National College of Ireland

Configuration Manual

MSc Research Project
Data Analytics

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Project Submission Sheet
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Configuration Manual

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1 Introduction

This configuration manual explains the hardware and the software used in project to identify the social distancing from Video Surveillance Cameras using Deep Learning Architectures. The steps mentioned in this manual can be followed to reproduce the results and build a Social Distancing Monitoring model.

2 System Specification

In this section we will discuss Hardware and Software specifications that are used while implementing this project

2.1 Hardware Requirement

The system specification of the system in which all the experiments are implemented are discussed below:

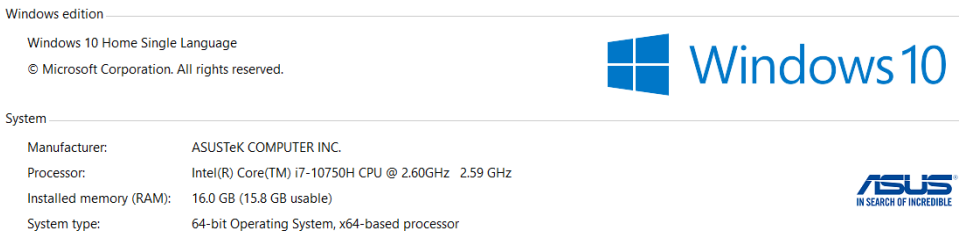

Figure 1: System Specification

- **Processor:** Intel Core i7.
- **System Memory:** 1TB Hard disk
- **RAM:** 16GB

2.2 Software Requirement

- **Windows Edition** Windows 10 Enterprise.
- **Scripting Language:** Python 3.9.9

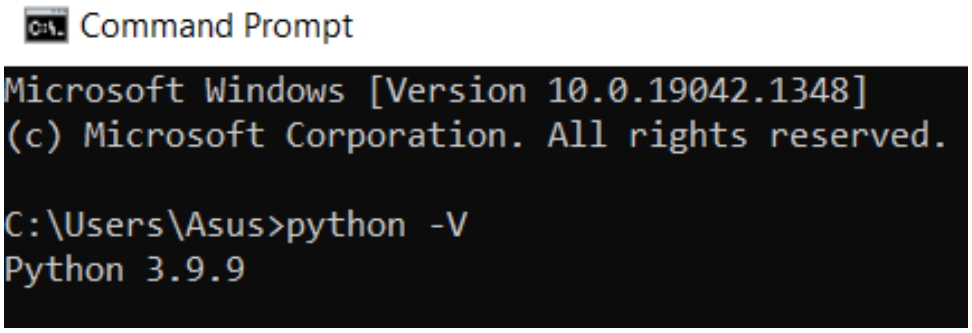

Figure 2: System Specification

- **RAM:** 16GB
- **Cloud Storage:** Google Drive
- **Libraries:** TensorFlow, Matplotlib, OpenCV, Numpy, Keras.

3 Implementation of social distancing monitoring tool

The main task of person detection with bounding boxes has been achieved using YOLOv3 model along with 2 other algorithm plot.py and utills.py and finally importing these two algorithum to main main.ipynb.

Step 1 is to install important libraries before executing main.ipynb *opencv* (2021)

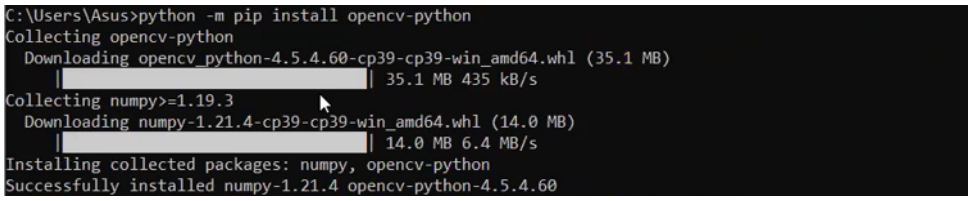

Figure 3: Library's installation step 1

Step 2 is to import required libraries and 2 other algorithm plot.py and utills.py in main.ipynb.

