

# Configuration Manual

MSc Research Project Master's in Data Analytics

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**Project Title:** Solar Sight Forecast: Deep Learning Approaches for Solar PV

Power Prediction at Bui Solar Power Station Ghana

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**Date:** 12/08/2024

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# Configuration Manual

Mitali Sopte Student ID: X22198121

### 1 Introduction

This configuration manual gives us the detailed information of the environmental setup and configuration setup for "Solar Power Generation Prediction Using Machine Learning Techniques". This manual provides the requirement needed to carry out the research project successfully and also gives a step-by-step guidance.

The Configuration setup section and data gathering section gives information about the necessary software and hardware that were required in this project.

### 1.1 Project Objective

The main Objective of the project is to develop solar power generation prediction using deep learning methods for BUI Solar power station in Ghana. The dataset which consists of wide range of environmental parameters like humidity, wind speed and global irradiation aims to verify the generation of solar power with deep learning models like LSTM. The end goal of the project to offer insightful information that can help the energy management company to effective plan supply the power.

# **2** Configuration Setup

## 2.1 Hardware Configuration

The below are the specification of hardware which was configured for this project.

Memory: 8 GBProcessor: Apple M1System: macOSOperating system: 8 GB

Operating system: 8 GGPU: integrated GPU

### 2.2 Software Configuration

The research project's software setup uses Jupyter Notebook which offer an interactive environment for creating and testing deep leaning models. All the models are coded in Python version 3.11.4. Throughout the research several python libraries are used such as Keras version (from TensorFlow): 3.3.3 for high level neural network API and TensorFlow version: 2.16.1 for creating and training deep leaning models, Matplotlib (3.7.1) is used for visualisation of data. Other Libraries have also been used including NumPy for numerical

calculation and pandas for data manipulation and scikit-learn for machine learning tool. Effective data processing and performance evaluation are made possible by using the combination of the above-mentioned tools.

# 3 Data Gathering

The gathering for this research id obtained from the previous researchers who focused on solar power generation at the BUI Solar Power Station in Ghana. This dataset is very significant as it includes a wide range of factors such as humidity, global irradiation and ambient temperature. With the time interval of 15-minute interval the data comprised of 32736 records and covers a 11 month period of April 25, 2021 till March 31, 2022. By working on the models like LSTM the present study seeks to improve the forecasting capacities of solar power generation by working on the preexisting dataset.

# 4 Data Preprocessing

The data which is obtained in then imported in the juypter notebook as below and then the handling missing value and outliers' steps are being carried out. As shown in the Fig 2 missing values are being identified and then handled by time-based interpolation technique.

```
: 1 # Load the dataset
2 solarData = pd.read_excel('/Users/mitalisopte/Documents/Research/Solar_Data_updated.xlsx')
3 # Assuming your DataFrame is named 'solarData' and the date column is named 'Date'
4 num_unique_dates = solarData['Date'].nunique()
5 print(f"Number of unique dates: {num_unique_dates}")
Number of unique dates: 341
```

Fig. 1 Importing the data

```
import pandas as pd

# Assuming 'solarData' is your DataFrame
missing_values = solarData.isnull().sum()

# Display columns with missing values
print("Missing values in each column:")
print(missing_values[missing_values > 0])
```

Fig. 2 Missing values

```
# Set 'Datetime' as the index
solarData.set_index('Datetime', inplace=True)
# Perform time-based interpolation
try:
solarData.interpolate(method='time', limit_direction='forward', inplace=True)
except ValueError as e:
print(f"Interpolation error: {e}")

# Check for missing values often interpolation
```

Fig. 3 Time Based Interpolation

```
# Calculate Q1 (25th percentile) and Q3 (75th percentile) for each feature
outlier_features = columns_to_check # List of features to check for outliers
lower_bounds = {}
upper_bounds = {}
for feature in outlier_features:
    Q1 = solarData[feature].quantile(0.25)
    Q3 = solarData[feature].quantile(0.75)
    IQR = Q3 - Q1
    lower_bounds[feature] = Q1 - 1.5 * IQR
    upper_bounds[feature] = Q3 + 1.5 * IQR
```

