

Configuration Manual

MSc Research Project Data Analytics

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Configuration Manual

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1 Introduction

This manual is for building the personal protective equipment (PPE) detection model which is trained with the YOLOv8x model. The configuration steps include a dataset collection, labelling, build the model, and evaluate the model using a specific python library.

2 System Configuration

2.1 Software Requirements

The two cloud Integrated Development Environment (IDE), which are Kaggle Notebook, and Google Collaboratory were used to build the object detection model. Both platforms are a form of website, so they can be used without installation. And the two platforms allow use free GPU. This research project was run on the GPU to accelerate training speed. As a programming language, python was adopted, and Google Chrome browser was used as shown in Figure 1. All libraries that are used to train the model are based on Python module.

Language	Python		
Browser	Google Chrome		
Cloud Platform	Kaggle Kernels	Google Colaboratory	
GPU Specification	NVIDIA Tesla T4 GPUS	NVIDIA Tesla T4 GPU	

Figure 1: Software specifications

2.2 Configuration setup

• Kaggle Notebook

On the Kaggle Notebook, one environment setup and two libraries installation needed to download dataset and train the model. Before installing libraries, the Internet usage option setting must be enabled. Figure 2 shows the step to activate the Internet usage setting: (1) Verify the phone number. This is set on the Account Settings and can be accessed by click on the profile. (2) Activate the Internet usage. This is set on the Notebook Settings. By clicking the right-side arrow icon, the setting menu is displayed. The Internet option is in the Notebook options.

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Ø	Þ	▶ !pip install roboflow
Φ		+ Code + Markdown
	I	<pre>!pip install ultralytics</pre>
ሔ		
\sim	ſ	from roboflow import Roboflow
		<pre>rf = Roboflow(api_key="GjXhEB7hz0Gz4KYWJn82")</pre>
୍ ତ		<pre>project = rf.workspace("research-project-i8wzf").project("ppe-detection-2e71 dataset = project.version(6).download("yolov8")</pre>
~		
	I	pip uninstall -y clearml
ē	_	
.0	>_	
		Notebook options ACCELERATOR None LANGUAGE Python PERSISTENCE No persistence
		ENVIRONMENT
		Pin to original environment
		You won't get new packages, but your code is less likely to break. What is a notebook environment? ①
		INTERNET
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Figure 2: Enable the Internet usage setting in Kaggle Notebook

• Activate GPU accelerator in the Kaggle Notebook

The three-dot icon on the right-side in the Notebook give access the environment configuration, as shown in Figure 3. In the sixth menu, in the Accelerator sub-menu, the GPU T4 x2 type is selected.

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Φ		+ Code + Markdown		¢	Factory reset		
	L]:	<pre>!pip install ultralytics</pre>		•	Restart & Clea	r Cell Outputs	
*		pip install ultralytics		í	View Session M	Metrics	
<>			w	Ø	Upgrade to Go	ogle Cloud Al Noteb	ooks
	[]:	from roboflow import Roboflo		۲	Accelerator)		
ଡ		<pre>rf = Roboflow(api_key="GjXF project = rf.workspace("res</pre>	🗸 None			"ppe-detection-2	e71
~		<pre>dataset = project.version(6</pre>	GPU T4 x2				
			GPU P100				
	[]:	pip uninstall -y clearml	TPU VM v3-8				
						J	_
	[]:	pip uninstall -y wandb					
Ē	2_						

Figure 3: Enable GPU accelerator in Kaggle Notebook

• Google Colab Notebook

On the Google Colab Notebook, two configuration is needed: Activate GPU usage and mount Google Drive. The prediction phase was executed using the GPU, and the test dataset and the result for the prediction were stored in Google Drive. This can keep the files even if the notebook is closed. Figure 4 shows the Hardware Accelerator settings in the Colab Notebook: (1) Click Runtime menu and Change runtime type. (2) Select Python3 and T4 GPU. To access the Google Drive can be executed the code in the Figure 5. This must be run whenever the notebook is opened.

