

Configuration Manual

MSc Research Project
Data Analytics

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Project Submission Sheet
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Configuration Manual

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1 Introduction

This configuration manual walks through the different stages of code development for the Few-Shot Thoracic Disease Classification Using Prototypical Networks. These stages include:

- Data Collection
- Data Preprocessing
- Implementation of Few-Shot Thoracic Disease Classification Using Prototypical Networks
- Evaluation of Systems

2 System Configuration

2.1 Hardware Specification

A configuration manual contains comprehensive setup instructions for a system or device. The goal of the handbook is to fully describe how to carry out the research study. It also details the machine setup needed to create and execute the models. The procedures include installing the necessary apps and packages as well as the basic configuration advised for a project to be successful.

The system was implemented on Google co-labs. The detailed description of the environment is in the figure below

Machine Source	Google Colabs
Type	GPU
Name	Tesla T4
RAM	16GB

Table 1: Environment Specification

2.2 Software and Libraries

The list below contains the libraries and software tools used for this research.

- Python 3
- Torch==2.1.0
- Torchvision==0.16.0
- Torch-summary==1.4.4
- Numpy >=1.24.0
- Pandas >=2.00
- Matplotlib >=3.7.0
- Scikit-learn >=1.3.0
- Opencv-python >=4.8.0
- VGG19,ResNet50 and DenseNet121 Model Weights

Download DenseNet121 Model Link

Download ResNet50 Model Link

Download VGG19 Model Link

2.3 Importing the required Libraries

Figure 1 below shows the number of packages and libraries imported for the classification task.

```
In [1]: from google.colab import drive
        drive.mount('/content/drive')

Mounted at /content/drive

In [1]: import sys
        sys.path.append('/content/drive/MyDrive/Researcher/PyTorch')
        import prototypical_network
        import torch_and_publication

In [1]: import torch
        import torch.nn as nn
        import torch.nn.functional as F
        import torchvision
        from torchvision.models import resnet18
        from torchvision.models import resnet50
        from torchvision.models import resnet101
        from torchvision.models import resnet152
        from torchvision.models import resnext101
        from torchvision.models import resnext101_32x8d
        from torchvision.models import resnext101_32x4d
        from torchvision.models import resnext101_32x8d_tq

import numpy as np
from torchvision.models import resnet18
import matplotlib.pyplot as plt

import random as rd
from sklearn.metrics import classification_report

import os
import sys
import random
import matplotlib.pyplot as plt
from sklearn.metrics import roc_curve, auc
from sklearn.metrics import confusion_matrix, ConfusionMatrixDisplay
import cv2
import time as tm
import torch.nn as nn
import torch.nn.functional as F
import torch.nn.init as init
import torch.nn.parallel as parallel

Collecting torch-summary==1.4.4
Installing torch-summary==1.4.4 to /opt/miniconda3/envs/py310/lib/python3.10/site-packages (17 MB)
Installing collected packages: torch-summary
Successfully installed torch-summary-1.4.4
```

Figure 1: Importing the necessary python libraries

3 Data Collection

For the research 2 datasets were used NIH Chest X-ray Image Data Set which is available on kaggle has a size of 2.5GB. Another dataset of x-ray images of Covid19 was also utilised which is also available on kaggle has a size of 187MB.

```

def read_images(directory_path, img_height, img_width, selected_class_names, augmentation=True,
               normalize=False, apply_color_flag=True, display_comparisons=False):
    data = []
    data = []

    sub_directories = os.listdir(directory_path)
    if selected_class_names is None:
        selected_class_names = sub_directories
    else:
        for cls in selected_class_names:
            if cls not in sub_directories:
                raise ValueError(f'Class "{cls}" not found in {directory_path}. Available classes: {sub_directories}')

    for sub_dir in selected_class_names:
        sub_dir_path = os.path.join(directory_path, sub_dir)
        correct_image_filenames = check_image_path(sub_dir_path)

        for fnam in correct_image_filenames:
            image = cv.imread(fnam)
            image = cv.cvtColor(image, cv.COLOR_BGR2RGB)
            image = cv.resize(image, (img_width, img_height))
            original_image = image.copy()

            if apply_color_flag:
                enhanced_image = apply_color(image)
                image = enhanced_image

            if augmentation:
                image_tensor = cv.convert_to_tensor(image, dtype=cv_32f)
                augmented_image = augmentation_layer(image_tensor) # Apply augmentation layer
                augmented_image = augmented_image.numpy().astype(np.uint8) # Convert back to numpy array

            if normalize:
                image = image / 255.0

            if display_comparisons:
                display_image_comparison(original_image, enhanced_image, augmented_image)

            data.append(image)
            data.append(sub_dir)

    return np.array(data), np.array(data)

