

Configuration Manual

MSc Research Project
MSc. in Data Analytics

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Project Submission Sheet
School of Computing**



Student Name:	Mardwin Alejandro Cardenas Rodriguez
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Programme:	MSc. in Data Analytics
Year:	2022
Module:	MSc Research Project
Supervisor:	Majid Latifi
Submission Due Date:	31/01/2022
Project Title:	Configuration Manual
Word Count:	963
Page Count:	15

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Configuration Manual

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1 Introduction

This setup documentation contains all of the relevant data, including the equipment I utilized, software and hardware specifications, crucial code screenshots, and reproducibility requirements. The specifications are detailed in Section 2, which includes the Software Standard and Hardware Specifications.

2 Specifications

The following chapters go through the software and hardware requirements for this proposed study.

2.1 Software Configurations

As we can see in the Table 1, the summarize of the software configurations that it have been employed over this investigation. Figure 2 demonstrates the hardware and operating system performance.

Table 1: Software

Software	Configuration
Operational System	Windows 10 Home Single Language
Online IDE	Google Colab notebooks
Coding Language	Python
Coding Language Version	Python 3.7
Additional Tools Used	RoboFlow, LabelMe, Google Colab

2.2 Hardware Configurations

Table 2 illustrates the hardware configurations used in this investigation.

Table 2: Hardware

Hardware	Configuration
System	Intel(R) Core(TM) 4210U
Operation System	Windows 10 Home Single Language
RAM	6.00 GB
Hard Disk	Acer Aspire V3- EA107501
Libraries	cv2, os, torch, roboflow, yaml, utils
Graphic Card	Intel (R) HD Graphics Family



Figure 1: Device and Windows Specifications

3 Integrated Development Environment

To conduct the research and run the code, Google Colab's Jupyter Notebook was utilized. Anaconda Navigator is now loaded, and the Figure 2 bellow shows how it appears once I start it.

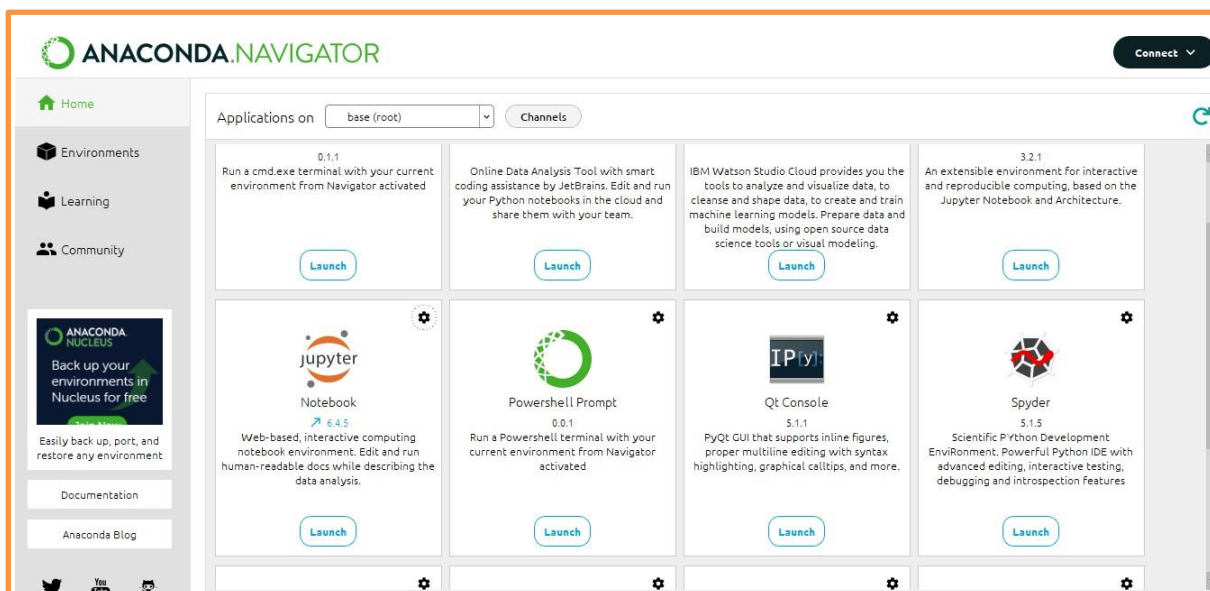


Figure 2: Anaconda Navigator

To utilize the Jupyter Notebook, launch the Anaconda Navigator and select on jupyter notebook, as can be seen in Figure 3. You should see something like this.

