

Configuration Manual

MSc Research Project Programme Name

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MSc Project Submission Sheet



School of Computing

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Programme:	Master's Degree in Artificial Intelligence Year: 2023-2024	
Module:	MSc Research Practicum	
Lecturer: Submission Due Date:	Sheresh Zahoor	
	12/08/2024	
Project Title:	Deep Learning-Based Multi-Object Group Detection and Tracking in Video Streams	

Word Count: 5608 Page Count: 27

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Configuration Manual

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This Configuration Guide provides the software tools and settings needed to replicate the experimental setup for a multi-object tracking system. It describes the Python libraries and settings needed for data processing, model training and implementation of tracking algorithms. In particular, it includes the modules needed for training the Faster R-CNN model and for multi-object tracking. This document is designed to enable other researchers to accurately reproduce the results of this work. It does not cover setup procedures for standard software tools.

1. Introduction

This guide provides the Python libraries and settings needed for data processing and model training. In particular, it focuses on training the Faster R-CNN model and implementing object tracking algorithms.

2. Software Tools and Libraries

Getting Started

To get started, you need to have Python and a few basic libraries installed on your system. If you don't have these tools yet, here's what you need:

- Python: Make sure you have Python 3.8 or later installed. It's the programming language we'll be using.
- Environment Manager: Using Conda or Miniconda is recommended for managing your Python packages.

Required Python Libraries

To make sure everything works properly, you need to install a few Python libraries. Open your command line interface and run the following commands:

These libraries serve the following purposes:

- torch and torchvision: For implementing the Faster R-CNN model and transformations.
- opencv-python: For processing and displaying video frames.
- **numpy:** For handling numerical operations.
- pandas: For data manipulation, if needed.

Choosing an IDE

You can use any **Python-compatible IDE** or code editor to write and run your code. Popular options include **Jupyter Notebook, PyCharm or Visual Studio Code.**

3. Model Training and Setup

Install and Configure the Model

Your system consists of two main components: ObjectDetector and VideoProcessor classes. Here is a brief summary of what each one does:

ObjectDetector Class:

- Initialization: This class loads the Faster R-CNN model and prepares it for object detection.
- Model Loading: The model is configured with a custom number of classes and loaded from a file.

• Prediction: Processes images to detect objects and filters out low-reliability predictions. VideoProcessor Class:

Video Processing: Reads video frames, applies object detection and tracks objects across frames. Visualization: Draws bounding boxes and labels on detected objects and displays the video in a window.

Configuration Details

In the main() function, you need to provide paths to the trained model and the video file you want to process:

def	main():	
	nodel_path = 'C:/Workspace/MOT17_Object_Tracking/models/faster_rcnn.pth' # Path to your trained model fil	re
	<pre>video_path = 'MOT17_Object_Tracking/data/MOT17-13-SDP/test.mp4' # Path to your video file</pre>	
	<pre>#video_path = 'MOT17_Object_Tracking/data/MOT17-13-SDP/traininMOT17-14-FRCNN.mp4'</pre>	

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