```

Figure 2: Read Images Functions

[NIH Chest X-ray Dataset Link](#)

[Covid19 Dataset Link](#)

4 Data Preprocessing

To train the dataset for this research different techniques were utilised. All the techniques of preprocessing applied on the data are as below:

- **Input Validation** Checks for valid image extensions (.png, .jpg, .jpeg) and verifies existence of specified classes in the directory
- **Image Resizing** All images are resized to a fixed size of $224 \times 224 \times 3$ pixels (HEIGHT \times WIDTH \times CHANNELS). This standardization is crucial for deep learning models that expect consistent input dimensions
- **Color Space Conversion** Images are first read in BGR format (OpenCV default) Converted from BGR to RGB color space using cv2.
- **CLAHE** Contrast Limited Adaptive Histogram Equalization) Converts image to grayscale and applies CLAHE with clip limit of 2.0 and tile grid size of 8×8 then converts it back to RGB. It Helps improve contrast and enhance image details.
- **Random Horizontal Flipping** It Randomly flips images horizontally which helps model learn orientation-invariant features.
- **Random Zoom** Height factor range: -1% to +10% and Width factor range: -10% to +10% to adds robustness to scale variations

5 System Implementation

Starting by loading the pretrained models which will be our feature extractors

After loading we will freeze the model to stops any parameter updates during back-propagation and Flatten outputs from the Convolutional base networks and remove the Linear layers

```
def apply_clahe(image, clip_limit=2.0, tile_grid_size=(8, 8)):
    gray_image = cv2.cvtColor(image, cv2.COLOR_RGB2GRAY)
    clahe = cv2.createCLAHE(clip_limit=clip_limit, tileGridSize=tile_grid_size)
    enhanced_image = clahe.apply(gray_image)
    enhanced_image_rgb = cv2.cvtColor(enhanced_image, cv2.COLOR_GRAY2RGB)
    return enhanced_image_rgb
```

Figure 3: Clahe Function

```
augmentation_layer = Sequential([
    layers.RandomFlip(mode='horizontal', seed=CFG.TF_SEED),
    layers.RandomZoom(height_factor=(-.01, 0.1), width_factor=(-0.1, 0.1), seed=CFG.TF_SEED)
], name='augmentation_layer')
```

Figure 4: Augmentation Layer

```
def check_image_path(directory):
    return [os.path.join(directory, f) for f in os.listdir(directory) if f.endswith(('.png', '.jpg', '.jpeg'))]
```

Figure 5: Image path

```
for fpath in correct_image_filepaths:
    image = cv2.imread(fpath)
    image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
    image = cv2.resize(image, (img_width, img_height))
```

Figure 6: Resize and Color Space Code

After that we will be doing episodic learning using prototypical network and calculate euclidean distance between feature vectors which can be seen in the figure below

Then we will be doing episodic learning with Prototypical Network on a test set and saves every 100th episode result to a CSV file.