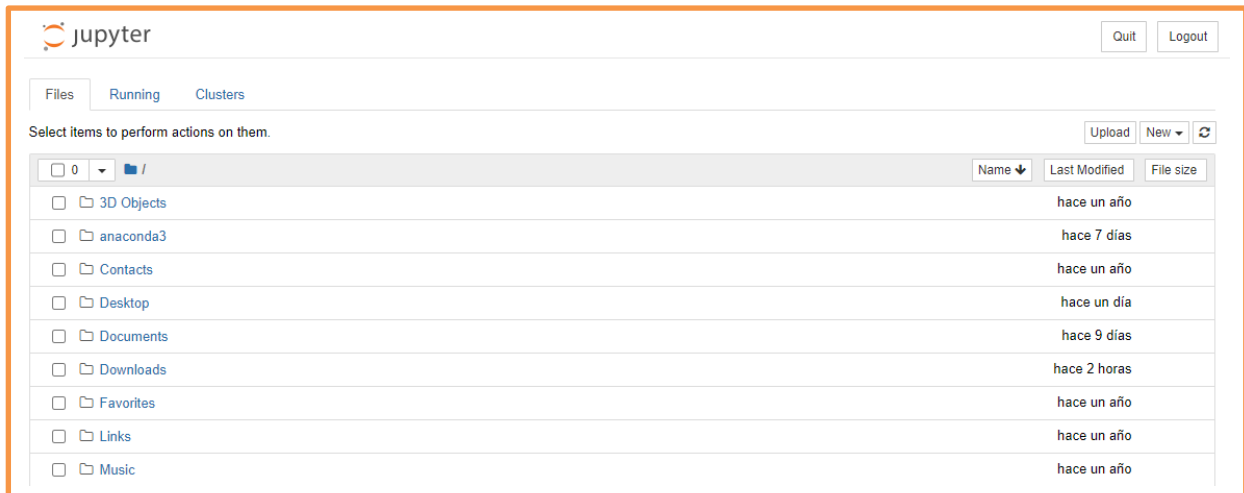


Figure 3: Jupyter notebook launched

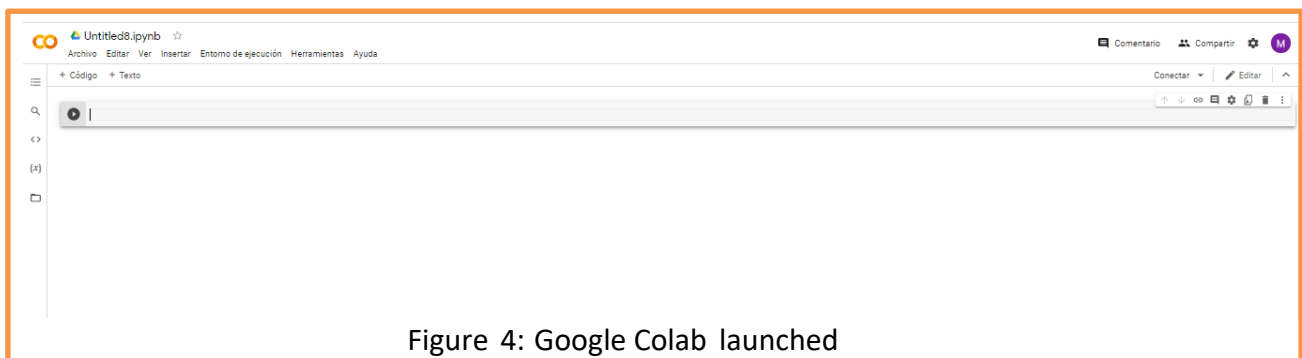


Figure 4: Google Colab launched

4 LabelMe

After Anaconda is installed, In an Anaconda Prompt we must run the following commands:

4.1 Download Labelme

```
# python3
conda create --name=labelme python=3.6
conda activate labelme
pip install labelme
```