Fig. 4 Interquartile Range Method

The above fig shows the method to handling the outliers. The outlier are those data points that can cause issue to the analysis and resulting in skewed outcome. So IQR method is applied before the data is applied to the model.

```
# Calculate the correlation matrix
correlation_matrix = solarData.corr()

# Set up the matplotlib figure
plt.figure(figsize=(10, 8))

# Create a heatmap for the correlation matrix
sns.heatmap(correlation_matrix, annot=True, fmt=".2f", cmap='coolwarm', square=True, cbar_kws={"shrink": .8})

# Add title and show the plot
plt.sitle('Correlation Matrix')
plt.show()

# Get the correlation_coefficients with 'POWER'
power_corr = correlation_matrix['POWER'].drop('POWER') # Drop the 'POWER' column itself
# identify effective features based on correlation
7 effective_features = power_corr[abs(power_corr) > 0.5].sort_values(ascending=False)
print("effective_features)
9 print(effective_features)
```

Fig. 5 Correlation Heat map

# **5** Feature Selection

The feature selection is done by the Recursive Feature Extraction Method this technique which uses a machine learning model like Random Forest to evaluate the importance of feature

```
# Prepare your data
2 X = solarData_no_outliers[['Diffuse', 'Wind direction', 'PANEL TEMP.', 'GLOBAL IRRADIATION', 'HUMIDITY', 'AMBIEN'
3 y = solarData_no_outliers[POWER']

4 # Split the data into training and testing sets
6 X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)

7 # Create a Random Forest model
9 model = RandomForestRegressor()

10 # Create the RFE model and select the top 5 features
10 rfe = RFE(estimator=model, n_features_to_select=3)
13 rfe.fit(X_train, y_train)
14 # Print the selected features
16 selected_features = X.columns[rfe.support_]
17 print("Selected features using RFE:")
18 print(selected_features using RFE:")
19 print(selected_features)
20 # Optionally, you can also print the ranking of all features
21 feature_ranking = pd.Series(rfe.ranking_, index=X.columns)
22 print("\nFeature_ranking= pd.Series(rfe.ranking_, index=X.columns)
24 print(feature_ranking.sort_values())
```

Fig.6 Recursive Feature Extraction

# 6 Implementation

### 6.1 Linear Regression Base Model

The linear regression model serves as the base model for the further execution. Fig 8 shows the execution results.

```
# Step 1: Prepare the data
features = solarData_no_outliers.drop(columns=['POWER']).values
target = solarData_no_outliers['POWER'].values

# Normalize the features
scaler = MinMaxScaler(feature_range=(0, 1))
features_scaled = scaler.fit_transform(features)

# Create sequences (if applicable, otherwise skip this step for linear regression)
def create_dataset(data, target, time_step=1):
    X, y = [], []
    for i in range(len(data) - time_step):
        a = data[i:(i + time_step), :]
        X.append(a)
        y.append(target[i + time_step]) # This will now be within bounds
    return np.array(X), np.array(y)

# Set the time step (number of previous time steps to use)
time_step = 10
    X, y = create_dataset(features_scaled, target, time_step)

# Step 2: Split the data into training and testing sets
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)

# Step 3: Reshape the data for Linear Regression
    X_train_flat = X_train.reshape(X_train.shape[0], -1)
    X_test_flat = X_train.reshape(X_train.shape[0], -1)

# Step 4: Define the Linear Regression model
lr_model = LinearRegression()

# Step 5: Train the Linear Regression model
lr_model.fit(X_train_flat, y_train)
```

Fig.7 Linear Regression Model

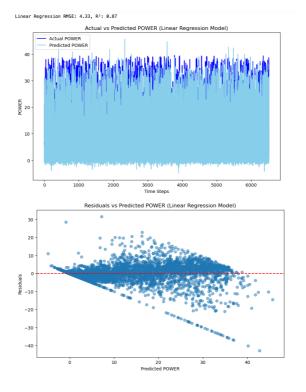


Fig.8 Linear Regression Results

#### **6.2** Models with All Features

The below fig shows the code for the Models like LSMT, CNN- LSTM and Stacked LSTM when all the features are applied. Fig 13 shows the result of stacked LSTM which has lower RMSE and high R2

