

Configuration Manual

MSc Research Project Data Analytics

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Configuration Manual

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1 Introduction

This document contains the instructions for reproducing the code for the project on driver drowsiness. The steps taken for reproducing the deep learning models are listed below.

2 System Configuration

Hardware and software setup for the research work is explained below with respective diagrams.

2.1 Hardware Configuration

The hardware configuration, Dell Alienware M15 R6 has been used. The specifications are – Operating System - Microsoft Windows 11 Home Single Language, Processor – Intel Core i7, RAM – 16GB, GPU – nvidia 3060 8GB, SSD – 500GB shown in Figure. 1

System > /	About
Ravjyot Alienware m15 R6	
i Device specif	ications
Device name	Ravjyot
Processor	11th Gen Intel(R) Core(TM) i7-11800H @ 2.30GHz 2.30 GHz
Installed RAN	1 16.0 GB (15.7 GB usable)

Figure 1: System configuration

2.2 Software Configuration

For software configuration, Python 3.10, Jupyter notebook Figure. 2

- Jupyter Notebook It is used as the primary GUI for model development purposes.
- Python 3.10 Python has been used as the main programming language.



Figure 2: Jupyter notebook

3 Implementation

3.1 Data Source

Dataset can be downloaded from the below. MRL Dataset.¹ Refer Figure. 3



Figure 3: MRL dataset

3.2 Feature Engineering

- Open data preparation code in Jupyter notebook.
- Importing necessary libraries Figure. 4
- Checking the files ending with ".png" format and copying the data into two folders closed eye and open eye. Figure. 5

https://www.overleaf.com/project/639a3b5a0c912cc351a54e26

- Installing split-folders library Figure. 6
- Splitting the data into train, test, and validation Figure. 7

¹http://mrl.cs.vsb.cz/eyedataset

💭 jupyter	data preparat	ion Last Ch	eckpoint:	Last Sunda	y at 12:11 PM (autosa	ived)
File Edit	View Insert	Cell Kerr	nel H	lelp		
8 + % 4) 🖪 🛧 🖌 J	Run	C H	Code	~	
Tn [2]:	import os					
1[2].	<pre>import shutil import glob from tqdm import</pre>	t tqdm				

Figure 4: Importing libraries



Figure 5: Checking image format

In [4]: !pip install split-folders

Collecting split-folders

Downloading split_folders-0.5.1-py3-none-any.whl (8.4 kB) Installing collected packages: split-folders Successfully installed split-folders-0.5.1

Figure 6: Installing library split-folders



Figure 7: Train, test, validation split

3.3 Training the model

• Importing the required library. Figure. 8



Figure 8: Importing library

- Checking if system GPU is active and available. Figure. 9
- Keras function ImageDataGenerator is used to extract the Train and validation dataset from the prepared dataset folder, with image size defined as 80 pixels length 80 pixels width. Figure. 10
- InceptionV3 model's architecture is pre-defined in Keras. By default, InceptionV3 takes input of the shape (299, 299, 3). But it needs to be customized to accommodation the input shape of the images, that is (80, 80, 3) where 3 is the RGB Component. Figure. 11

```
In [5]: from tensorflow.python.client import device_lib
def get_available_devices():
    local_device_protos = device_lib.list_local_devices()
    return [x.name for x in local_device_protos]
print(get_available_devices())
In [8]: tf.test.is_gpu_available()
True
In [4]: with tf.device('/gpu:1'):
    tf.config.list_physical_devices('GPU')
```

Figure 9: System GPU check



Figure 10: Extracting the train and validation dataset



Figure 11: Model's architecture

• Since the pre-trained weights from Imagenet have been used, thus the model needs to be prevented from updating the weights during the training. Thus, for each layer the trainable parameter has been set to False. Figure. 12



Figure 12: Trainable parameter

• Summarizing the model Figure. 13

In [13]:	model.summary()				
	Model: "model"				^
	Layer (type)	Output Shape	Param #	Connected to	1
	input_1 (InputLayer)	[(None, 80, 80, 3)]	0	[]	
	conv2d (Conv2D)	(None, 39, 39, 32)	864	['input_1[0][0]']	
	<pre>batch_normalization (BatchNorm alization)</pre>	(None, 39, 39, 32)	96	['conv2d[0][0]']	
	activation (Activation)	(None, 39, 39, 32)	0	['batch_normalization[0][0]']	
	conv2d_1 (Conv2D)	(None, 37, 37, 32)	9216	['activation[0][0]']	
	<pre>batch_normalization_1 (BatchNo rmalization)</pre>	(None, 37, 37, 32)	96	['conv2d_1[0][0]']	
	activation_1 (Activation)	(None, 37, 37, 32)	0	['batch_normalization_1[0][0]']	÷

Figure 13: Model Summary

• Saves the Best model. Figure. 14

In [14]:	<pre>from tensorflow.keras.callbacks import ModelCheckpoint,EarlyStopping, ReduceLROnPlateau</pre>	
In [15]:	<pre>checkpoint = ModelCheckpoint(r"C:\Users\ravjy\Documents\College Subjects\Semester 3\Research Project\driver drowsiness 1311\driv monitor='val_loss',save_best_only=True,verbose=3)</pre>	ł