Figure 5: Installation commands

1.1 Open Labelme

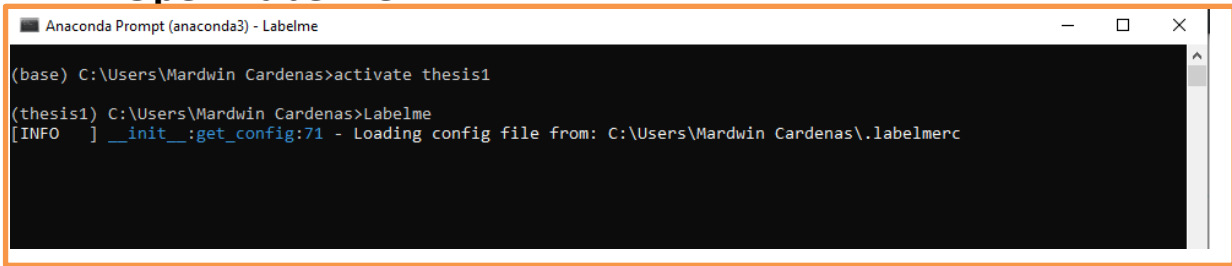


Figure 6: Anaconda Prompt command

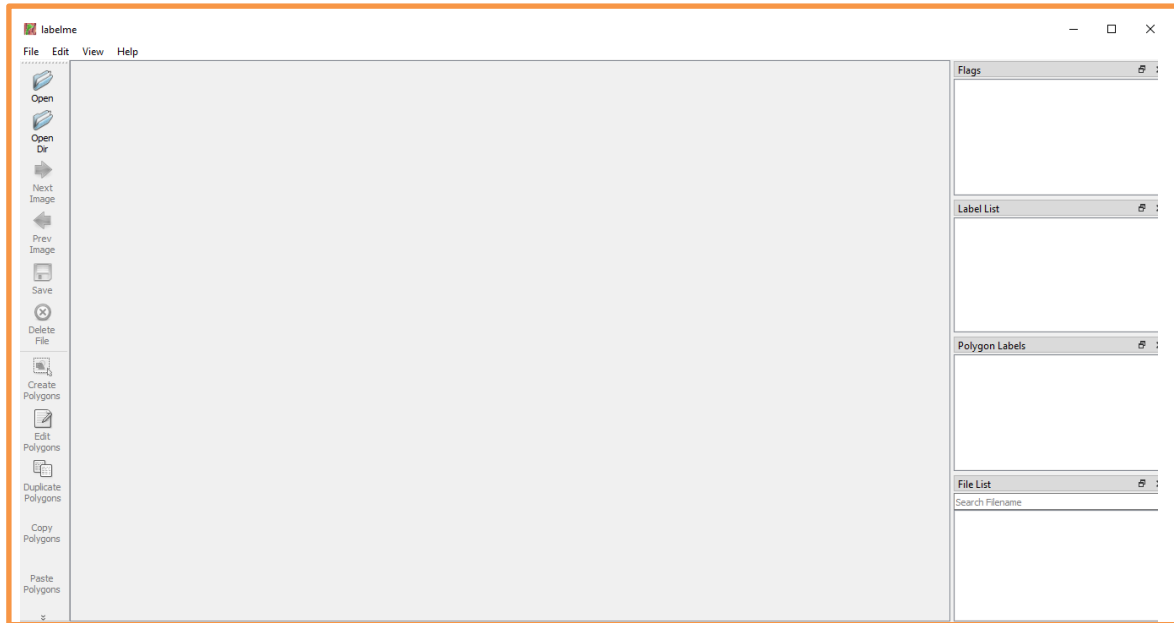


Figure 7: LabelMe Application

1.1 Select Directory to open and save images

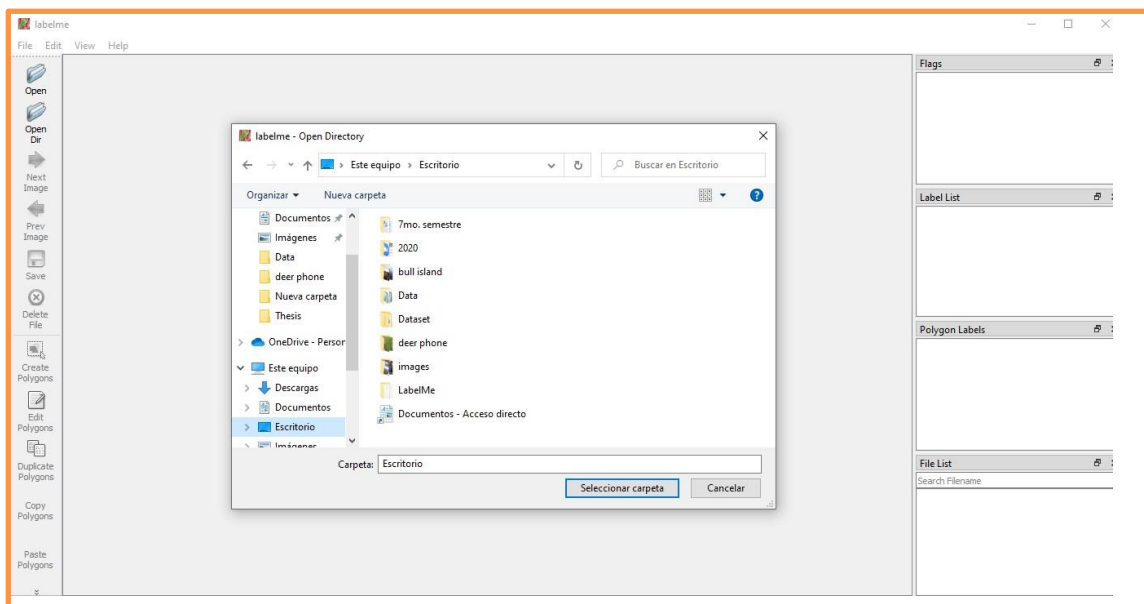


Figure 8: LabelMe Directory Selection

1.2 Draw and Save Annotations

When we select and save, the photograph is stored to the place we have specified previously. Afterwards we just click on the next photograph and repeat the process for each picture..