6 Evaluation

Evaluation in the code was done using classification reports , confusion matrix and plotting ROC Curves. Predict Function to test samples can be seen in the figure 17 below

```

In [19]: resnet50_model = models.resnet50(pretrained=True)

/usr/local/lib/python3.6/dist-packages/torchvision/models/_utils.py:388: UserWarning: The parameter 'pretrained' is
at least since 0.13 and may be removed in the future, please use 'weights' instead.
  warnings.warn(

/usr/local/lib/python3.6/dist-packages/torchvision/models/_utils.py:388: UserWarning: Arguments other than a weight
or 'None' for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent
to using 'weights=torchvision.models.DEFAULT_WEIGHTS'. You can also use 'weights=torchvision.models.DEFAULT' to get the next
set of weights.
  warnings.warn(

/usr/local/lib/python3.6/dist-packages/torchvision/models/_utils.py:388: UserWarning: The parameter 'pretrained' is
at least since 0.13 and may be removed in the future, please use 'weights' instead.
  warnings.warn(

In [20]: resnet50_model = resnet50_model.to(device)
print(resnet50_model)

ResNet(
  (conv1): Conv2d(3, 64, kernel_size=[7, 7], stride=[2, 2], padding=[3, 3], bias=False)
  (bn1): BatchNorm2d(64, eps=0e-05, momentum=0.1, affine=True, track_running_stats=True)
  (relu): ReLU(inplace=True)
  (maxpool): MaxPool2d(kernel_size=3, stride=2, padding=1, dilation=1, ceil_mode=False)
  (layer1): Sequential(
    (0): Bottleneck(
      (conv1): Conv2d(64, 64, kernel_size=[1, 1], stride=[1, 1], bias=False)
      (bn1): BatchNorm2d(64, eps=0e-05, momentum=0.1, affine=True, track_running_stats=True)
      (conv2): Conv2d(64, 64, kernel_size=[3, 3], stride=[1, 1], padding=[1, 1], bias=False)
      (bn2): BatchNorm2d(64, eps=0e-05, momentum=0.1, affine=True, track_running_stats=True)
      (conv3): Conv2d(256, 64, kernel_size=[1, 1], stride=[1, 1], bias=False)
      (bn3): BatchNorm2d(64, eps=0e-05, momentum=0.1, affine=True, track_running_stats=True)
      (relu): ReLU(inplace=True)
      (downsample): Sequential(
        (0): Conv2d(64, 64, kernel_size=[1, 1], stride=[1, 1], bias=False)
        (1): BatchNorm2d(64, eps=0e-05, momentum=0.1, affine=True, track_running_stats=True)
      )
    )
  )
)

```

Figure 7: ResNet50 Model

```

In [21]: densenet121_model = models.densenet121(pretrained=True)

/usr/local/lib/python3.6/dist-packages/torchvision/models/_utils.py:388: UserWarning: The parameter 'pretrained' is
at least since 0.13 and may be removed in the future, please use 'weights' instead.
  warnings.warn(

/usr/local/lib/python3.6/dist-packages/torchvision/models/_utils.py:388: UserWarning: Arguments other than a weight
or 'None' for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent
to using 'weights=torchvision.models.DEFAULT_WEIGHTS'. You can also use 'weights=torchvision.models.DEFAULT' to get the
next set of weights.
  warnings.warn(

/usr/local/lib/python3.6/dist-packages/torchvision/models/_utils.py:388: UserWarning: The parameter 'pretrained' is
at least since 0.13 and may be removed in the future, please use 'weights' instead.
  warnings.warn(

In [22]: densenet121_model = densenet121_model.to(device)
print(densenet121_model)

DenseNet(
  (features): Sequential(
    (0): Conv2d(3, 64, kernel_size=[7, 7], stride=[2, 2], padding=[3, 3], bias=False)
  )
)

```

Figure 8: DenseNet121 Model

```

In [23]: vgg11_model = models.vgg11(pretrained=True)

/usr/local/lib/python3.6/dist-packages/torchvision/models/_utils.py:388: UserWarning: The parameter 'pretrained' is
at least since 0.13 and may be removed in the future, please use 'weights' instead.
  warnings.warn(

/usr/local/lib/python3.6/dist-packages/torchvision/models/_utils.py:388: UserWarning: Arguments other than a weight
or 'None' for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent
to using 'weights=torchvision.models.DEFAULT_WEIGHTS'. You can also use 'weights=torchvision.models.DEFAULT' to get the
next set of weights.
  warnings.warn(

/usr/local/lib/python3.6/dist-packages/torchvision/models/_utils.py:388: UserWarning: The parameter 'pretrained' is
at least since 0.13 and may be removed in the future, please use 'weights' instead.
  warnings.warn(

In [24]: vgg11_model = vgg11_model.to(device)
print(vgg11_model)

VGG(
  (features): Sequential(
    (0): Conv2d(3, 64, kernel_size=[3, 3], stride=[1, 1], padding=[1, 1])
  )
)