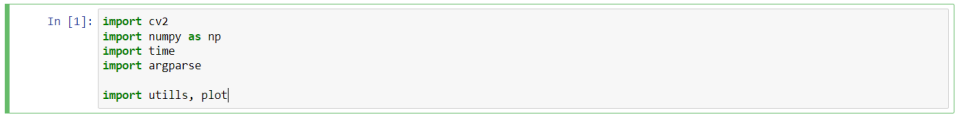

Figure 4: Import required libraries and 2 other algorithm

Step 3 is to run cell 2 having default configuration for confidence, threshold and cell 3 having function to get mouse point.

```
In [2]: confid = 0.5
        thresh = 0.5
        mouse_pts = []
```

```
In [3]: def get_mouse_points(event, x, y, flags, param):

            global mouse_pts
            if event == cv2.EVENT_LBUTTONDOWN:
                if len(mouse_pts) < 4:
                    cv2.circle(image, (x, y), 5, (0, 0, 255), 10)
                else:
                    cv2.circle(image, (x, y), 5, (255, 0, 0), 10)

                if len(mouse_pts) >= 1 and len(mouse_pts) <= 3:
                    cv2.line(image, (x, y), (mouse_pts[len(mouse_pts)-1][0], mouse_pts[len(mouse_pts)-1][1]), (70, 70, 70), 2)
                    if len(mouse_pts) == 3:
                        cv2.line(image, (x, y), (mouse_pts[0][0], mouse_pts[0][1]), (70, 70, 70), 2)

                if "mouse_pts" not in globals():
                    mouse_pts = []
                mouse_pts.append((x, y))
```

Figure 5: Default values

Step 4, Defining calculate_social_distancing function and giving Yolo model Path and sample video path.

```
In [4]: def calculate_social_distancing(vid_path, net, output_dir, output_vid, ln1):

            count = 0
            vs = cv2.VideoCapture(vid_path)

            # Get video height, width and fps
            height = int(vs.get(cv2.CAP_PROP_FRAME_HEIGHT))
            width = int(vs.get(cv2.CAP_PROP_FRAME_WIDTH))
            fps = int(vs.get(cv2.CAP_PROP_FPS))

            # Set scale for birds eye view
            # Bird's eye view will only show ROI
            scale_w, scale_h = utills.get_scale(width, height)


            points = []
            global image

            while True:

                (grabbed, frame) = vs.read()

                if not grabbed:
                    print('here')
                    break
```

Figure 6: calculate_social_distancing function

```
In [5]: """video_path = input("Video_Path")
        model_path = input("Model_Path")"""
        video_path = r"example.mp4"
        model_path = r"models"
```

Figure 7: Yolo model Path and sample video path

Final step is run last cell of main.ipynb to run complete framework and generate bounding box around sample video.

```
In [6]:

output_dir = './output/'
output_vid = './output/'
uop = "NO"

if model_path[len(model_path) - 1] != '/':
    model_path = model_path + '/'

weightsPath = model_path + "yolov3.weights"
configPath = model_path + "yolov3.cfg"

net_yl = cv2.dnn.readNetFromDarknet(configPath, weightsPath)
ln = net_yl.getLayerNames()
ln1 = [ln[i - 1] for i in net_yl.getUnconnectedOutLayers()]

cv2.namedWindow("image")
cv2.setMouseCallback("image", get_mouse_points)
np.random.seed(42)

calculate_social_distancing(video_path, net_yl, output_dir, output_vid, ln1)
```

Figure 8: Complete framework

After completing this step, a window will appear as shown in fig 9, where mouse points must be picked to convert the frame into a Bird's-eye view, and distance between individual bounding boxes must be determined using Euclidean Distance as shown in fig 10.

