

Configuration Manual

MSc Research Project
Cyber Security

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MSc Project Submission Sheet
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Configuration Manual

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1 Introduction

In the research project we explored the idea of using a computer vision model specifically trained to detect cheating techniques in competitive video games while utilizing minimum user data and resources. The AI model was then deployed on a cloud service to test its viability and increase in performance relative to local deployment. This configuration manual serves as a step-by-step guide to recreate all the environment both locally, and on the cloud, that was used to carry out the research.

2 Configurations

Below are the software artefacts used to carry out the research followed by the minimum required hardware to be able to train and run inference on the model locally.

Table 1: Software requirements

Software	Version
Python	3.11
Ultralytics package	8.0.202
YOLO model	V8n
AssaultCube game	1.3.0.2
PyTorch	0.16.0+cu118
OpenCV Python	4.8.1.78
Roboflow	1.1.9
MinGW	0.6.0-beta-20130904-1
OBS Studio	30.0.2

Table 2: Hardware requirements

Hardware (Local deployment)	Minimum requirement
Operating System	Windows 10 (64 bit)
CPU	Intel Core i5 2500k or AMD FX-6300
Memory	4 GB of RAM
Graphics	GTX 1060
Storage	10 GB of free space on the hard disk

2.1 Dependencies and Compilers

The command shown is a one-click solution that calls the pip utility to install the required python modules (Intel, no date; Meta AI, no date; *Ultralytics / Revolutionizing the World of Vision AI*, no date; *ultralytics/ultralytics: NEW - YOLOv8 🚀 in PyTorch > ONNX > OpenVINO > CoreML > TFLite*, no date).



```
pip3 install ultralytics opencv-python roboflow torch torchvision torchaudio --index-url
https://download.pytorch.org/whl/cu121
```

Figure 1: Python pip module to install dependencies

Further we must install MinGW¹ which is a C/C++ compiler for Microsoft Windows. This is needed to compile the ESP cheat written in C++ (*MinGW-w64*, 2007).