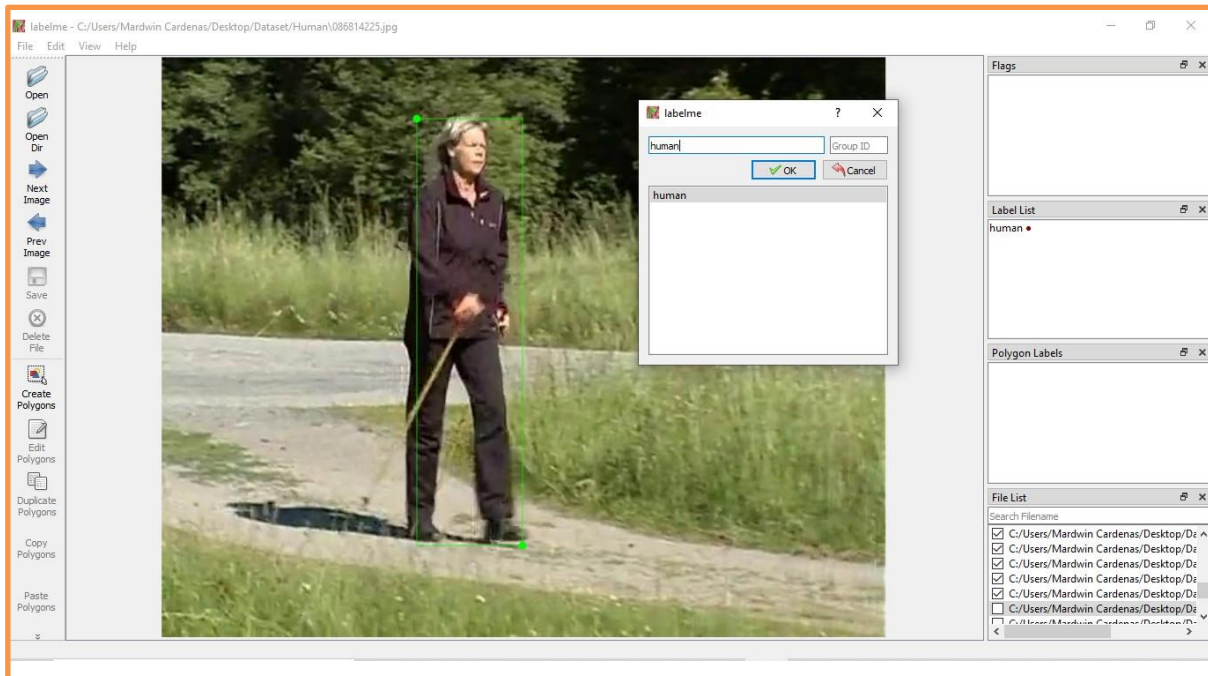


Figure 9: Image labeling

2 RoboFlow


Roboflow intends to make computer vision more accessible to the general public by simplifying and streamlining machine learning procedure. This application can allow us to focus on the real challenge instead of worrying of annotation formats, building scripts to process the raw photographs, or understanding how to code.