Figure 9: Mouse points selection to convert the frame into Bird-eye view

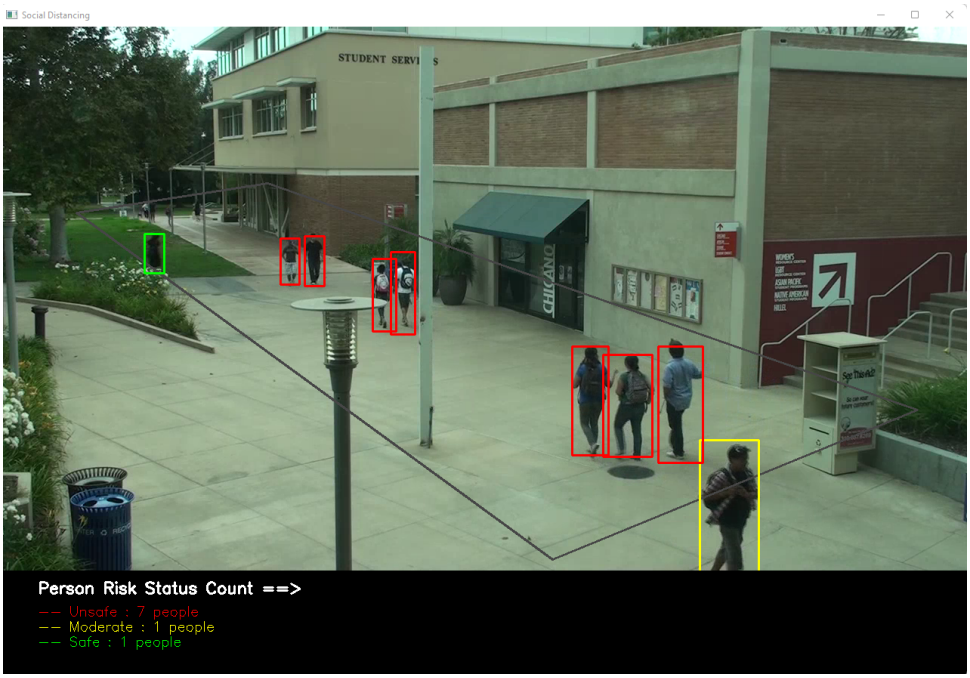

Figure 10: Final output calculated using Euclidean Distance

4 Results and evaluation recreation using tensorboard

In this paper, we used three different object detection methods to identify the person class. A performance analysis of each algorithm was carried out to understand the best model.

Step 1 install important libraries tenserflow *tensorflow* (2021)

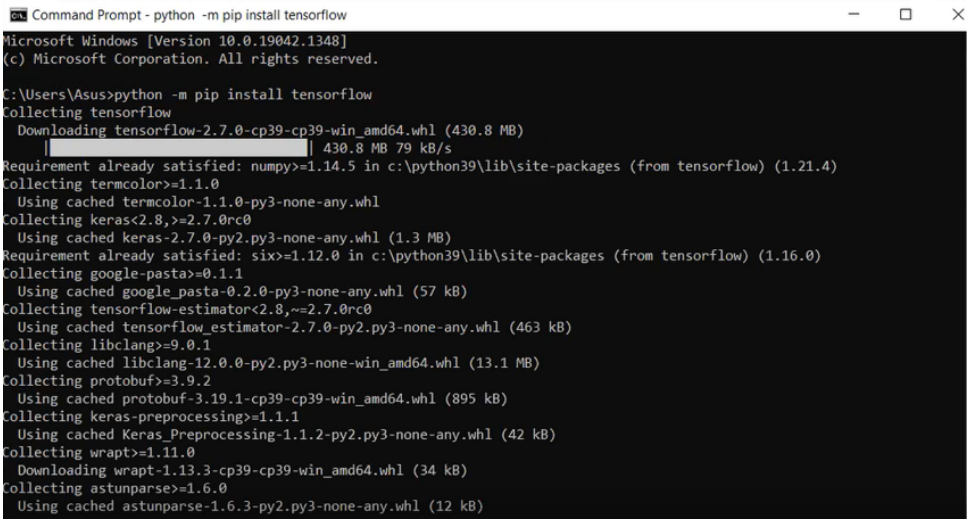

Figure 11: Tenserflow libraries installation

Step 2 changing current directory to directory containing trained models file as shown in fig 12.

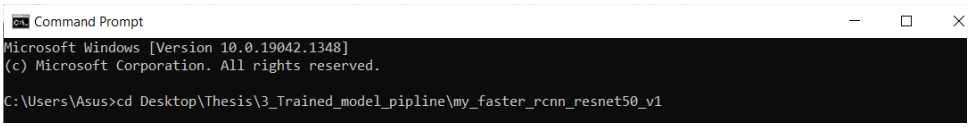

Figure 12: Changing current directory to directory containing trained models filel

Step 3 Ruining tensorboard command to show the output of selected model as shown in figure 13
tensorboard –logdir=my_faster_rcnn_resnet50_v1

