

# Configuration Manual

MSc Research Project MSc. in Data Analytics

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# Configuration Manual

### Subhashree Bera x20241062

### 1 Introduction

This report's objective is to provide a step-by-step guide for conducting the research. It includes details on the setting up of the hardware and software, as well as the preprocessing, model-building, implementation, and evaluation phases.

### 2 System Configuration

### 2.1 Hardware Configuration

#### Device specifications

#### HP Pavilion Laptop 13-bb0xxx

Device name	LAPTOP-RCHQ5D2D
	Subhashree-PC
Processor	11th Gen Intel(R) Core(TM) i7-1165G7 @ 2.80GHz 2.80 GHz
Installed RAM	16.0 GB (15.8 GB usable)
Device ID	B96116A2-79BC-49BE-A18E-2A96A1B63843
Product ID	00327-35932-23117-AAOEM
System type	64-bit operating system, x64-based processor
Pen and touch	No pen or touch input is available for this display

### 2.2 Software Specification

Operating System	Windows 10 Home Single Language
RAM	16 GB
Disk Space	200 GB
Programming Language	Python 3.8.8
Framework	Jupyter-Notebook
Libraries	Sklearn, OpenCV, plotly, Matplotlib, Keras, TensorFlow
Report	Overleaf, Ms. Word
Web Browser	Google Chrome

### 3 Dataset Description

The dataset is collected from Kaggle which is a open source repository. This dataset contains four types of rocks and they are igneous, metamorphic, sedimentary and minerals. The total images in the dataset is 5887 and the format is .jpg.

### 4 Installation and Importing Python Libraries

For the research task, the following python libraries are installed using pip command and imported:

```
import os
import shutil
import cv2
import numpy as np
import pandas as pd
import pickle
import matplotlib.pyplot as plt
import plotly.graph_objects as go
import tensorflow as tf
import tensorflow_addons as tfa
from tensorflow import keras
from tensorflow.keras import layers
```

### 5 Data Loading

The dataset have been loaded into the python jupyter notebook with the help of below code

#### **Data Preparataion**

```
data_dir_train = "Data/Training"
data_dir_val = "Data/Validation"
target_size = (128,128)
epochs = 50
```

#### Data Loading

```
def plot(data,grid,meta,classes=None):
    images = data[0]
    labels = data[1]
    plt.figure(figsize=(11,8))
    plt.title(meta)
    for i in range(len(images)):
        plt.subplot(grid[0],grid[1],i+1)
        plt.stticks([])
        plt.yticks([])
        plt.yticks([])
        plt.imshow(images[i])
        plt.imshow(images[i])
        plt.xlabel(classes[np.argmax(labels[i])],fontsize=8)
    plt.tight_layout()
```

## 6 Image Preprocessing

Below code have been used for image pre-processing:



## 7 Sample Train and Validation Data



## 8 VGG19 Design and Execution

Below code describes how the VGG19 is designed and executed.

#### VGG19

```
vgg_19 = tf.kenas.applications.vgg19.VGG19(include_top-False,weights=None,input_shape=(target_size[0],target_size[1],3))
model = tf.kenas.models.Sequential()
model.add(vf.kenas.layers.Flatten())
model.add(tf.kenas.layers.Dense(256, activation='relu'))
model.add(tf.kenas.layers.Dense(256, activation='relu'))
model.add(tf.kenas.layers.Dense(256, activation='relu'))
model.add(tf.kenas.layers.Dense(128, activation='relu'))
model.add(tf.kenas.layers.Dense(Dense(Dense), activatio
```

### 9 Custom Architecture Design and Execution

Below code describes how the custom architecture is designed and executed.