Fig.9 Sequence creation for All feature dataset

```
# Step 3: Define the LSTM model
model = Sequential()
model.add(LSTM(50, return_sequences=True, input_shape=(X_train.shape[1], X_train.shape[2])))
model.add(lSTM(50, return_sequences=False))
model.add(lSTM(50, return_sequences=False))
model.add(lorpoput(0.2))
model.add(Dense(1)) # Output layer

# Compile the model
model.compile(optimizer='adam', loss='mean_squared_error')

# Step 3: Print the model summary
model.summary()

# Step 4: Train the model
model.fit(X_train, y_train, epochs=50, batch_size=32)

# Step 5: Make predictions
y_pred = model.predict(X_test)

# Step 6: Calculate RMSE and R²
rmse = np.sqrt(mean_squared_error(y_test, y_pred))
r2 = r2_score(y_test, y_pred)

print(f'RMSE: {rmse:.2f}, R²: {r2:.2f}')
```

Fig.10 LSTM Model

```
X_train_cnn, X_test_cnn, y_train_cnn, y_test_cnn = train_test_split(X, y, test_size=0.2, random_state=42)
# Step 12: Define the CNN-LSTM model
cnn_lstm_model = Sequential()
cnn_lstm_model.add(Conv1D(filters=64, kernel_size=2, activation='relu', input_shape=(X_train_cnn.shape[1], X_tra
cnn_lstm_model.add(MaxPooling1D(pool_size=2))
cnn_lstm_model.add(STM(50, return_sequences=False))
cnn_lstm_model.add(Dense(1)) # Output layer

# Compile the CNN-LSTM model
cnn_lstm_model.compile(optimizer='adam', loss='mean_squared_error')
# Step 3: Print the model summary
cnn_lstm_model.summary()
# Step 13: Train the CNN-LSTM model
cnn_lstm_model.fit(X_train_cnn, y_train_cnn, epochs=50, batch_size=32)
```

Fig.11 CNN LSTM Model

```
# Step 8: Define the Stacked LSTM model
stacked_lstm_model = Sequential()
stacked_lstm_model.add(LSTM[50, return_sequences=True, input_shape=(X_train.shape[1], X_train.shape[2])))
stacked_lstm_model.add(LSTM[50, return_sequences=True)) # Stacking another LSTM layer
stacked_lstm_model.add(LSTM[50, return_sequences=False)) # Last LSTM layer
stacked_lstm_model.add(LSTM[50, return_sequences=False)) # Last LSTM layer
stacked_lstm_model.add(Dropout(0.21)
stacked_lstm_model.add(Dropout(0.21))
# Compile the Stacked LSTM model
stacked_lstm_model.compile(optimizer='adam', loss='mean_squared_error')
stacked_lstm_model.summary()
# Step 9: Train the Stacked LSTM model
stacked_lstm_model.fit(X_train, y_train, epochs=50, batch_size=32)
```

Fig.12 Stacked LSTM Model

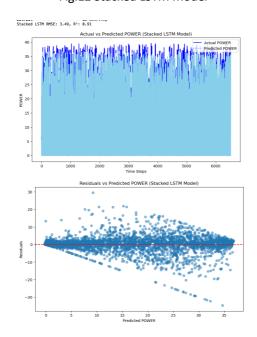


Fig.13 Stacked LSTM Model Results

#### 6.3 Model with 3 Features

The below fig shows the code for the Models like LSMT , CNN- LSTM and Stacked LSTM when only 3 of the features are applied. Fig 17 shows the result of stacked LSTM which has lower RMSE and high R2