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Figure 4: Enable GPU accelerator in Google Colab Notebook

```
from google.colab import drive
drive.mount('<u>/content/drive</u>', force_remount=True)
Mounted at /content/drive
```

Figure 5: Setup access to Google Drive in Google Colab Notebook

3 Data collection

The dataset was obtained from an open-source platform.¹ There are various topics of image datasets for research project. By using a keyword "PPE detection", the dataset was found in the platform. It was downloaded in the local file system to labelling task. The platform is a website that provides graphic interface. So, the download step was executed to click "Download the Dataset" button.

4 Data pre-processing

4.1 Data labelling

The dataset was downloaded contained 13 classes. This study needed the four items of safety equipment. Therefore, the new classes were named to have only four items using an annotation tool.² The new names of the items are "helmet", "vest", "glove", and "boots". The step to capture bounding boxes of the four objects consists of the two steps. Firstly, the dataset is needed to upload the annotation platform. Lastly, dragging boxes is where the objects are in the images and then entering class's name as shown in Figure 6.



Figure 6: Example of labelling for helmet, vest, and boots

¹https://universe.roboflow.com

 $^{^{2}} https://roboflow.com/annotate$

4.2 Data augmentation

After labelling task, the dataset is 1,490 images. Three data augmentation techniques were applied to increase and improve the detection performance. This can be applied in the same platform where the labelling task was performed.² When the labelling step was completed, the new dataset was deployed to the platform where the dataset was collected. As the tool feature, the augmentation techniques are applied after splitting dataset into the three sub-datasets, which are the training, validation, and test dataset. The dataset was divided according to the percentage set in the tool.

5 Implementation

5.1 Install Python Packages and Import Dataset

Two libraries were installed for downloading dataset and pre-trained model in Figure 7 and 8. The dataset that was completed pre-processing phase was stored in the same platform where it is acquired. The platform provide Application Programming Interface (API) key to download the dataset in the Notebook. Figure 9 shows the download code using API. The dataset was stored in Output folder in Kaggle Notebook.

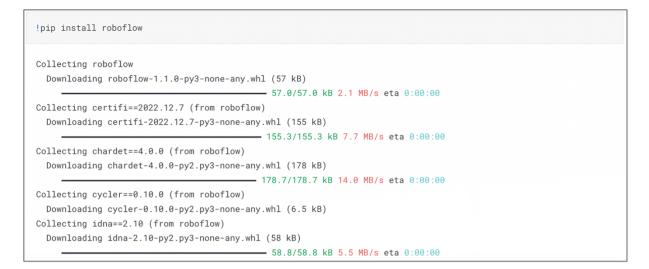
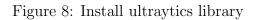