```

Figure 9: VGG19 Model

```

In [10]: for param in vgg11_model.parameters():
param.requires_grad = False

In [11]: vgg11_model.eval()
summary(vgg11_model, (1, 3, 224, 224), device=device)

Layer (type:depth-idx)           Output Shape         Param #
-----
Sequential: 1-1                  [-1, 112, 1, 1]      --
  |--Conv2d: 2-1                  [-1, 64, 112, 112]   (1,400)
  |--BatchNorm2d: 2-2             [-1, 64, 112, 112]   (128)
  |--ReLU: 2-3                   [-1, 64, 112, 112]   --
  |--MaxPool2d: 2-4              [-1, 64, 56, 56]     --
  |--Sequential: 2-5              [-1, 256, 56, 56]     --
    |--BatchConv2d: 2-1          [-1, 256, 56, 56]     (1,400)
    |--BatchNorm2d: 2-2          [-1, 256, 56, 56]     (128)
    |--ReLU: 2-3                 [-1, 256, 56, 56]     --
    |--BatchConv2d: 2-4          [-1, 256, 56, 56]     (1,400)
    |--BatchNorm2d: 2-5          [-1, 256, 56, 56]     (128)
    |--ReLU: 2-6                 [-1, 256, 56, 56]     --
    |--Conv2d: 2-7               [-1, 128, 28, 28]     (1,280)

```

Figure 10: VGG19 Freeze And Flatten

```

In [9]: for param in resnet50_model.parameters():
param.requires_grad = False

In [10]: resnet50_model.fc = nn.Flatten()
summary(resnet50_model, (1, 3, 224, 224), device=device)

Layer (type:depth-idx)           Output Shape         Param #
-----
Conv2d: 1-1                      [-1, 64, 112, 112]   (1,400)
BatchConv2d: 1-2                 [-1, 64, 112, 112]   (128)
ReLU: 1-3                        [-1, 64, 112, 112]   --
BatchConv2d: 1-4                 [-1, 64, 56, 56]     --
Sequential: 1-5                  [-1, 256, 56, 56]     --
  |--BatchConv2d: 2-1          [-1, 256, 56, 56]     (1,400)
  |--BatchNorm2d: 2-2          [-1, 256, 56, 56]     (128)
  |--ReLU: 2-3                 [-1, 256, 56, 56]     --
  |--BatchConv2d: 2-4          [-1, 256, 56, 56]     (1,400)
  |--BatchNorm2d: 2-5          [-1, 256, 56, 56]     (128)
  |--ReLU: 2-6                 [-1, 256, 56, 56]     --
  |--Conv2d: 2-7               [-1, 128, 28, 28]     (1,280)

```

Figure 11: ResNet50 Freeze and Flatten

```

In [9]: for param in densenet121_model.parameters():
param.requires_grad = False

In [10]: densenet121_model.classifier = nn.Flatten()
summary(densenet121_model, (1, 3, 224, 224), device=device)

Layer (type:depth-idx)           Output Shape         Param #
-----
Sequential: 1-1                  [-1, 1024, 1, 1]     --
  |--Conv2d: 2-1                  [-1, 64, 112, 112]   (1,400)
  |--BatchConv2d: 2-2            [-1, 64, 112, 112]   (128)
  |--ReLU: 2-3                   [-1, 64, 112, 112]   --
  |--MaxPool2d: 2-4              [-1, 64, 56, 56]     --
  |--BatchConv2d: 2-5            [-1, 256, 56, 56]     (1,400)
  |--BatchNorm2d: 2-6            [-1, 256, 56, 56]     (128)
  |--ReLU: 2-7                   [-1, 256, 56, 56]     --
  |--BatchConv2d: 2-8            [-1, 256, 56, 56]     (1,400)
  |--BatchNorm2d: 2-9            [-1, 256, 56, 56]     (128)
  |--ReLU: 2-10                  [-1, 256, 56, 56]     --
  |--Transition: 2-11           [-1, 128, 28, 28]     (1,280)