Fig.14 LSTM Model

```
# Step 4: Define the CNN-LSTM model
cnn_lstm_model.add(Conv1D[filters=64, kernel_size=2, activation='relu', input_shape=(X_train_cnn_lstm.shape[1],
cnn_lstm_model.add(MaxPooling1D(pool_size=2))
cnn_lstm_model.add(ISTM(50, return_sequences=False))
cnn_lstm_model.add(Dropout(0.2))
cnn_lstm_model.add(Dropout(0.2))
cnn_lstm_model.add(Dense(1)) # Output layer

# Compile the CNN-LSTM model
cnn_lstm_model.compile(optimizer='adam', loss='mean_squared_error')

# Step 5: Train the CNN-LSTM model
cnn_lstm_model.fit(X_train_cnn_lstm, y_train_cnn_lstm, epochs=50, batch_size=32)
```

Fig.15 LSTM Model

```
# Step 3: Define the Stacked LSTM model
stacked_lstm_model = Sequential()
stacked_lstm_model.add(LSTM(50, return_sequences=True, input_shape=(X_train_stacked_lstm.shape[1], X_train_stack
stacked_lstm_model.add(LSTM(50, return_sequences=True)) # Stacking another LSTM layer
stacked_lstm_model.add(Dropout(0.2))
stacked_lstm_model.add(LSTM(50, return_sequences=False)) # Last LSTM layer
stacked_lstm_model.add(Dropout(0.2))
stacked_lstm_model.add(Dropout(0.2))
stacked_lstm_model.add(Dense(1)) # Output layer

# Compile the Stacked_LSTM model
stacked_lstm_model.compile(optimizer='adam', loss='mean_squared_error')

# Step 4: Train the Stacked_LSTM model
stacked_lstm_model.fit(X_train_stacked_lstm, y_train_stacked_lstm, epochs=50, batch_size=32)
```

Fig.16 Stacked LSTM Model

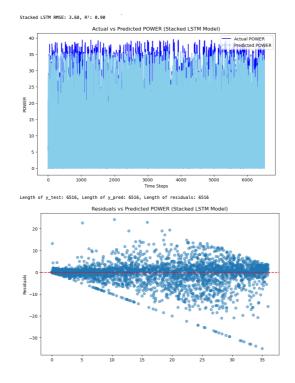


Fig.17 Stacked LSTM Model Results

### 6.4 Model with no 0 data values with All Feature

The below fig shows the code for the Models like LSMT , CNN- LSTM and Stacked LSTM when 0 data values form the power are removed and all the features are applied. Fig 23 shows the result of stacked LSTM which has lower RMSE and high R2

#### Power removing 0 with all feature

```
# Remove rows where POWER is zero
solarData_no_outliers = solarData_no_outliers['POWER'] != 0]

# Check the shape of the DataFrame after removal
print(f"Data shape after removing zero power values: {solarData_no_outliers.shape}")

# Check for missing values after interpolation
print("Missing values after removing zero power values:")
print(solarData_no_outliers.isnull().sum())
```

Fig.18 Removing 0 data form power

```
import pandas as pd
import numpy as np
from sklearn.preprocessing import MinMaxScaler
from keras.models import Sequential
from keras.layers import LSTM, Dense, Dropout
from sklearn.model_selection import train_test_split
import matplotlib.pyplot as plt

# Assuming 'solarData' is your DataFrame with 'POWER' and other features
# Step 1: Prepare the data
# Select relevant features
features = solarData_no_outliers.drop(columns=['POWER']).values
target = solarData_no_outliers['POWER'].values

# Normalize the features
scaler = MinMaxScaler(feature_range=(0, 1))
features_scaled = scaler.fit_transform(features)

# Create sequences
def create_dataset(data, target, time_step=1):
    X, y = [], []
    for i in range(len(data) - time_step - 1):
        a = data[i:(i + time_step), :]
        X.append(a)
        y.append(target[i + time_step])
        return np.array(X), np.array(y)

# Set the time step (number of previous time steps to use)
time_step = 10
X, y = create_dataset(features_scaled, target, time_step)

# Step 2: Split the data into training and testing sets
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)
```