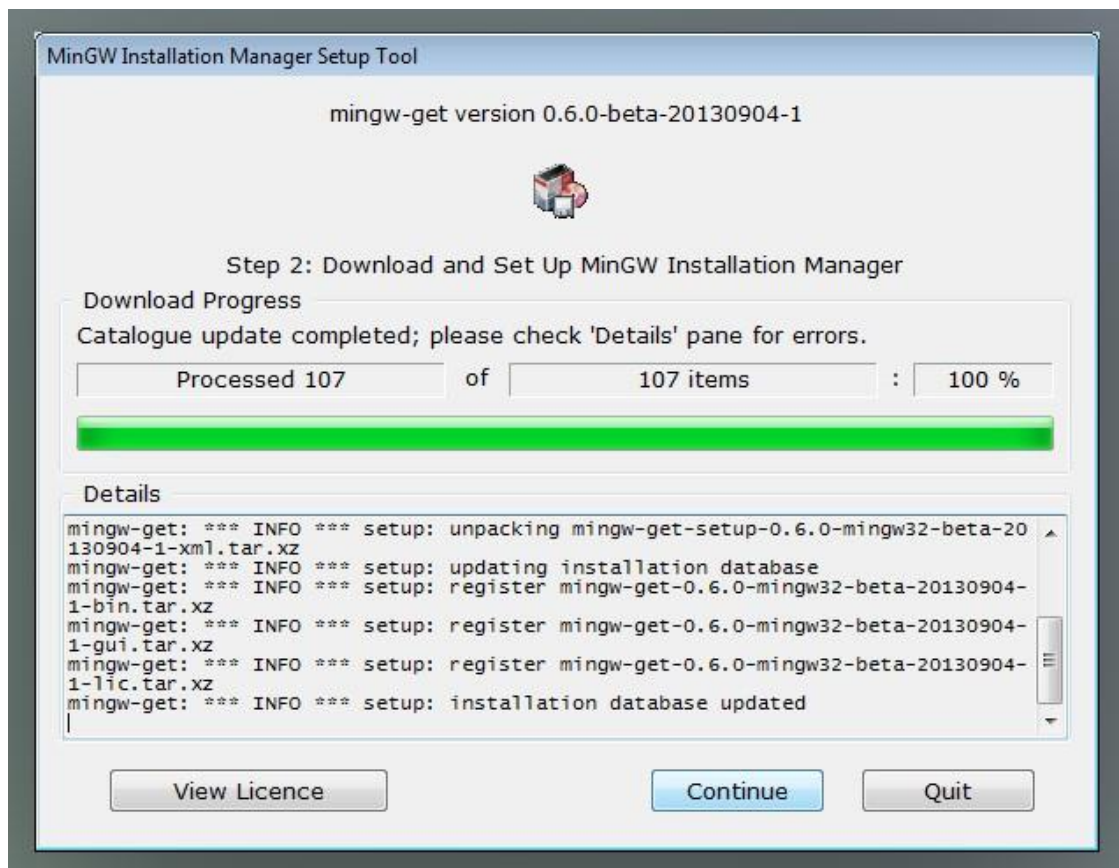


Figure 2: MinGW installation

¹ MinGW Sourceforge: <https://sourceforge.net/projects/mingw/>

2.2 AssaultCube Setup

Download and install AssaultCube from <https://assault.cubers.net/> as this is the open-source game used in the research (Rabid Viper Productions, 2006).

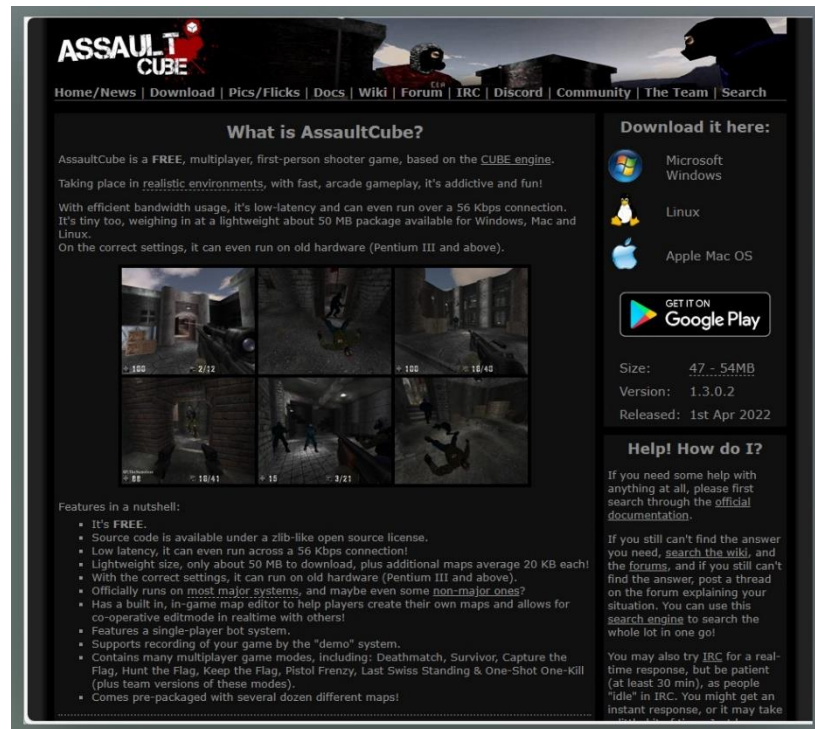


Figure 3: AssaultCube official website

2.3 Compiling the ESP Cheat

Using a terminal, after successful installation of MinGW, navigate to the root directory of the ESP cheat and execute the following command which will output an executable named ESP.exe to the present working directory.

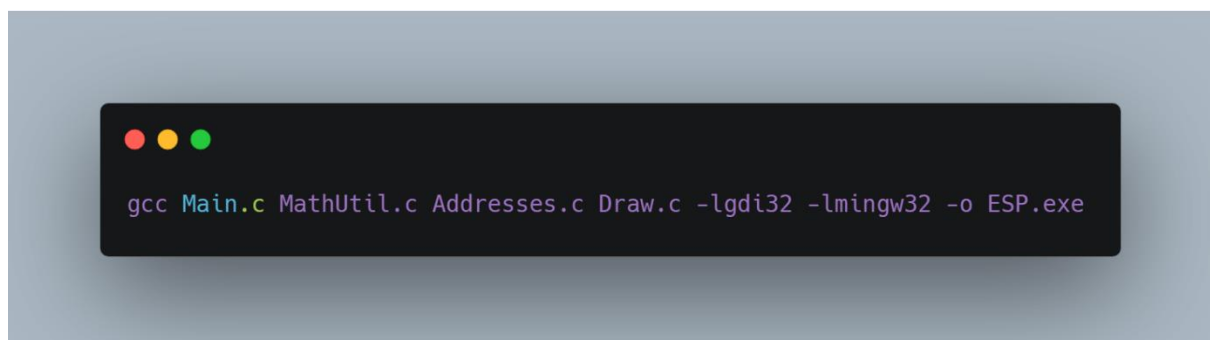


Figure 4: Compiling the C++ code

2.4 OBS Studio Setup

OBS Studio is an open-source screen recording and streaming solution that was used to record AssaultCube in two different scenarios where the ESP cheat was on and off. This tool proved

to be a very efficient tool to generate the dataset required to train the AI model (*Open Broadcaster Software / OBS*, no date).



