

Configuration Manual

MSc Research Project Data Analytics

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Configuration Manual

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1 Introduction

This manual discusses in detail the instructions for configuring and deploying the tuberculosis detection system using pre-trained CNN models. A hybrid approach was implemented using deep learning models and transfer learning techniques to perfectly identifyTB infected from healthy cells.

2 System Requirements

Certain system requirements are needed for efficient model processing and minimizing the duration of time.

2.1 Hardware Requirements

The device used for the implementation was a Lenovo IdeaPad 330 with the below configurations:

- 1. Processor: Intel(R) Core (TM) i5-8250U CPU @ 1.60GHz 1.80 GHz
- 2. RAM: 8.00 GB
- 3. Hard Disk: 256GB SSD, 1 TB HDD
- 4. OS: Windows 10 Pro 64-bit

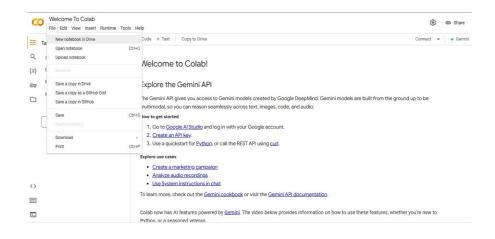
2.2 Software Requirements

Software	Information
Google Collab Platform	Cloud-based environment for running Python scripts.
Python	Google Collab uses version 3.8 or later.
TensorFlow/Keras	Building, training, and evaluating CNN models like Mo-
	bileNetV2 and DenseNet121.
NumPy	For mathematical and array manipulation.
Pandas	For managing and processing datasets.
Matplotlib/Seaborn	For visualizing data.
sci-kit-learn	For generating metrics like confusion matrices, precision,
	recall, and F1-scores.

Table 1: Software and their Information

3 Implementation

3.1 Sign in to Google Collab, create a new notebook, and mount it to Google Drive.



3.2 Import all the necessary libraries

```
!pip install tensorflow --upgrade
 Installing required libraries
!pip install xmltodict
!pip install tensorflow !pip install efficientnet
!pip install imbalanced-learn
import xml.etree.ElementTree as ET
import cv2
import matplotlib.pyplot as plt
import numpy as np
import random
from tensorflow.keras.applications import MobileNetV2
from tensorflow.keras.layers import Dense, GlobalAveragePooling2D
from tensorflow.keras.models import Model
from sklearn.model_selection import train_test_split
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras.callbacks import EarlyStopping
from tensorflow.keras.applications import DenseNet121
from tensorflow.keras.layers import Dense, GlobalAveragePooling2D, Dropout
from sklearn.metrics import classification_report, confusion_matrix
import seaborn as sns
```

3.3 Importing the dataset with positive and negative images and combining them into a single folder with all the images.

```
# Paths to the folders

positive_images_dir = '/content/drive/MyDrive/content/tb_positive/'
negative_images_dir = '/content/drive/MyDrive/content/tb_negative_augmented/'
bbox_images_dir = '/content/drive/MyDrive/content/tb_mages_bbox/'
all_images_dir = '/content/drive/MyDrive/content/all_images_box/'
all_images_dir = '/content/drive/MyDrive/content/all_images_2/' # Directory to store all images together

os.makedirs(all_images_dir, exist_ok=True)

# Copy images

def copy_images(src_dir, dst_dir, image_filenames=None):

if image_filenames is None:
    image_filenames = [f for f in os.listdir(src_dir) if f.endswith('.jpg')]

for filename in image_filenames:
    src_path = os.path.join(src_dir, filename)
    if os.path.exist(src_path):
        shutil.copy(src_path, dst_path)

positive_images = [f for f in os.listdir(positive_images_dir) if f.endswith('.jpg')]
negative_images = [f for f in os.listdir(negative_images_dir) if f.endswith('.jpg')]

# Combine all positive and negative images
all_images = positive_images + negative_images
# Copy all positive and negative images to the all_images directory
copy images(positive images dir, all images dir, positive images)
```