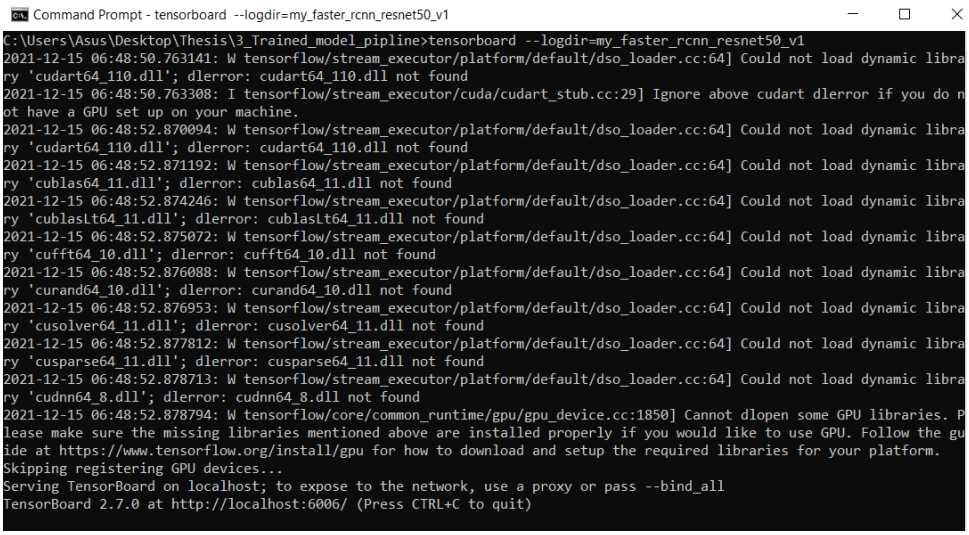

Figure 13: Tensorboard command to get total/$_{l}oss$

Step 4 Opening http://localhost:6006/ to get the total tensorboard output

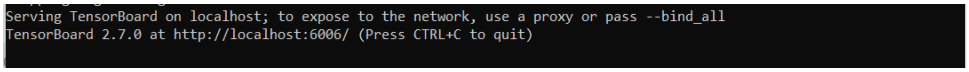

Figure 14: output link

Loss is a statistic that must be calculated in order to assess the model's effectiveness. In terms of performance, the model with the lowest Total loss is regarded the best. The mAP score, training duration, and FPS were observed and graphically depicted during the model training.

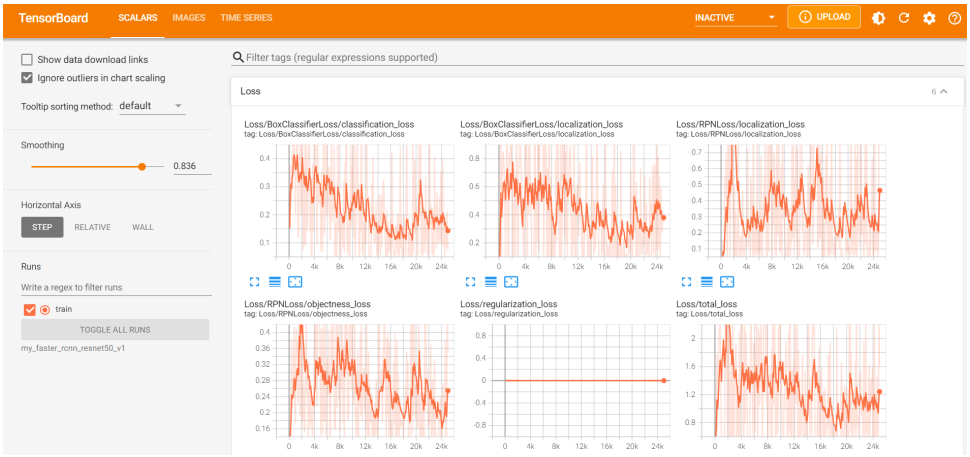

Figure 15: Tensorboard output

5 Other Software Used

For the thesis's documentation, we used the overleaf. Figure 16 shows how Overleaf can be used for documentation.*overleaf* (2021).

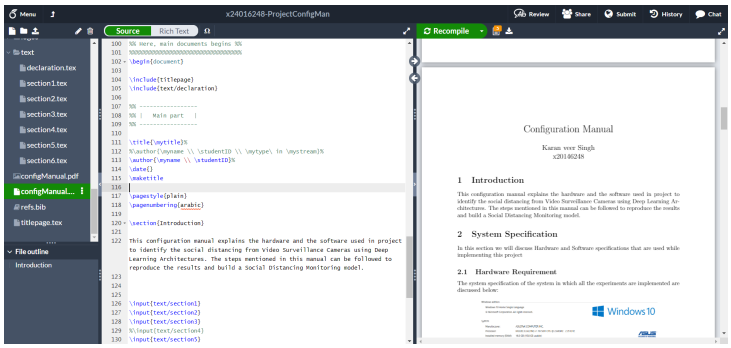

Figure 16: Overleaf

References

opencv (2021). [Online; accessed 9. Dec. 2021].
URL: *https://pypi.org/project/opencv-python/*

overleaf (2021). [Online; accessed 9. Dec. 2021].
URL: *https://www.overleaf.com/project*

tensorflow (2021). [Online; accessed 10. Dec. 2021].
URL: *https://www.tensorflow.org/*