```

Figure 12: DenseNet121 Freeze and Flatten

```

class PrototNet(nn.Module):
    def __init__(self, encoder, device="CPU"):
        super(PrototNet, self).__init__()
        self.device = device
        self.encoder = encoder.to(self.device)

    def set_forward_loss(self, sample):
        sample_images = sample['images'].to(self.device) # retrieve the support + query images
        n_way = sample['n_way'] # get no. of classes in sample
        n_support = sample['n_support'] # no. of support images in each class
        n_query = sample['n_query'] # no. of query images in each class

        # separate the support and query images
        x_support = sample_images[:, :n_support]
        x_query = sample_images[:, n_support:]

        target_inds = 0 ... n_way-1
        target_inds = torch.arange(0, n_way).view(n_way, 1).expand(n_way, n_query, 1).long() # result = torch.Size([n_way, n_query, 1])
        target_inds = Variable(target_inds, requires_grad=False)
        target_inds = target_inds.to(self.device)

        #encode images of the support and the query set
        x = torch.cat([x_support.contiguous().view("n_support", "n_query.size([1]-1)"),
            x_query.contiguous().view("n_way - n_support", "n_query.size([1]-1)"), 0])

        z = self.encoder.forward(x) # returns embedded vector
        z_dim = z.size(-1) # get the size of the flattened vector
        # find the mean, that becomes the class prototype
        z_proto = [n_way*n_support].view(n_way, n_support, z_dim).mean(1)
        z_query = [n_way*n_support:]

        #compute distances between vectors of images in the query set and the class prototypes
        dists = euclidean_dist(z_query, z_proto)

        #compute probabilities
        log_p_y = F.log_softmax(-dists, dim=-1).view(n_way, n_query, -1)

        loss_val = -log_p_y.gather(2, target_inds).squeeze().view(-1).mean()
        ... y_hat = log_p_y.max(2)
        acc_val = torch.eq(y_hat, target_inds.squeeze()).float().mean()

        # Collect predictions and true labels
        y_true = target_inds.squeeze().cpu().numpy()
        y_pred = y_hat.cpu().numpy()

        return loss_val, {
            'loss': loss_val.item(),
            'acc': acc_val.item(),
            'y_hat': y_hat,
            'y_true': y_true,
            'y_pred': y_pred
        }

```

Figure 13: Prototypical Network with Forward Loss Function

```

# Function to compute the Euclidean distance between feature vectors
def euclidean_dist(x, y):
    """
    Computes euclidean distance btw x and y

    Args:
        x (torch.Tensor): shape (n, d). n usually n_way*n_query
        y (torch.Tensor): shape (m, d). m usually n_way

    Returns:
        torch.Tensor: shape(n, m). For each query, the distances to each centroid

    """
    n = x.size(0)
    m = y.size(0)
    d = x.size(1)
    assert d == y.size(1)

    x = x.unsqueeze(1).expand(n, m, d)
    y = y.unsqueeze(0).expand(n, m, d)

    return torch.pow(x - y, 2).sum(2)