2.1 Create an Account

The screenshot shows the RoboFlow 'Login or Create an Account' page. It features a purple 'roboflow' logo at the top. Below the logo, the text 'Login or Create an Account' is displayed. The page prompts the user to 'Sign in with your work email'. There are three input fields: 'Work Email' with the value 'x20144237@student.ncirl.ie', 'First & last name' with the value 'Mardwin Cardenas', and 'Choose password' with a masked password '*****'. At the bottom, there are 'Cancel' and 'Save' buttons, and links for 'Terms of Service' and 'Privacy Policy'.

2.2 Create a Project

Welcome to Roboflow, let's get started.

 **Create a Project**
Upload images, preprocess, augment, and export

Create
⌚ 5 minutes

Create Project

Mardwin Cardenas / 🌐 New Public Project

Project Name

License

Project Type


Annotation Group ?


2.3 Upload


Upload

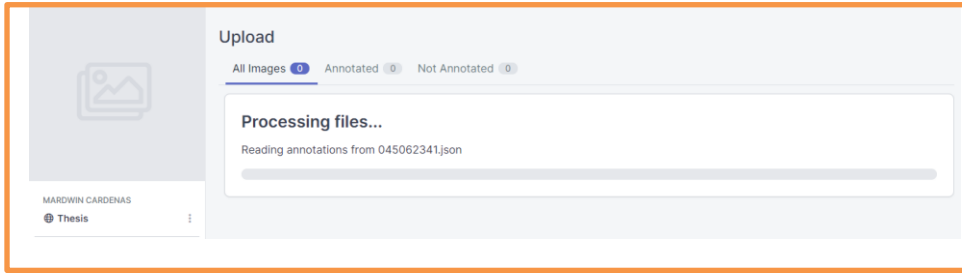
All Images 0 Annotated 0 Not Annotated 0

Now, drop your image and annotation files here, then continue the upload! (If you don't have your own data yet, try using our [sample dataset](#).)

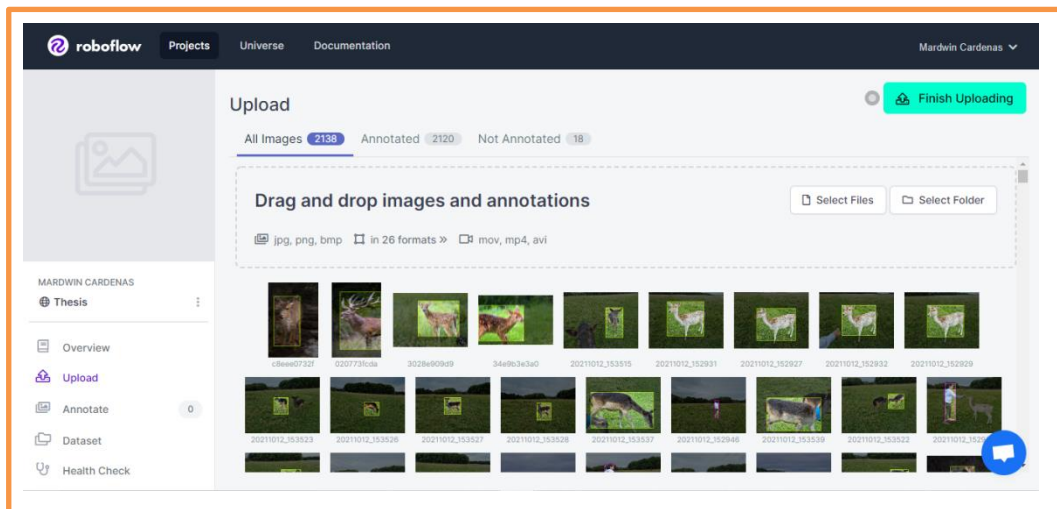
 **Images**
jpg, png, bmp

 **Annotations**
in 26 formats >>

 **Video**
mov, mp4, avi



2.4 Image Preprocessing



Source Images	Images: 2,136 Classes: 2 Unannotated: 0
Train/Test Split	Training Set: 1.5k images Validation Set: 427 images Testing Set: 214 images
Preprocessing	Auto-Orient: Applied Resize: Stretch to 416×416
Augmentation	90° Rotate: Clockwise, Counter-Clockwise Grayscale: Apply to 25% of images