Figure 5: OBS Studio splash screen

2.5 Roboflow Setup

Roboflow was used to organize and optimize the dataset for training. After extracting frames from the recorded AssaultCube sessions in OBS Studio, we use roboflow to perform annotation and clearly define our classes for detection. The features available for free proved sufficient for carrying out this research (*Roboflow: Give your software the power to see objects in images and video*, no date).

After signing up for Roboflow, create a new project.

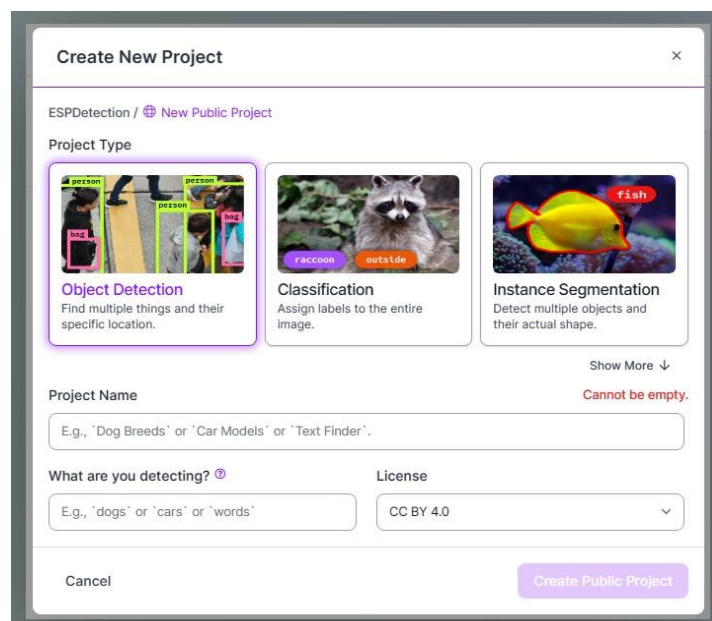


Figure 6: Create new project

Upload the collected images that must be used for training the model.

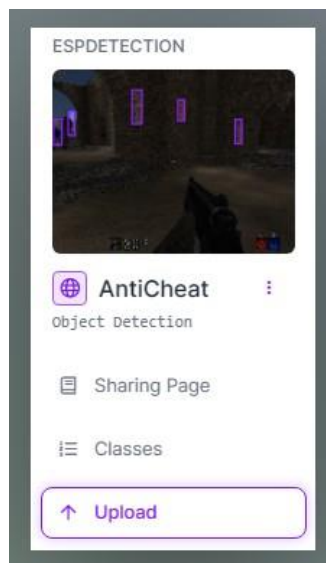


Figure 7: Upload dataset

Each frame must be annotated with the desired classifications.