```

Figure 14: Euclidean Distance Function

```

def test_model_on_new_task(model, n_way, n_support, n_query, test_episodes, n_test, n_test, output_dir, file_name):
    """
    Tests the Prototypical Network on a test set and saves every 100th episode result to a CSV file.

    Args:
        model: trained model
        n_way (int): number of classes in a classification task
        n_support (int): number of images per class in the support set
        n_query (int): number of images per class in the query set
        test_episodes (int): number of episodes to test on
        n_test (np.array): images of testing set
        y_test (np.array): labels of testing set
        output_dir (str): Directory to save the CSV file
        file_name (str): The name of the CSV file to save results

    Returns:
        avg_loss (float): average loss
        avg_acc (float): average accuracy
    """
    running_loss = 0.0
    running_acc = 0.0

    results = []
    model.eval()

    print("Training loss and accuracy every 100 episodes:")
    with torch.no_grad():
        for episode in range(test_episodes):
            sample = train_and_evaluation.extract_sample(n_way, n_support, n_query, n_test, y_test)
            loss, output = model.set_forwards(sample)
            running_loss += output['loss']
            running_acc += output['acc']

            if episode % 100 == 0:
                print(f"episode: {episode} ----> loss: {output['loss']:.4f}, Accuracy: {output['acc']:.4f}")
                results.append({
                    'episode': episode,
                    'loss': output['loss'],
                    'accuracy': output['acc']
                })

    avg_loss = running_loss / test_episodes
    avg_acc = running_acc / test_episodes

    if not os.path.exists(output_dir):
        os.makedirs(output_dir)

    csv_path = os.path.join(output_dir, file_name)
    df = pd.DataFrame(results)
    df.to_csv(csv_path, index=False)

    return avg_loss, avg_acc

```

Figure 15: Episodic Learning Function



Figure 16: 2 way 3 shot Configuration

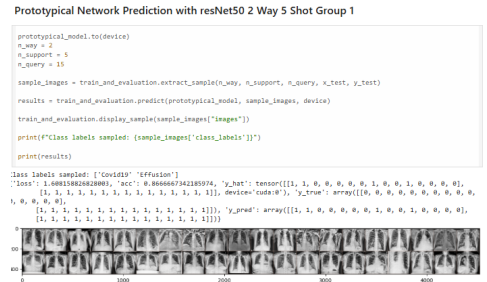


Figure 17: 2 way 5 shot Configuration

```

def predict(model, sample, device="cpu"):
    """
    Args:
        model (object): trained prototypical model
        sample (dict): dictionary containing the following keys:
            images - images for the support + query set
            n_way - number of classes to sample
            n_support - number of support images
            n_query - number of query images

        device (str): device to run the model on - 'cpu' or 'cuda'

    Returns:
        output (dict): dictionary with the following keys:
            loss - loss value
            acc - accuracy of prediction
            y_hat - prediction tensor for each query image in each class
    """
    model.to(device)
    output = model.set_forwards(sample)

    return output

```

Figure 18: Predict Function

The Figure below 18 shows the function for calculating classification report.

```
def generate_classification_report(results, sample_images):
    y_true_flat = results["y_true"].flatten()
    y_pred_flat = results["y_pred"].flatten()

    class_labels = sample_images["class_labels"]
    label_mapping = {i: label for i, label in enumerate(class_labels)}

    report = classification_report(y_true_flat, y_pred_flat, target_names=class_labels)
    return report
```

Figure 19: Code for Classification Report

The Figure 19 below shows the function to plot the confusion matrix

```
def plot_confusion_matrix(y_true, y_pred, class_labels):
    conf_matrix = confusion_matrix(y_true, y_pred)

    cmap = plt.cm.Blues
    plt.figure(figsize=(8, 6))
    disp = ConfusionMatrixDisplay(conf_matrix, display_labels=class_labels)

    disp.plot(cmap=cmap, values_format='d')

    plt.title("Confusion Matrix", fontsize=12, pad=20)
    plt.grid(False)
    plt.colorbar(disp.im_, fraction=0.046, pad=0.04)

    plt.tight_layout()
    plt.show()
```

Figure 20: Code For Plotting Confusion Matrix

The Figure 20 below shows the function to plot ROC Curve

```
def plot_roc_curve(results):
    """
    Generates and plots the Receiver Operating Characteristic (ROC) curve.
    """

    y_true_flat = results["y_true"].flatten()
    y_scores = results["y_pred"].flatten()

    fpr, tpr, thresholds = roc_curve(y_true_flat, y_scores, pos_label=1)
    roc_auc = auc(fpr, tpr)

    plt.figure()
    plt.plot(fpr, tpr, color='blue', label=f'ROC curve (area = {roc_auc:.2f})')
    plt.plot([0, 1], [0, 1], color='gray', linestyle='--')
    plt.xlabel('False Positive Rate')
    plt.ylabel('True Positive Rate')
    plt.title('Receiver Operating Characteristic (ROC) Curve')
    plt.legend(loc="lower right")
    plt.show()
```