Figure 7: Install roboflow library





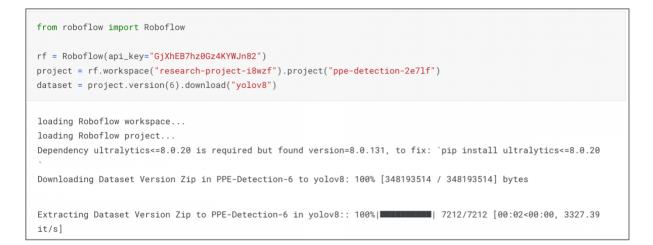


Figure 9: Download dataset to Kaggle Notebook

5.2 Build the YOLOv8x Model

from ultralytics import YOLO						
path = "	<pre>path = "/kaggle/working/PPE-Detection-6/data.yaml"</pre>					
# Load a	model					
model =	YOLO('volov8x	. D	t') # 1	oad a pretrained model (recommend	ed for training)	
model	1020()02010		. , " -	oud a precrained model (recommend	ed for craining/	
# Troin	the model					
train_re	esult = model.	tr	ain(data	=path, batch=8, epochs=100, imgs;	z=640, save_period=10)	
print(tr	ain_result)					
	from		params	module	arguments	
0	-1		2320	ultralytics.nn.modules.conv.Conv	[3, 80, 3, 2]	
1	-1		115520	ultralytics.nn.modules.conv.Conv	[80, 160, 3, 2]	
2	-1		436800	ultralytics.nn.modules.block.C2f	[160, 160, 3, True]	
3	-1		461440	ultralytics.nn.modules.conv.Conv	[160, 320, 3, 2]	
4	-1		3281920	ultralytics.nn.modules.block.C2f	[320, 320, 6, True]	
5	-1		1844480	ultralytics.nn.modules.conv.Conv	[320, 640, 3, 2]	
6	-1	-	13117440	ultralytics.nn.modules.block.C2f	[640, 640, 6, True]	
7	-1	1	3687680	ultralytics.nn.modules.conv.Conv	[640, 640, 3, 2]	
8	-1	3	6969600	ultralytics.nn.modules.block.C2f	[640, 640, 3, True]	
9	-1	1	1025920	ultralytics.nn.modules.block.SPPF	[640, 640, 5]	
10	-1	1	0	torch.nn.modules.upsampling.Upsample	[None, 2, 'nearest']	
11	[-1, 6]	1	0	ultralytics.nn.modules.conv.Concat	[1]	
12	-1	3	7379200	ultralytics.nn.modules.block.C2f	[1280, 640, 3]	
13	-1	1	0	torch.nn.modules.upsampling.Upsample	[None, 2, 'nearest']	
14	[-1, 4]	1	0	ultralytics.nn.modules.conv.Concat	[1]	
15	-1	3	1948800	ultralytics.nn.modules.block.C2f	[960, 320, 3]	
16	-1	1	922240	ultralytics.nn.modules.conv.Conv	[320, 320, 3, 2]	
17	[-1, 12]	1	0	ultralytics.nn.modules.conv.Concat	[1]	
18	-1	3	7174400	ultralytics.nn.modules.block.C2f	[960, 640, 3]	
19	-1	1	3687680	ultralytics.nn.modules.conv.Conv	[640, 640, 3, 2]	
20	[-1, 9]	1	0	ultralytics.nn.modules.conv.Concat	[1]	
21	-1	3	7379200	ultralytics.nn.modules.block.C2f	[1280, 640, 3]	
22 [15, 18, 21] 1 8721820 ultralytics.nn.modules.head.Detect [4, [320, 640, 640]]						
Model summary: 365 layers, 68156460 parameters, 68156444 gradients						

Figure 10: The summary of the YOLOv8x model

The above code is for importing the pre-trained model, YOLOv8x model and setup the hyperparameters to train the model with the dataset. 'path' variable is to indicate where the training, validation, and test dataset is located in. When the above code is executed, the outline of the model's architecture is provided.

100 epochs completed in 6.667 hours. Optimizer stripped from runs/detect/train/weights/last.pt, 136.7MB Optimizer stripped from runs/detect/train/weights/best.pt, 136.7MB Validating runs/detect/train/weights/best.pt.. Ultralytics YOLOv8.0.131 🚀 Python-3.10.10 torch-2.0.0 CUDA:0 (Tesla T4, 15110MiB) Model summary (fused): 268 layers, 68127420 parameters, 0 gradients mAP50 mAP50-95): 100% Class Images Instances Box(P R 1.62it/sl all 152 670 0.956 0.945 0.965 0.695 boots 152 146 0.892 0.846 0.9 0.652 glove 152 216 0.981 0.965 0.986 0.652 helmet 152 152 0.972 1 0.989 0.74 152 156 0.978 0.968 0.982 0.738 vest Speed: 1.6ms preprocess, 24.8ms inference, 0.0ms loss, 2.6ms postprocess per image Results saved to runs/detect/train

Figure 11: Training result and validation of the YOLOv8x model

Figure 11 is given when the training is completed. The trained model is saved the form of a 'best.pt' file. The trained model is examined with the validation dataset. In addition to the time spent on learning, the number of images for each class is displayed and the accuracy is calculated.

6 Assessment the trained model

The test dataset is used to evaluate the trained model. The test dataset and the 'best.pt' file are needed to assess the model. This step can be executed in the Google Colab Notebook to use GPU. Mounting Google Drive, installing libraries, and downloading dataset is consistent with the code in Figures 5, 7, 8 and 9.