3.2 Download Correctly Formatted Custom Dataset

Loading into this notebook our data

```
#follow the link below to get your download code from from Roboflow
!pip install roboflow

from roboflow import Roboflow
import torch
from IPyT

Requirement already satisfied: roboflow in /usr/local/lib/python3.7/dist-packages (0.2.0)
Requirement already satisfied: python-dotenv in /usr/local/lib/python3.7/dist-packages (from roboflow) (0.19.2)
Requirement already satisfied: python-dateutil in /usr/local/lib/python3.7/dist-packages (from roboflow) (2.8.2)
Requirement already satisfied: PyYAML>=5.3.1 in /usr/local/lib/python3.7/dist-packages (from roboflow) (6.0)
Requirement already satisfied: kiwisolver<=1.3.1 in /usr/local/lib/python3.7/dist-packages (from roboflow) (1.3.1)
Requirement already satisfied: chardet<=4.0.0 in /usr/local/lib/python3.7/dist-packages (from roboflow) (4.0.0)
Requirement already satisfied: idna<=2.10 in /usr/local/lib/python3.7/dist-packages (from roboflow) (2.10)
Requirement already satisfied: opencv-python<=4.1.2 in /usr/local/lib/python3.7/dist-packages (from roboflow) (4.1.2.30)
Requirement already satisfied: Pillow<=7.1.2 in /usr/local/lib/python3.7/dist-packages (from roboflow) (7.1.2)
Requirement already satisfied: six in /usr/local/lib/python3.7/dist-packages (from roboflow) (1.15.0)
Requirement already satisfied: tqdm<=4.41.0 in /usr/local/lib/python3.7/dist-packages (from roboflow) (4.62.3)
Requirement already satisfied: cycler<=0.10.0 in /usr/local/lib/python3.7/dist-packages (from roboflow) (0.10.0)
Requirement already satisfied: pyparsing<=2.4.7 in /usr/local/lib/python3.7/dist-packages (from roboflow) (2.4.7)
Requirement already satisfied: urllib3<=1.26.6 in /usr/local/lib/python3.7/dist-packages (from roboflow) (1.26.6)
Requirement already satisfied: matplotlib in /usr/local/lib/python3.7/dist-packages (from roboflow) (3.2.2)
Requirement already satisfied: numpy<=1.18.5 in /usr/local/lib/python3.7/dist-packages (from roboflow) (1.19.5)
Requirement already satisfied: certifi<=2021.5.30 in /usr/local/lib/python3.7/dist-packages (from roboflow) (2021.5.30)
Requirement already satisfied: requests in /usr/local/lib/python3.7/dist-packages (from roboflow) (2.26.0)
Requirement already satisfied: wget in /usr/local/lib/python3.7/dist-packages (from roboflow) (3.2)
Requirement already satisfied: charset-normalizer<=2.0.0 in /usr/local/lib/python3.7/dist-packages (from requests->roboflow) (2.0.8)
loading Roboflow workspace...
loading Roboflow project...
Downloading Dataset Version Zip in Thesis-try-3 to yolov5pytorch: 100% [147630036 / 147630036] bytes
Extracting Dataset Version Zip to Thesis-try-3 in yolov5pytorch:: 100% [██████████] 8878/8878 [00:10<00:00, 832.49it/s]
```

Figure 11:

3.3 Model Architecture

We can use the pre created yaml file because it specifies our model's characteristics, such as the number of classes, anchors, and layers.

```
# this is the YAML file Roboflow wrote for us that we're loading into this notebook with our data
!cat {dataset.location}/data.yaml

names:
- deer
- human
nc: 2
train: Thesis-try-3/train/images
val: Thesis-try-3/valid/images
```

Figure 12: Data Model Specifications

3.4 Train the Model

Based on the information we have. Yolov5s is now ready to train with our yaml files on hand. To start training, execute the training instruction with the following parameters:

