. The data is to be split into training and validation sets with the help of a data loader that will make the data processing easier during the training phase of the model.

```
#Datasets

!pip install roboflow

from roboflow import Roboflow
rf = Roboflow(api_key="8d9pP12P0bhURtZQqY81")
project = rf.workspace("university-tboyn").project("iaufd-football")
version = project.version(1)
dataset = version.download("yolov5")
```

Figure 1: Code snippet for the code setup

4. Transfer Learning with YOLO models

There is also an option to transfer learn by importing YOLO with weights from pre-trained sources. Modify some of the characteristics of the model so as to reflect the types of labels available within the IAUFD set. This takes the form of modifying the model structure in regard to the count of classes present in the dataset. For this task, YOLO should be taken as the base model and then the model is fine-tuned on IAUFD dataset.

5. Model Training

YOLOv5, as opposed to IAUFD, train and exploit the model. Training the model to a determinant number of epochs under strict accuracy check in conjunction with loss values will ensure increased knowledge acquisition. The best model weights are stored to be used in real-time detection as the model is being trained.

6. Real-Time Detection

In OpenCV, train the YOLOv5 to recognize football in real-time. Launch the webcam that captures video in real-time and use YOLOv5 to identify referees, players, goalkeepers and balls in each frame. To display the result, the detections will be shown in form of bounding boxes and labels on the detected objects in the frames.

```
def detect(self, video_path):
    results = self.model.predict(video_path)
    detections = []

    for box in results[0].boxes:
        class_idx = int(box.cls[0])
        class_name = results[0].names[class_idx]
        xyxy = box.xyxy[0].cpu().numpy()
        detections.append({
            'class_name': class_name,
            'coordinates': xyxy # coordinates
        })

    return detections
```

Figure 2: real time detection

7. Ball Tracking

To enrich the system, introduce ball tracking which would be detection of the position of the ball within each frame in which it is captured by the cameras. Extrapolate the respective location of the ball and attempt to sketch through the ball path using the coordinate plane of the video frames. In that way, they are able to take the game dynamics, such as in case of free-kick and penalties.

```

# Track ball positions
for detection in ball_detections:
    x1, y1, x2, y2 = detection['coordinates']
    center_x = int((x1 + x2) / 2)
    center_y = int((y1 + y2) / 2)
    ball_positions.append((center_x, center_y))

# Draw the ball trajectory
for i in range(1, len(ball_positions)):
    if ball_positions[i - 1] is None or ball_positions[i] is None:
        continue
    thickness = 6
    cv2.line(frame, ball_positions[i - 1], ball_positions[i], (0, 0, 255), thickness)

# Write the frame to the video file
out.write(frame)

```



Figure 3: Code Snippet for the ball tracking

8. Drive Location

Data: <https://universe.roboflow.com/university-tboyn/iaufd-football>

Code: <https://drive.google.com/drive/folders/1SOxcWdb4AV-eOUBaydsxtnZKWTsu130C?usp=sharing>

9. How to Run the Code

Step 1: Download the Data and put it in the Drive -> Or link the data in the colab file (Code is there)

Step 2: Open the Colab file

Step 3: Authenticate to provide access to the google drive and storage

Step 4: Run All

Step 5: Save the outputs

10. Conclusion and Future Work

The proposed application is intended to accommodate rural enthusiasts who are looking for means of self-betterment (in terms of their rockets) as well those consumers that are just genuinely passionate about the sport. It analyzes the angle of a shot, predicts its possible trajectory and adjusts tracking using real-time feedback. This method intended to allow users to increase their performance level by allowing them to diagnose and fix problems themselves, thereby improving the skill capacity of the user which would further resemble an ELO system meant for games.

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