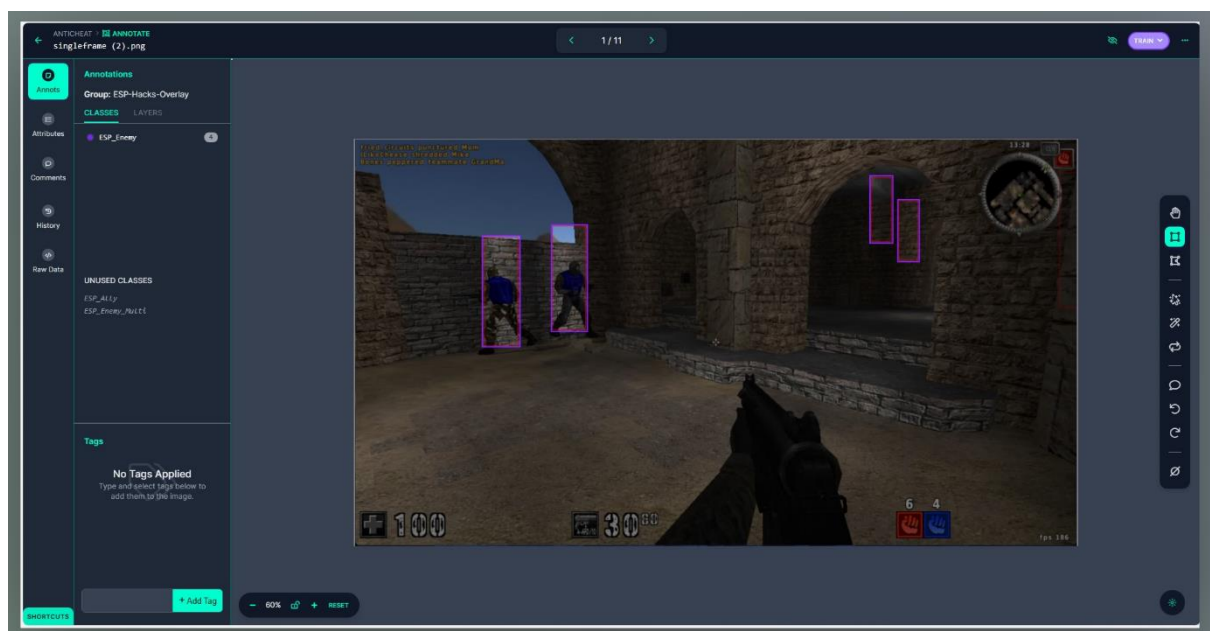


Figure 8: Frame annotation

Generate your personal API key by navigating from Account to Settings and then workspaces. This is essential to download the optimized dataset directly through the python script written for this research and initiate training of the model.

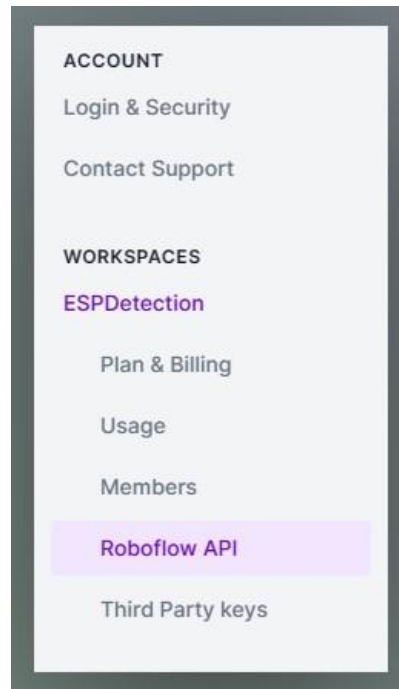


Figure 9: Generate API key

3 Model Training and Detection

Proceed to execute the “train AC.py” file available in the project artefact to download and initiate training of the model.

