

Configuration Manual

MSc Research Project Data Analytics

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Programme:	Data Analytics
Year:	2025
Module:	MSc. Research Project
Supervisor:	Arjun Chikkankod
Submission Due Date:	03/01/2025
Project Title:	Configuration Manual
Word Count:	1050
Page Count:	8

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Configuration Manual

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1 Introduction

This document provides a comprehensive overview of the hardware and software configurations essential for the successful implementation of this research project. It encompasses details on the computational environment setup, the dataset used, the libraries and tools required, and the step-by-step process of model preparation and analysis.

The dataset, sourced from the MetroPT3 system, contains time-series sensor readings critical for identifying machine failures. To prepare the data for analysis, preprocessing steps include cleaning, feature engineering with rolling statistics and handling class imbalance while maintaining the temporal integrity of the data. The project employs Random Forest as the predictive model. SHAP is integrated to enhance interpretability, providing both global and local insights into the model's decision-making process. This comprehensive configuration ensures that the research achieves its dual objectives of delivering actionable insights for predictive maintenance and demonstrating the practical value of Explainable AI techniques.

2 System Configurations

The project was implemented under the following configurations:

2.1 Local Machine



Figure 1: System Configuration on Local Machine.

2.2 GPU Configuration

In this research project, all code development is conducted using Google Colab Pro+, Google's computing platform.

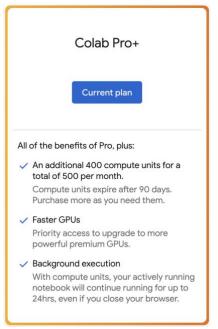


Figure 2: Google Colab Pro+ Specifications.

3 Project Implementation

The project was implemented under the following configurations:

3.1 Data Collection

The dataset, MetroPT3, which is available at UC Irvine Machine Learning Repository, is a time-series dataset collected from the air compressors of Metro do Porto trains. It comprises 15,169,480 data points recorded at a 1Hz frequency from February to August 2020, characterized by 15 features derived from 7 analog and 8 digital sensors. The analog sensors monitor critical metrics such as compressor pressure (TP2), pneumatic panel pressure (TP3), pressure drop during cyclonic separator discharge (H1), and motor current, among others, providing detailed insights into the system's physical operations. The digital sensors capture key operational signals, such as the air intake valve state (COMP), compressor outlet valve status (DV electric), and tower operations for air drying (TOWERS). These combined features comprehensively represent the compressor's functional state and operational environment, enabling effective predictive maintenance analysis.

4 Package Requirements

The following Python libraries were used in the implementation:

- **Pandas**: For data manipulation and preprocessing.
- **NumPy**: For numerical computations.
- Matplotlib: For data visualisation.

- Scikit-learn: For Random Forest implementation and evaluation.
- **SHAP**: For explainability analysis of the Random Forest model.
- Google Colab Environment: For GPU-accelerated model training and SHAP computations.

5 Model Preparation

This section explains the detailed steps involved in preparing the dataset for modelling. The objective is to clean and transform the data to improve the performance of the Random Forest model for predictive maintenance. Each step corresponds to a specific purpose in the pipeline.

Basic data inspection was done as can be seen in Fig. 3.

```
Dataset Information:
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 1516948 entries, 0 to 1516947
Data columns (total 17 columns):
#
     Column
                     Non-Null Count
                                        Dtype
0
    Unnamed: 0
                      1516948 non-null int64
    timestamp
                      1516948 non-null
                                       object
1
                      1516948 non-null
2
    TP2
                                       float64
3
    TP3
                      1516948 non-null
                                       float64
 4
                      1516948 non-null float64
5
    DV_pressure
                      1516948 non-null float64
    Reservoirs
                                       float64
                      1516948 non-null
6
    Oil_temperature 1516948 non-null
                                        float64
 8
    Motor_current
                      1516948 non-null
                                        float64
    COMP
9
                      1516948 non-null
                                        float64
    DV_eletric
                                       float64
                      1516948 non-null
10
                      1516948 non-null
    Towers
                                       float64
11
    MPG
                      1516948 non-null
12
13
    LPS
                      1516948 non-null
                                       float64
    Pressure_switch 1516948 non-null
 14
                                       float64
15
    Oil_level
                      1516948 non-null
                                       float64
    Caudal_impulses 1516948 non-null
dtypes: float64(15), int64(1), object(1)
memory usage: 196.7+ MB
None
```

Figure 3: Dataset information.