3.4 Preprocessing the dataset

```
from matplotlib.image import imread
# Paths to the folders
positive_images_dir = '/content/drive/MyDrive/content/tb_positive/' # Directory with positive images
negative_images_dir = '/content/drive/MyDrive/content/tb_negative_augmented/' # Directory with negative images
all_images_dir = '/content/drive/MyDrive/content/tb_negative_augmented/' # Directory with negative images
all_images_dir = '/content/drive/MyDrive/content/dlimages2/' # Directory to store all images together

# List all images in the positive and negative directories
positive_images = [f for f in os.listdir(positive_images_dir) if f.endswith('.jpg')]
negative_images = [f for f in os.listdir(negative_images_dir) if f.endswith('.jpg')]

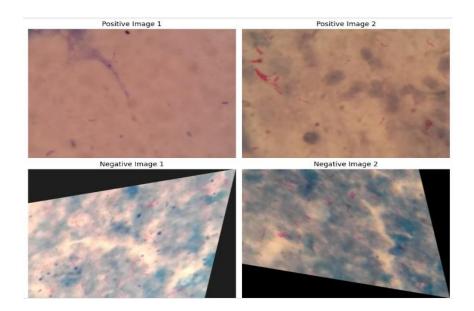
# Randomly select 2 positive and 2 negative images
selected_positive_images = random.sample(positive_images, 2)
selected_negative_images = random.sample(negative_images, 2)

# Plotting the images
fig, axes = plt.subplots(2, 2, figsize=(10, 8))

# Load and display positive images
for i, img_name in enumerate(selected_positive_images):
    ax = axes[i//2, i%2]
    img_path = os.path.join(positive_images_dir, img_name)
    img = imread(img_path)
    ax.imshow(img)
    ax.set_title(f'Positive Image {i+1}')
    ax.axis('off')

# Load and display negative images
for i, img_name in enumerate(selected_negative_images):
```

3.5 Visualizing the images in the dataset



3.6 Oversampling the minority class (Negative sample)

Due to class imbalance (less sample in negative class) oversampling was done in negative class with positive samples as 1863 and negative as 1863, and then splitting the dataset into train and validation for training the models.

3.7 Building a MobileNetV2 model

```
# Build the model
base_model = MobileNetv2(weights='imagenet', include_top=False, input_shape=(img_height, img_width, 3))
base_model.trainable = False  # Freeze the base model

x = base_model.output

x = GlobalAveragePooling2D()(x)
output = Dense(1, activation='sigmoid')(x)  # Removed intermediate Dense layers
model = Model(inputs=base_model.input, outputs=output)

# Compile the model
model.compile(optimizer='adam', loss='binary_crossentropy', metrics=['accuracy'])

# Add early stopping
early_stopping = EarlyStopping(monitor='val_accuracy', patience=2, restore_best_weights=True)

# Train the model
history = model.fit(
    train_dataset,
    validation_data=val_dataset,
    epochs=epochs,
    callbacks=[early_stopping]
)

# Save the model
model_path = '/content/drive/MyDrive/content/saved_model/mobilenetv2_tb_classifier.hs'
model.save(model_path)
print(f"Model saved to {model_path}")

# Evaluate the model
val_loss, val_accuracy = model.evaluate(val_dataset)
print(f"Validation accuracy: {val_accuracy * 100:.2f}%")
```

3.8 After Model implementation validation Accuracy is considered as evaluation factor

3.9 Building a DenseNet121 model

```
y_train_resampled = np.concatenate([y_train_subset, y_train_augmented])
train_dataset = tf.data.Dataset.from_tensor_slices((X_train_resampled, y_train_resampled)).batch(batch_size).shuffle(1000)

# Load DenseNet121 for feature extraction
base_model = DenseNet121(weights='imagenet', include_top=False, input_shape=(img_height, img_width, 3))
base_model.trainable = False # Freeze the base model

# Add custom layers
x = base_model.output
x = GlobalAverageroolingzD()(X)
output = Dense(1, activation='sigmoid')(X) # Sigmoid for binary classification
model = Model(inputs=base_model.input, outputs=output)

# Compile the model
model.compile(optimizer='adam', loss='binary_crossentropy', metrics=['accuracy'])

# Add early stopping
arrly_stopping = EarlyStopping(monitor='val_accuracy', patience=2, restore_best_weights=True)

# Train_the model
history = model.fit(
    train_dataset,
    validation_data=val_dataset,
    epochs=epochs,
    callbacks=[early_stopping]
)

# Save the model
model_path = '/content/drive/MyOrive/content/saved_model/densenet121_classifier.hs'
model.save(model_path)
print(f"Model saved to {model_path}")

# Evaluate the model
val_loss, val_accuracy = model.evaluate(val_dataset)
print(f"Woldel accuracy = model.evaluate(val_dataset)
print(f"Woldel accuracy = model.evaluate(val_dataset)
print(f"Woldel accuracy = wold.evaluate(val_dataset)
```

3.10 After Model implementation validation Accuracy is considered as evaluation factor

Total time taken:

MobileNetV2 model overall took 1009 seconds for the training time and evaluation time with the accuracy of 88.74%, and DenseNet121 model overall took 3274 seconds for the training time and evaluation time with the accuracy of 86.46%.

DenseNet121 is significantly slower, taking approx. 3.25x longer than MobileNetV2 for the same task.

To conclude, this code file includes one project file titled TB_detection.ipynb which includes both the models training and evaluation with the visualizations.

References

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