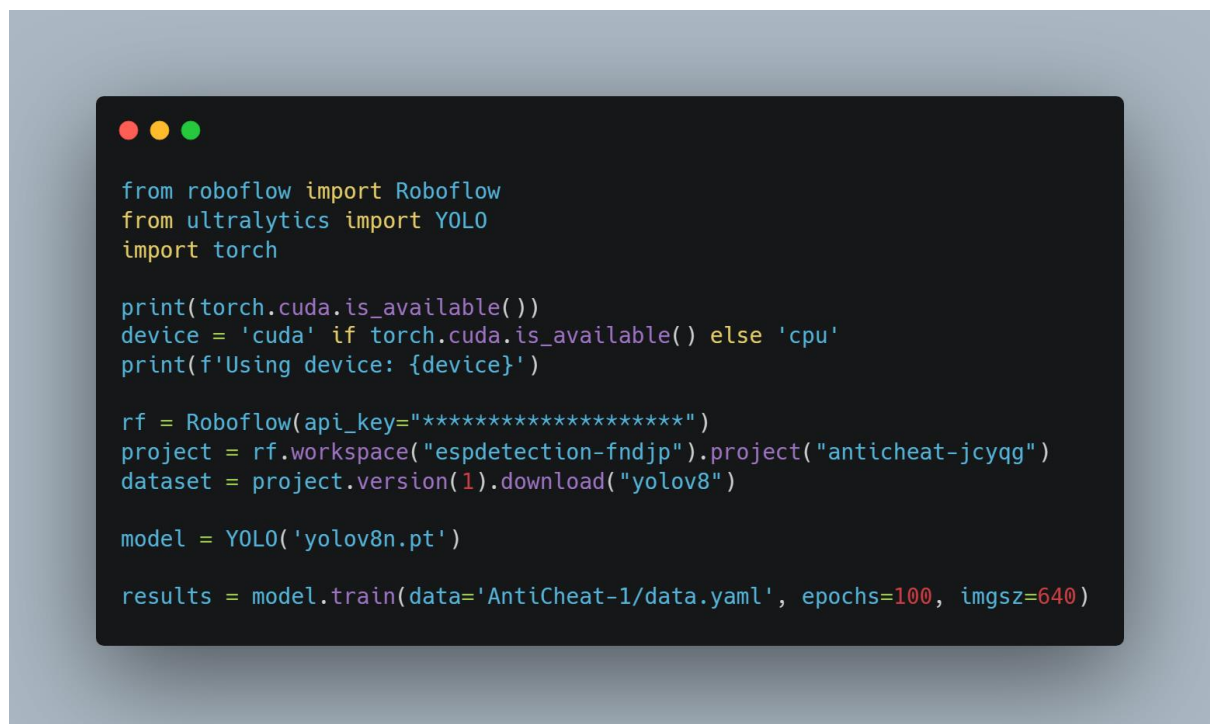


Figure 10: Sample code for dataset download and training locally

This code can also be used on a cloud platform supporting python runtime or jupyter notebooks.

3.1 Launching AssaultCube and Enabling Cheat

With AssaultCube successfully installed and our ESP cheat compiled into an executable, we run the game and start a singleplayer match with bots.

To do that, we select “Singleplayer” when the game launches, and select “Bot Team Deathmatch” followed by selection of the difficulty, and finally how many bots to add to the game.

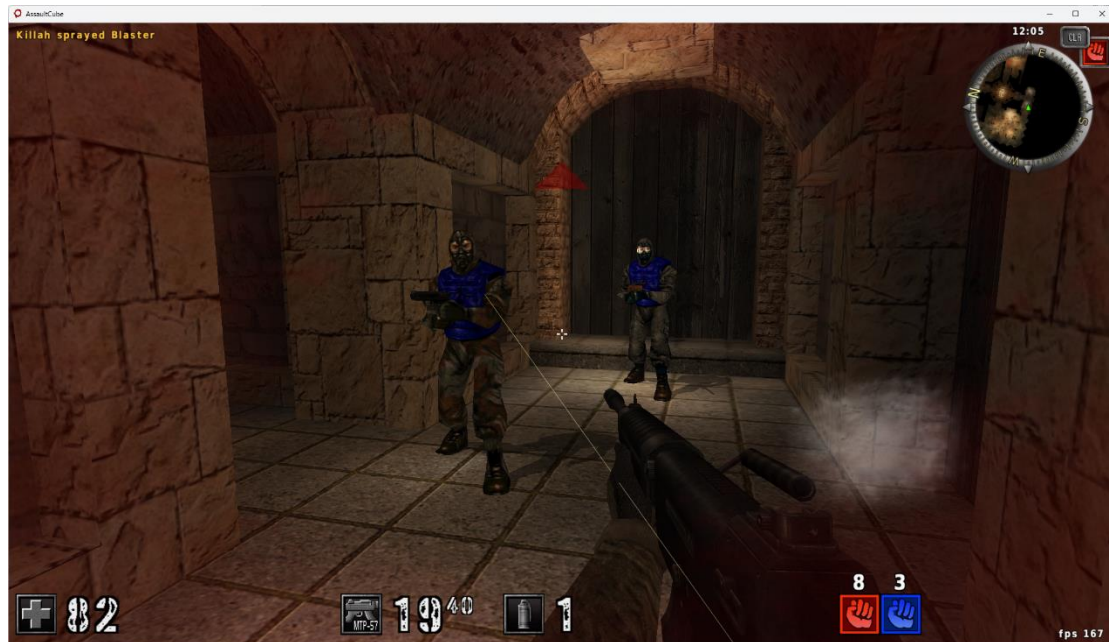


Figure 11: AssaultCube match launched with bots

With the game launched, run the ESP.exe compiled in the section 2.3 to enable the cheat and record the screen playing the game.