Fig.19 Sequence creation for All feature dataset

```
# Set the time step (number of previous time steps to use)
time_step = 10
X, y = create_dataset(features_scaled, target, time_step)

# Step 2: Split the data into training and testing sets
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)

# Step 3: Define the LSTM model
imodel_lstm_zero = Sequential()
model_lstm_zero = Sequential()
model_lstm_zero add(USIM(50, return_sequences=True, input_shape=(X_train.shape[1], X_train.shape[2])))
model_lstm_zero.add(Dropout(0.2))
model_lstm_zero.add(Dropout(0.2))
model_lstm_zero.add(Dropout(0.2))
model_lstm_zero.add(Dense(1)) # Output layer

# Compile the model
model_lstm_zero.compile(optimizer='adam', loss='mean_squared_error')

model_lstm_zero.summary()

# Step 4: Train the model
model_lstm_zero.fit(X_train, y_train, epochs=50, batch_size=32)
```

Fig.20 LSTM Model

```
# Define the CNN model
def create_cnn_model(input_shape):
    model = Sequential()
    model.add(Conv1D(filters=64, kernel_size=2, activation='relu', input_shape=input_shape))
    model.add(MaxPooling1D(pool_size=2))
    model.add(MaxPooling1D(pool_size=2))
    model.add(MaxPooling1D(pool_size=2))
    model.add(Flatten())
    model.add(Dense(50, activation='relu'))
    model.add(Dense(50, activation='relu'))
    model.add(Dense(1)) # Output layer
    return model

# Reshape X_train and X_test for CNN input
X_train_cnn = X_train.reshape(X_train.shape[0], X_train.shape[1], X_train.shape[2])
X_test_cnn = X_test.reshape(X_test.shape[0], X_test.shape[1], X_test.shape[2])

# Create and compile the model
cnn_model = create_cnn_model((X_train_cnn.shape[1], X_train_cnn.shape[2]))
cnn_model.compile(optimizer='adam', loss='mean_squared_error')

# Train the model
cnn_model.fit(X_train_cnn, y_train, epochs=50, batch_size=32)
```

Fig.21 CNN-LSTM Model

```
# Define the Stacked LSTM model
def create_stacked_lstm_model(input_shape):
    model = Sequential()
    model.add(LSTM(50, return_sequences=True, input_shape=input_shape))
    model.add(Dropout(0.2))
    model.add(LSTM(50, return_sequences=True))  # Stacking another LSTM layer
    model.add(Dropout(0.2))
    model.add(Dropout(0.2))
    model.add(Dropout(0.2))
    model.add(Dropout(0.2))
    model.add(Dropout(0.2))
    model.add(Dense(1))  # Output layer
    return model

# Create and compile the model
stacked_lstm_model = create_stacked_lstm_model((X_train.shape[1], X_train.shape[2]))
stacked_lstm_model.compile(optimizer='adam', loss='mean_squared_error')

# Train the model
stacked_lstm_model.fit(X_train, y_train, epochs=50, batch_size=32)
stacked_lstm_model.summary()
```

Fig.22 Stacked LSTM Model

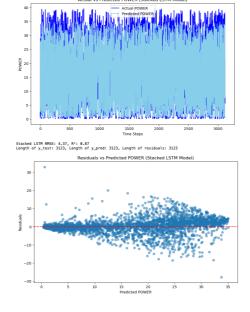


Fig.23 Stacked LSTM Model Results

#### 6.5 Model with no 0 data values with 3 Features

The below fig shows the code for the Models like LSMT , CNN- LSTM and Stacked LSTM when 0 data values form the power are removed and only 3 of the features are applied. Fig 28 shows the result of stacked LSTM which has lower RMSE and high R2