6.1 Prediction with the trained model

The trained model is loaded as shown in Figure 12. And then the prediction is made of what class each object is. Figure 13 shows the codes for the prediction and for displaying the prediction result.

```
from ultralytics import YOLO
model = YOLO('<u>/content/drive/MyDrive/best.pt</u>')
WARNING A /content/drive/MyDrive/best.pt appears to require 'dill', which is not in ultralytics requirements.
AutoInstall will run now for 'dill' but this feature will be removed in the future.
Recommend fixes are to train a new model using the latest 'ultralytics' package or to run a command with an official YOLOV8 model,
requirements: Ultralytics requirement ['dill'] not found, attempting AutoUpdate...
Collecting dill
Downloading dill-0.3.6-py3-none-any.whl (110 kB)
110.5/110.5 kB 4.7 MB/s eta 0:00:00
Installing collected packages: dill
Successfully installed dill-0.3.6
requirements: AutoUpdate success S 5.0s, installed 1 package: ['dill']
requirements: A Restart runtime or rerun command for updates to take effect
```

Figure 12: Load the trained model



Figure 13: The prediction process and the prediction result

6.2 Evaluation the trained model

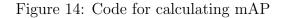
The evaluation library is required to evaluate the prediction result. mAP and F1 score are calculated using Object-Detection-Metrics library.³ For using the library, the two requirements are needed. Converting the text file which is the YOLO format to the xml file, which has PASCAL VOC format and the library's source codes.⁴ The python files can be copied to Google Drive. The converting code is obtained from Kaggle and is modified

³https://github.com/eypros/Object-Detection-Metrics

⁴https://github.com/ultralytics/ultralytics/issues/2042

for this project's dataset.⁵ '!python' command can be used to run the evaluation library in the Colab Notebook as shown in Figure 14. The F1 score is calculated from the results generated from the code in Figure 14. The F1 score calculation code is shown in Figure 15.

```
Ipython /content/drive/MyDrive/Object-Detection-Metrics/pascalvoc.py -g /content/drive/MyDrive/gt/ -d /content/drive/MyDrive/Dject-Detection-Metrics/pascalvoc.py:432: SyntaxWarning: "is not" with a literal. Did you mean "!="?
if len(errors) is not 0:
Figure(640x480)
AP: 0.50760 (0)
Figure(640x480)
AP: 0.54074 (1)
Figure(640x480)
AP: 0.54074 (2)
Figure(640x480)
AP: 0.92217 (2)
Figure(640x480)
AP: 0.92215 (3)
mAP: 0.72544
```



```
def GetMetricsValues(content):
   content = content.replace(']', '')
   content = content.replace('[', '')
   str line = content.split(':')
   str list = str line[1].split(',')
   num_list = [eval(i) for i in str_list]
   #print(len(num list))
   return num_list
with open('/content/drive/MyDrive/Object-Detection-Metrics/results/results.txt') as f:
  lines = f.readlines()
  content = [line.strip() for line in lines]
  f.close()
pre_list = []
rec_list = []
for i in range(0, len(content)):
  if "Precision:" in content[i]:
   pre_list.append(GetMetricsValues(content[i]))
  elif "Recall:" in content[i]:
   rec_list.append(GetMetricsValues(content[i]))
for i in range(0, len(pre_list)):
 img_score = 0
  total = len(pre_list[i])
  for j in range(0, total):
   precision = float(pre_list[i][j])
   recall = float(rec_list[i][j])
   score = (2*precision*recall)/(precision+recall)
   img_score = img_score + score
  print(f'class {i}')
  print(f'sum: {img_score}, total: {total}')
  print(f'f-1 score: {img_score / total}')
  print('\n')
```

Figure 15: Code for calculating F1 score

 $^{{}^{5}}https://www.kaggle.com/code/siddharthkumarsah/convert-yolo-annotations-to-coco-pascal-voc$