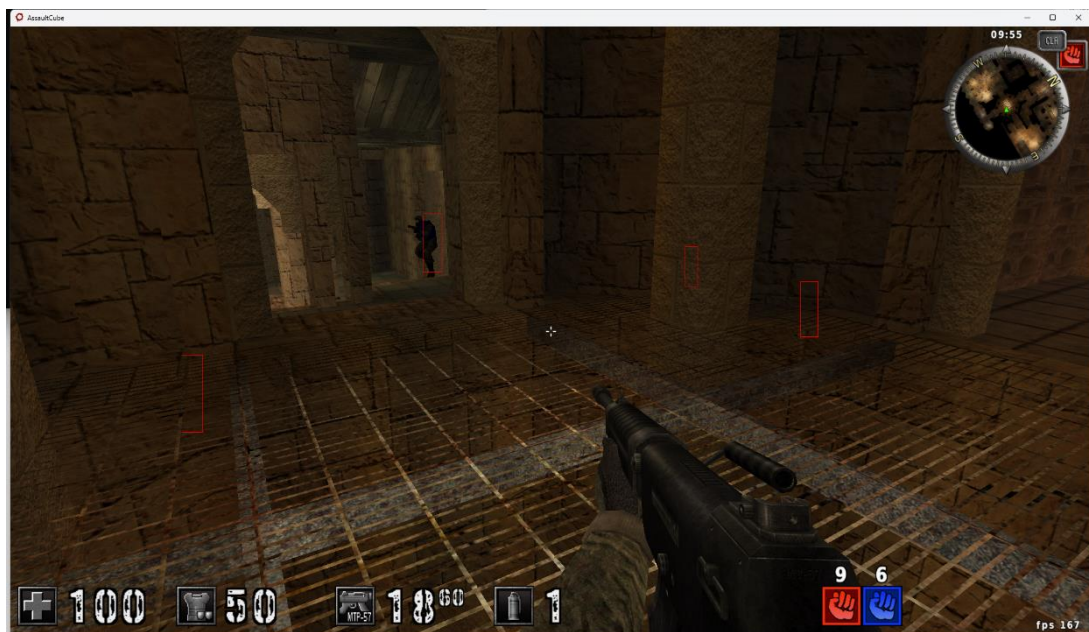


Figure 12: AssaultCube with ESP cheat enabled

3.2 Detection Testing

Finally, use the trained model checkpoint over the recorded AssaultCube session with ESP cheat turned on to test its output.

Simply execute the “detectVideo.py” python script included in the project artefact to iterate through all frames and plot the results over them in real-time. To run the script on a cloud platform instead, we run the “detectVideo_Cloud.py” script instead which is optimized for execution on a cloud service.



Figure 13: Detection testing

```
0: 384x640 2 ESP_Energys, 7.2ms
Speed: 1.0ms preprocess, 7.2ms inference, 3.0ms postprocess per image at shape (1, 3, 384, 640)

0: 384x640 2 ESP_Energys, 7.0ms
Speed: 2.1ms preprocess, 7.0ms inference, 2.0ms postprocess per image at shape (1, 3, 384, 640)

0: 384x640 2 ESP_Energys, 7.0ms
Speed: 3.0ms preprocess, 7.0ms inference, 1.0ms postprocess per image at shape (1, 3, 384, 640)

0: 384x640 2 ESP_Energys, 7.9ms
Speed: 1.1ms preprocess, 7.9ms inference, 1.0ms postprocess per image at shape (1, 3, 384, 640)

0: 384x640 2 ESP_Energys, 8.1ms
Speed: 1.0ms preprocess, 8.1ms inference, 2.0ms postprocess per image at shape (1, 3, 384, 640)

0: 384x640 4 ESP_Energys, 7.0ms
Speed: 2.0ms preprocess, 7.0ms inference, 2.0ms postprocess per image at shape (1, 3, 384, 640)
```

Figure 14: Console output of the detection script

References

MinGW-w64 (2007). Available at: <https://www.mingw-w64.org/> (Accessed: December 13, 2023).

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Intel (no date) *OpenCV - Open Computer Vision Library, 2000*. Available at: <https://opencv.org/> (Accessed: December 13, 2023).

Meta AI (no date) *PyTorch, 2016*. Available at: <https://pytorch.org/> (Accessed: November 13, 2023).

Rabid Viper Productions (2006) *AssaultCube*. Available at: <https://assault.cubers.net/> (Accessed: November 11, 2023).

Roboflow: Give your software the power to see objects in images and video (no date). Available at: <https://roboflow.com/> (Accessed: November 12, 2023).

Ultralytics / Revolutionizing the World of Vision AI (no date). Available at: <https://www.ultralytics.com/> (Accessed: November 17, 2023).

ultralytics/ultralytics: NEW - YOLOv8 🚀 in PyTorch > ONNX > OpenVINO > CoreML > TFLite (no date). Available at: <https://github.com/ultralytics/ultralytics> (Accessed: November 17, 2023).