The dataset was checked for missing values (Fig. 4) and irrelevant columns were dropped (Unnamed) to ensure relevance.

```
Missing Values Count:
timestamp
TP2
                    0
TP3
                    0
H1
                    0
DV_pressure
                    0
Reservoirs
                    0
                    0
0il_temperature
Motor_current
                    0
COMP
                    0
DV_eletric
                    0
Towers
                    0
MPG
                    0
LPS
                    0
Pressure_switch
                    0
Oil_level
                    0
Caudal_impulses
dtype: int64
```

Figure 4: Missing values count.

Based on the failure report provided by the company, four distinct failure events were identified and incorporated into the dataset. A new target feature, labelled as "status," was introduced to indicate the operational state of the system. For each data point, the "status" was assigned a value of 1 if it corresponded to a failure event, and 0 otherwise, representing normal operation. This binary classification enabled the dataset to be structured for supervised learning, facilitating the prediction of failure events and enhancing the accuracy of the predictive maintenance model. The process ensured that the labelling accurately reflected the real-world scenarios described in the failure report, making the dataset a robust foundation for modeling (Fig. 5).

Figure 5: Labelling the dataset.

The class distribution was analysed (Fig. 6) to assess the degree of imbalance in the dataset, highlighting potential challenges in achieving a clean and balanced representation of the target variable.



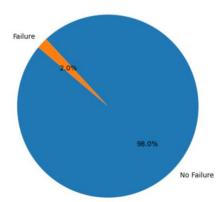


Figure 6: Class Imbalance.

Subsequently, a detailed correlation analysis was conducted to identify features with the strongest relationship to the target feature "status" (Fig. 7).

```
# Separating analog and digital sensors
analog_features = ['TP2', 'TP3', 'H1', 'DV_pressure', 'Reservoirs', 'Oil_temperature', 'Motor_current']
digital_features = ['COMP', 'DV_eletric', 'Towers', 'MPG', 'LPS', 'Pressure_switch', 'Oil_level', 'Caudal_impulses']

# Calculating correlations for analog features
analog_corr = data[analog_features + ['status']].corr()
print("\Analog_corr['status'])

# Checking correlation among digital sensors
digital_corr = data[digital_features + ['status']].corr()
print("\ADigital Features Correlation Matrix with Target:")
print(digital_corr['status'])

# Combining digital and analog correlations for inspection
combined_features = analog_features + digital_features
combined_corr = data[combined_features + ['status']].corr()
print("\Combined_Features Correlation Matrix with Target:")
print(combined_corr['status'])
```

Figure 7: Calculating correlations.

Features with weak or negligible correlations were removed to reduce noise and improve model efficiency (Fig. 8).

Figure 8: Dropping features.

'MPG', 'LPS', 'status'],

dtype='object')

To enhance the dataset further, rolling mean and standard deviation values were computed and added for key analog and digital sensor features (Fig. 9), capturing temporal trends and fluctuations critical for time-series analysis. Any missing values introduced during this process were systematically handled using forward and backward fill methods to ensure data integrity.

```
# Define rolling window size
rolling_window = 180

# Adding rolling mean and standard deviation for key analog features
for feature in ['DV_pressure', 'Motor_current', 'Oil_temperature', 'TP2', 'H1']:
    data[f'{feature}_rolling_mean'] = data[feature].rolling(window=rolling_window, min_periods=1).mean()
    data[f'{feature}_rolling_std'] = data[feature].rolling(window=rolling_window, min_periods=1).std()

# Adding rolling mean for key digital features
for feature in ['DV_eletric', 'COMP', 'MPG']:
    data[f'{feature}_rolling_mean'] = data[feature].rolling(window=rolling_window, min_periods=1).mean()

# Verifying the new features
print(data.head())
```

Figure 9: Rolling mean and standard deviation.