Fig.24 Sequence creation for 3 feature dataset

```
# Step 3: Verine the LSIM mode!
modeL_lstm_zero3 = Sequential()
modeL_lstm_zero3.add(LSTM(50, return_sequences=True, input_shape=(X_train.shape[1], X_train.shape[2])))
modeL_lstm_zero3.add(LSTM(50, return_sequences=False))
modeL_lstm_zero3.add(loropout(0.2))
modeL_lstm_zero3.add(Dense(1)) # Output layer

# Compile the mode!
modeL_lstm_zero3.compile(optimizer='adam', loss='mean_squared_error')

modeL_lstm_zero3.summary()

# Step 4: Train the mode!
modeL_lstm_zero3.fit(X_train, y_train, epochs=50, batch_size=32)

# Step 5: Make predictions
y_pred = modeL_lstm_zero3.predict(X_test)

# Step 6: Evaluate the mode!
# Inverse transform the predictions if necessary
# For example, if you want to compare predictions to actual values
# (you may need to scale back the predictions if you normalized the target)
plt.figure(figsize=(10, 6))
plt.plot(y_test, label='Actual POWER', color='blue')
plt.plot(y_test, label='Actual POWER', color='red')
plt.tile('Actual vs Predicted POWER')
plt.xlabel('Time Steps')
plt.xlabel('Time Steps')
plt.xlabel('Time Steps')
plt.show()
```

Fig.25 LSTM Model

```
# Define the CNN model
def create_cnn_model3(input_shape):
    model = Sequential()
    model.add(Conv1D(filters=64, kernel_size=2, activation='relu', input_shape=input_shape))
    model.add(MaxPooling1D(pool_size=2))
    model.add(Gonv1D(filters=32, kernel_size=2, activation='relu'))
    model.add(Gonv1D(filters=32, kernel_size=2, activation='relu'))
    model.add(Gonv1D(filters=32, kernel_size=2, activation='relu'))
    model.add(Dense(50, activation='relu'))
    model.add(Dense(50, activation='relu'))
    model.add(Dense(1)) # Output layer
    return model

# Reshape X_train and X_test for CNN input
X_train_cnn = X_train.reshape(X_train.shape[0], X_train.shape[1], X_train.shape[2])

X_test_cnn = X_test.reshape(X_test.shape[0], X_test.shape[1], X_test.shape[2])

# Create and compile the model
cnn_model3 = create_cnn_model((X_train_cnn.shape[1], X_train_cnn.shape[2]))
cnn_model3.compile(optimizer='adam', loss='mean_squared_error')

# Train the model
cnn_model3.fit(X_train_cnn, y_train, epochs=50, batch_size=32)
```

Fig.26 CNN LSTM Model

```
# Define the Stacked LSTM model
def create_stacked_lstm_model(input_shape):
    model = Sequential()
    model.add(LSTM(50, return_sequences=True, input_shape=input_shape))
    model.add(LSTM(50, return_sequences=True)) # Stacking another LSTM layer
    model.add(LSTM(50, return_sequences=False))
    model.add(LSTM(50, return_sequences=False))
    model.add(Dropout(0.2))
    model.add(Dropout(0.2))
    model.add(Dropout(0.2))
    model.add(Dense(1)) # Output layer
    return model

# Create and compile the model
stacked_lstm_model = create_stacked_lstm_model((X_train.shape[1], X_train.shape[2]))
stacked_lstm_model.compile(optimizer='adam', loss='mean_squared_error')

# Train the model
stacked_lstm_model.sim_model.sim_model.size=32)
stacked_lstm_model.summary()
```

Fig.27 Stacked LSTM Model

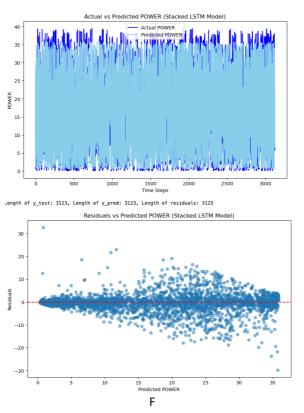


Fig.28 Stacked LSTM Model Results

### References

K. Pun, S. M. Basnet and W. Jewell, "Solar Power Prediction in Different Forecasting Horizons Using Machine Learning and Time Series Techniques," 2021 IEEE Conference on Technologies for Sustainability (SusTech), Irvine, CA, USA, 2021, pp. 1-7, doi: 10.1109/SusTech51236.2021.9467464. keywords: {Renewable energy sources;Time series analysis;Machine learning;Solar energy;Predictive models;Performance analysis;Solar power generation;Renewable Energy Resources;Forecasting;Machine Learning;Time Series},