Figure 21: Code for Plotting ROC Curve

Figure below shows the code to compare accuracy and loss during episodic learning

```
fig, (ax1, ax2) = plt.subplots(1, 2, figsize=(15, 7))

# Plot Accuracy on the first subplot (ax1)
ax1.plot(df_vgg_2way_3shot['Episode'], df_vgg_2way_3shot['Accuracy'], label='VGG19 Accuracy', color='blue')
ax1.plot(df_resnet_2way_3shot['Episode'], df_resnet_2way_3shot['Accuracy'], label='ResNet50 Accuracy', color='green')
ax1.plot(df_densenet_2way_3shot['Episode'], df_densenet_2way_3shot['Accuracy'], label='DenseNet121 Accuracy', color='red')
ax1.set_xlabel('Episodes')
ax1.set_ylabel('Accuracy')
ax1.set_title('Accuracy vs Episodes (2-Way 3-Shot)')
ax1.legend(loc='upper left')

# Plot Loss on the second subplot (ax2)
ax2.plot(df_vgg_2way_3shot['Episode'], df_vgg_2way_3shot['Loss'], label='VGG19 Loss', color='blue', linestyle='--')
ax2.plot(df_resnet_2way_3shot['Episode'], df_resnet_2way_3shot['Loss'], label='ResNet50 Loss', color='green', linestyle='--')
ax2.plot(df_densenet_2way_3shot['Episode'], df_densenet_2way_3shot['Loss'], label='DenseNet121 Loss', color='red', linestyle='--')
ax2.set_xlabel('Episodes')
ax2.set_ylabel('Loss')
ax2.set_title('Loss vs Episodes (2-Way 3-Shot)')
ax2.legend(loc='upper left')

# Adjust the layout to make sure everything fits
plt.tight_layout()

# Show the plot
plt.show()
```

Figure 22: Code for Comparing Accuracy and Loss

```
def plot_metrics_from_csv(csv_files, figsize=(11, 7)):
    """
    Plots precision, recall, and F1 score for multiple models from CSV files.

    Parameters:
    csv_files: Variable length argument list of CSV file paths.
    figsize: Tuple specifying the size of the figure, default is (11, 7).
    Returns: None, displays the plot.
    """
    metrics = ['Precision', 'Recall', 'F1 Score']
    data = {}
    models = []

    for csv_file in csv_files:
        model_name = csv_file.split('/')[-1].split('.')[0] # Assuming model name is in the directory name
        models.append(model_name)
        df = pd.read_csv(csv_file)

        def compute_metrics(df):
            y_true = df['True Class'].values
            y_pred = df['Pred Class'].values
            return {
                'precision_score': precision_score(y_true, y_pred, average='weighted'),
                'recall_score': recall_score(y_true, y_pred, average='weighted'),
                'f1_score': f1_score(y_true, y_pred, average='weighted')
            }

        precision, recall, f1 = compute_metrics(df)
        data[model_name] = {metric: compute_metrics(df) for metric in metrics}
        data[model_name].update({'model': model_name})

    # Create the plot
    fig, ax = plt.subplots(figsize=figsize)
    x = range(len(models))
    width = 0.25

    for i, metric in enumerate(metrics):
        offset = width * i
        for j, model in enumerate(models):
            ax.bar(x + offset + j*width, data[model][metric], width=width, label=metric)

    ax.set_xlabel('Model')
    ax.set_ylabel('Comparison of Precision, Recall, and F1 Score Across Models')
    ax.set_xticks([i + width * len(models) for i in range(len(models))])
    ax.set_xticklabels(models)
    ax.legend()

    plt.tight_layout()
    plt.show()
```

Figure 23: Function to compare metrics of different models