

Configuration Manual

MSc Research Project
Programme Name

Forename Surname
Student ID: XXX

School of Computing
National College of Ireland

Supervisor: XXX

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MSc Project Submission Sheet
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1 Environment Setup in Google Colab

The Sentiment Echo Detection System (SEDS) was implemented and executed entirely within the Google Colab environment to leverage its GPU-accelerated computation capabilities. Before running the model, the runtime must be configured to use a T4 GPU by navigating to Runtime , Change runtime type and selecting GPU as the hardware accelerator. This step is critical for efficient training, as the model incorporates a Graph Convolutional Network (GCN) alongside ConvLSTM and attention mechanisms, which require high-performance matrix operations. The implementation uses Python 3.11 and relies on libraries such as PyTorch, PyTorch Geometric, scikit-learn, pandas, NumPy, and Sentence Transformers. Missing dependencies can be installed directly in Colab cells using pip commands, allowing for an iterative and error-tolerant setup process. Such cloud-based Jupyter environments have been shown to significantly accelerate the development and testing of machine learning models by providing scalable compute resources without local hardware constraints (Bisong, 2019; Google, 2023).

2 Data Preparation and Upload

The system runs preprocessed datasets from Amazon and Yelp reviews, each coupled with precomputed MiniLM embeddings saved in .npz files. Otherwise, data and embeddings have to be uploaded straight into the current Colab runtime using google.colab.files module. When uploading the datasets they also need to be all the same length — this means that each review will have a 384-dimensional semantic vector. Mismatch in the number of textual entries and embeddings will lead to a runtime error building the graph. The uploaded files would be saved in the volatile Colab storage during a session, and are lost when the runtime is reset or disconnected. This style of embedding-based graph modeling is common in the realm of natural language processing where using precomputed vector representations minimizes computational overhead and allows for more reproducible experimentation (Reimers & Gurevych, 2019; Kipf & Welling, 2017).

3 Model Execution and Output Interpretation

After the environment is setup and data uploaded, the master execution script can be fully executed. The training pipeline start with loading the datasets, constructing a heterogeneous graph with review-to-review edges and user review user temporal edges, input them into a two-layer GCN model upgraded with node attention mechanism and ConvLSTM temporal processing. It then trains the model for a number of epochs, showing you classification metrics like precision, recall, F1-score as well confusion matrices directly in the colab output cells. There are no intermediate outputs saved to disk, everything is rendered in line ranging from the attention weight distributions to the final polarization histograms. This in-memory, display-

based approach is great for the kind of exploratory research done in Colab, where rapid iteration and visual feedback are more important than long-term storage. (Abadi et al., 2016; Fey & Lenssen, 2019).

References

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Fey, M., & Lenssen, J. E. (2019). Fast graph representation learning with PyTorch Geometric. arXiv preprint arXiv:1903.02428. <https://doi.org/10.48550/arXiv.1903.02428>

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