Img:	416 x416
Size of the batch	16
Epoch	100
Data location	{dataset.location}/data.yaml
Cfg	./models/custom_yolov5s.yaml
Weights	''
Name	yolov5_result

And run the training command:

```
▶ # define number of classes based on YAML
import yaml
with open(dataset.location + "/data.yaml", 'r') as stream:
    num_classes = str(yaml.safe_load(stream)['nc'])
```

```
❶ #this is the model configuration we will use for our tutorial
%cat /content/yolov5/models/yolov5s.yaml

# parameters
nc: 80 # number of classes
depth_multiple: 0.33 # model depth multiple
width_multiple: 0.58 # layer channel multiple

# anchors
anchors:
  - [10,13, 16,30, 33,23] # P3/8
  - [30,61, 62,45, 59,110] # P4/16
  - [116,90, 156,198, 373,326] # P5/32

# YOLOv5 backbone
backbone:
  # [from, number, module, args]
  [[-1, 1, Focus, [64, 3]], # 0-P1/2
  [-1, 1, Conv, [128, 3, 2]], # 1-P2/4
  [-1, 3, CS, [128]],
  [-1, 1, Conv, [256, 3, 2]], # 3-P3/8
  [-1, 9, CS, [256]],
  [-1, 1, Conv, [512, 3, 2]], # 5-P4/16
  [-1, 9, CS, [512]],
  [-1, 1, Conv, [1024, 3, 2]], # 7-P5/32
  [-1, 1, SPP, [1024, [5, 9, 13]]],
  [-1, 3, CS, [1024, False]], # 9
  ]

# YOLOv5 head
head:
  [[-1, 1, Conv, [512, 1, 1]],
  [-1, 1, nn.Upsample, [None, 2, 'nearest']],
  [[-1, 6], 1, Concat, [1]], # cat backbone P4
  [-1, 3, CS, [512, False]], # 13

  [-1, 1, Conv, [256, 1, 1]],
  [-1, 1, nn.Upsample, [None, 2, 'nearest']],
  [[-1, 4], 1, Concat, [1]], # cat backbone P3
  [-1, 3, CS, [256, False]], # 17 (P3/8-small)

  [-1, 1, Conv, [256, 3, 2]],
  [[-1, 14], 1, Concat, [1]], # cat head P4
  [-1, 3, CS, [512, False]], # 20 (P4/16-medium)

  [-1, 1, Conv, [512, 3, 2]],
  [[-1, 18], 1, Concat, [1]], # cat head P5
  [-1, 3, CS, [1024, False]], # 23 (P5/32-large)

  [[17, 20, 23], 1, Detect, [nc, anchors]], # Detect(P3, P4, P5)
  ]
```

```
▶ #customize iPython |
from IPython.core.magic import register_line_cell_magic

@register_line_cell_magic
def writetemplate(line, cell):
    with open(line, 'w') as f:
        f.write(cell.format(**globals()))
```

```

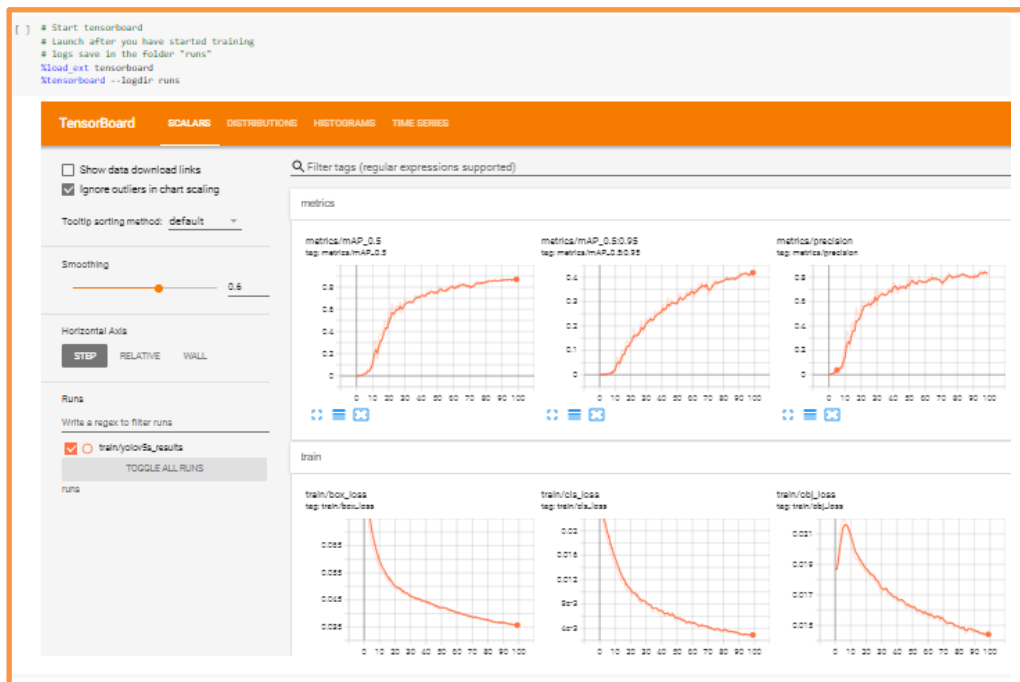
# Train yolo5v5 on custom data for 100 epochs
# Use its performance
train
run /root/.cache/yolo5/weights/yolo5v5.pt --img-size --batch-size --epochs 100 --data {dataset_location}/data.yaml --cfg {model_location}/yolo5v5.yaml --weights {weights} --name yolo5v5_results --cache