The dataset was then split into training and testing subsets, maintaining the sequential nature of the time-series data to preserve temporal dependencies (Fig. 10).

```
# Define a timestamp-based split point
split_timestamp = "2020-06-07 00:00:00" # Adjust based on the failure report
# Split the dataset into training and testing sets
train = data[data['timestamp'] < split_timestamp]</pre>
test = data[data['timestamp'] >= split_timestamp]
# Verify the split
print("Training Set Class Distribution:")
print(train['status'].value_counts())
print("\nTesting Set Class Distribution:")
print(test['status'].value_counts())
# Output dataset shapes
print(f"Training set size: {train.shape}")
print(f"Testing set size: {test.shape}")
Training Set Class Distribution:
status
     879787
0
1
      23450
Name: count, dtype: int64
Testing Set Class Distribution:
status
     607201
0
       6510
Name: count, dtype: int64
Training set size: (903237, 27)
Testing set size: (613711, 27)
```

Figure 10: Splitting the dataset.

To address the significant class imbalance, a weighted approach using class weights was implemented during model training (Fig. 11), ensuring the model could effectively learn from the underrepresented class while maintaining overall prediction reliability.

```
from sklearn.utils.class_weight import compute_class_weight
import numpy as np
# Convert classes to a NumPy array
classes = np.array([0, 1])
# Calculate class weights based on the `status` column
class_weights = compute_class_weight(
    class_weight='balanced',
    classes=classes.
    y=data['status']
# Create a dictionary for the weights
class_weights_dict = {cls: weight for cls, weight in zip(classes, class_weights)}
# Display the computed class weights
print("Computed Class Weights:")
print(class_weights_dict)
Computed Class Weights:
{0: 0.5100740557422118, 1: 25.316221628838452}
```

Figure 11: Class Weights.

5.1 **Regression Model**

The Random Forest model was employed (Fig. 12) to classify failure events based on the engineered dataset. The model was configured with 100 estimators, a maximum tree depth of 10 to prevent overfitting, and parallel processing to optimize computation. The dataset was split into training and testing subsets, excluding non-informative columns like timestamps. After training, the model's performance was evaluated using precision, recall, and F1-score, which were calculated based on the predictions against the testing set. The model underwent extensive evaluation, including threshold optimisation for improved F1-scores and a grid search for hyperparameter tuning, to handle the challenges of the imbalanced dataset.

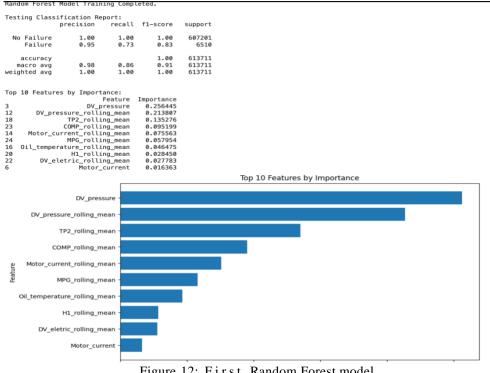


Figure 12: First Random Forest model.

5.2 SHAP

To interpret the predictions made by the Random Forest model, SHAP (SHapley Additive exPlanations) was utilized (fig. 13). SHAP values provided insights into how individual features contributed to specific predictions, enabling a transparent understanding of the model's behavior. The analysis focused on true positive failure cases, where borderline predictions (close to the decision threshold) were selected for detailed examination. The SHAP explainer was applied to these samples, and visualizations such as waterfall plots highlighted the contributions of key features to the predicted outcomes. Furthermore, high-impact features, including sensor readings like TP2, TP3, and DV_pressure, were analysed through density plots and correlation studies to understand their distribution in failure and non-failure scenarios. This interpretability framework ensured the model's decisions were explainable and aligned with domain expectations, enhancing its credibility for deployment in predictive maintenance.

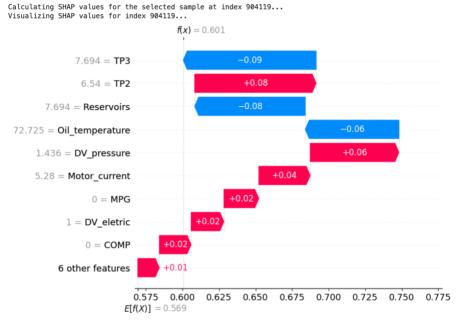


Figure 13: SHAP analysis.