Figure 14: Checkpoint

- It monitors the given parameter (validation loss in this case) for given number of patience level (5 in this case). If the value of validation loss does not improve for the 5 consecutive epochs, then the model training needs to stop. Figure. 15
- This also monitors the given parameter (validation loss in this case) for given number of patience level (3 in this case). If the value of validation loss does not improve for the 3 consecutive epochs, then the model training needs to stop. Figure. 16
- Following parameters were used when the model was compiled: Optimizer was chosen to be Adam, loss was chosen to be categorical crossentropy, evaluation metrics were chosen to be categorical accuracy, precision, and recall. 17
- Model training was then initiated with the epoch number set to 50. 18

earlystop = EarlyStopping(monitor = 'val_loss', patience=5, verbose= 3, restore_best_weights=True)

Figure 15: Early stopping from Keras

learning_rate = ReduceLROnPlateau(monitor= 'val_loss', patience=3, verbose= 3,)
callbacks=[checkpoint,earlystop,learning_rate]

Figure 16: ReduceLROnPlateau from Keras



Figure 17: Model compile

Figure 18: Model training

4 Evaluation

• During the training, the loss as well as validation loss are coming down with each epoch whereas the categorical accuracy of train and validation datasets are increasing with each epoch. Refer Figure. 19



Figure 19: Evaluation

• Plot of Train and validation losses over 50 epochs- 20



Figure 20: Plot of Train and validation losses over 50 epochs

- Plot of Train and validation categorical accuracies over 50 epochs 21
- Code for calculating accuracy and loss for train, validation and test datasets 22



Figure 21: Plot of Train and validation categorical accuracies over 50 epochs

```
In []: acc_tr, loss_tr = model.evaluate(train_data)
print(acc_tr)
print(loss_tr)
In []: acc_vr, loss_vr = model.evaluate(validation_data)
print(acc_vr)
print(loss_vr)
In []: acc_test, loss_test = model.evaluate(test_data)
print(acc_tr)
print(loss_tr)
```

Figure 22: Code for calculation of categorical accuracies and losses

5 Running the model

• Importing the libraries Refer Figure. 23



Figure 23: Importing libraries

• Importing Haar cascade files Refer Figure. 24

In [7]:	<pre>face_cascade = cv2.CascadeClassifier(cv2.data.haarcascades + 'haarcascade_frontalface_default.xml')</pre>
	<pre>eye_cascade = cv2.CascadeClassifier(cv2.data.haarcascades + 'haarcascade_eye.xml')</pre>
	<pre>model = load_model(r"C:\Users\ravjy\Documents\College Subjects\Semester 3\Research Project\driver drowsiness\driver drowsiness\driver</pre>

Figure 24: Haar cascade files

• Code for early stop. 25

earlystop = EarlyStopping(monitor = 'val_loss', patience=5, verbose= 3, restore_best_weights=True)

Figure 25: early stop

- Code for model compile and fit. 26
- Code for live camera feed. 27

Figure 26: Model compile and fit

```
import winsound
frequency = 2500 # Set frequency to 2500
duration = 1500 # Set duration to 1500 ms == 1.5 sec
import numpy as np
import cv2
path = "haarcascade_frontalface_default.xml"
faceCascade = cv2.CascadeClassifier(cv2.data.haarcascades + "haarcascade_frontalface_default.xml")
cap = cv2.VideoCapture(0)
#check if webcam is opened correctly
if not cap.isOpened():
   cap = cv2.VideoCapture(1)
cap.set(cv2.CAP_PROP_FPS, 15)
counter = 0
while True:
    ret,frame = cap.read()
    eye_cascade = cv2.CascadeClassifier(cv2.data.haarcascades + 'haarcascade_eye.xml')
    gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
eyes = eye_cascade.detectMultiScale(gray, 1.1, 4)
for x,y,w,h in eyes:
        roi_gray = gray[y:y+h, x:x+w]
roi_color = frame[y:y+h, x:x+w]
        cv2.rectangle(frame, (x,y), (x+w,y+h), (0, 255, 0), 2)
        eyess = eye_cascade.detectMultiScale(roi_gray)
        if len(eyess) == 0:
             print("Eyes are not detected")
        else:
             for (ex, ey, ew, eh) in eyess:
    eyes_roi = roi_color[ey: ey+eh, ex: ex+ew]
    gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
    if(faceCascade.empty()==False):
        print("detected")
    faces = faceCascade.detectMultiScale(gray, 1.1, 4)
    # Draw a rectangle around eyes
    for (x,y,w,h) in faces:
    cv2.rectangle(frame, (x, y), (x+w, y+h), (0, 255, 0), 2)
font = cv2.FONT_HERSHEY_SIMPLEX
    final_image = cv2.resize(eyes_roi, (80,80))
    final_image = np.expand_dims(final_image, axis=0)
    final_image = final_image/255.0
    Predictions = model.predict(final_image)
    print(Predictions)
```

Figure 27: Live camera feed