```

epoch	gpu_mem	loss	obj	cls	total	targets	img_size
01/99	1.80	0.0109	0.0107	0.000002	0.0109	0	512
02/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
03/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
04/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
05/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
06/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
07/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
08/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
09/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
10/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
11/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
12/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
13/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
14/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
15/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
16/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
17/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
18/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
19/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
20/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
21/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
22/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
23/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
24/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
25/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
26/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
27/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
28/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
29/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
30/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
31/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
32/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
33/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
34/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
35/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
36/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
37/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
38/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
39/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
40/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
41/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
42/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
43/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
44/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
45/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
46/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
47/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
48/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
49/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
50/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
51/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
52/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
53/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
54/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
55/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
56/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
57/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
58/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
59/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
60/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
61/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
62/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
63/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
64/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
65/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
66/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
67/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
68/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
69/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
70/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
71/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
72/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
73/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
74/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
75/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
76/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
77/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
78/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
79/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
80/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
81/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
82/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
83/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
84/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
85/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
86/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
87/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
88/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
89/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
90/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
91/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
92/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
93/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
94/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
95/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
96/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
97/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
98/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512
99/99	1.80	0.0109	0.0106	0.000002	0.0107	0	512

Optimizer stripped from run/train/yolo5v5_results/weights/last.pt, 11.7M
 Optimizer stripped from run/train/yolo5v5_results/weights/best.pt, 11.7M
 100 epochs completed in 3.016 hours.
 GPU times: user 3416.0s, sys: 18.0 s, total: 3434.0s
 wall time: 3.016 hours

3.5 Evaluate Custom YOLOv5 Detector Performance



3.6 Run Inference with Trained Weights

```
[ ] # trained weights are saved by default in our weights folder
%ls runs/

detect/ train/

[ ] %ls runs/train/yolov5s_results/weights

best.pt last.pt

[ ] # when we ran this, we saw .007 second inference time. That is 140 FPS on a TESLA P100!
# use the best weights!
%cd /content/yolov5/
!python detect.py --weights runs/train/yolov5s_results/weights/best.pt --img 416 --conf 0.4 --source /content/gdrive/MyDrive/deer

#display inference on ALL test images
import glob
from IPython.display import Image, display
for imageName in glob.glob('/content/yolov5/runs/detect/exp12/*.mp4'): #assuming JPG
    display(Image(filename=imageName))
    print("\n")
```

3.7 Export Trained Weights for Future Inference

```
from google.colab import drive
drive.mount('/content/gdrive')

Mounted at /content/gdrive
```

```
%cp /content/yolov5/weights/last_yolov5s_custom.pt /content/gdrive/My Drive
```

4 References

Ali, S. M. (n.d.). Comparative analysis of yolov3, yolov4 and yolov5 for sign language detection, p. 2021.

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EVOLUTION OF YOLO ALGORITHM AND YOLOV5: THE STATE-OF-THE-ART OBJECT DETECTION ALGORITHM (n.d.).

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