#### **Custom Architechtre**

```
model = tf.keras.models.Sequential()
model.add(tf.keras.layers.Conv2D(64, (3, 3), padding='same', input_shape=(target_size[0],target_size[1],3), activation='relu'))
model.add(tf.keras.layers.MaxPoolIng2D(pool_size-(2, 2)))
model.add(tf.keras.layers.Conv2D(128, (3, 3), padding='same',activation='relu'))
model.add(tf.keras.layers.NaxPoolIng2D(pool_size-(2, 2)))
model.add(tf.keras.layers.NaxPoolIng2D(pool_size-(2, 2)))
model.add(tf.keras.layers.NaxPoolIng2D(pool_size-(2, 2)))
model.add(tf.keras.layers.MaxPoolIng2D(pool_size-(2, 2)))
model.add(tf.keras.layers.NaxPoolIng2D(pool_size-(2, 2)))
model.add(tf.keras.layers.BatchNormalization())
model.add(tf.keras.layers.BatchNormalization())
model.add(tf.keras.layers.Flatten())
model.add(tf.keras.layers.Dense(256, activation='relu',input_dim=128))
model.add(tf.keras.layers.Dense(128, activation='relu'))
model.add(tf.keras.layers.Dense(128, activatio
```

### 10 Inception\_V3 Design and Execution

Below code describes how the Inception v3 is designed and executed.

#### Inception V3

<pre>inception = tf.keras.applications.inception_v3.InceptionV3(include_top=False, weights='imagenet',input_shape=(target_size[0],target_size[0])</pre>					
<pre>model = tf.keras.models.Sequential() model.add(inception) model.add(if.keras.layers.Flatten()) model.add(if.keras.layers.BatchNormalization()) model.add(if.keras.layers.Dense(256, activation='relu')) model.add(if.keras.layers.BatchNormalization()) model.add(if.keras.layers.Dense(218, activation='relu')) model.add(if.keras.layers.Dense(218, activation='relu')) model.add(if.keras.layers.BatchNormalization()) model.add(if.keras.layers.BatchNormalization()) model.add(if.keras.layers.Dense(218, activation='softmax'))</pre>					
model.layers[0].trainable=False					
4	•				
<pre>model.compile(optimizer="adam",loss="categorical_crossentropy",metrics=["accuracy",tf.keras.metrics.Precision(),tf.keras.metr {     history_inception = model.fit(train_data,batch_size=4,validation_data=val_data,epochs=epochs)</pre>	ics.				
<pre>Epoch 1/50 2360/2360 [</pre>	-				
2360/2360 [					
<pre>Lib():550 [===================================</pre>					
2360/2360 [					
2360/2360 [====================================					
2360/2360 [====================================	-				

# 11 Swin Transformer Class Definition, Design and Execution



Below code describes how the Swin Transformer architecture is designed and executed.

```
input = layers.Input(input_shape)
#x = Layers.RandomCrop(image_dimension, image_dimension)(input)
#x = layers.RandomFlip("horizontal")(x)
x = PatchExtract(patch_size)(input)
x = PatchEmbedding(num_patch_x * num_patch_y, embed_dim)(x)
x = SwinTransformer(
    dim=embed dim,
    num_patch=(num_patch_x, num_patch_y),
    num_heads=num_heads,
    window_size=window_size,
    shift size=0,
    num mlp=num mlp,
    qkv_bias=qkv_bias,
    dropout_rate=dropout_rate,
)(x)
x = SwinTransformer(
    dim=embed_dim,
    num_patch=(num_patch_x, num_patch_y),
    num_heads=num_heads,
    window_size=window_size,
    shift_size=shift_size,
    num_mlp=num_mlp,
    qkv_bias=qkv_bias
    dropout_rate=dropout_rate,
)(x)
x = PatchMerging((num_patch_x, num_patch_y), embed_dim=embed_dim)(x)
x = layers.GlobalAveragePooling1D()(x)
output = layers.Dense(num_classes, activation="softmax")(x)
```

```
model = keras.Model(input, output)
model.compile(
    loss=keras.losses.CategoricalCrossentropy(label_smoothing=label_smoothing),
   optimizer=tfa.optimizers.AdamW(
    learning_rate=learning_rate, weight_decay=weight_decay
   metrics=["accuracy",tf.keras.metrics.Precision(),tf.keras.metrics.Recall()],
history_swin = model.fit(
train_data,
batch_size=batch_size,
   epochs=epochs,
   validation_data=val_data,
3: 0.7258 - val_loss: 1.0024 - val_accuracy: 0.6943 - val_precision_3: 0.7785 - val_recall_3: 0.6063
_3: 0.7296 - val_loss: 1.0314 - val_accuracy: 0.7045 - val_precision_3: 0.7950 - val_recall_3: 0.6029
Enoch 48/50
cppcn 49/50
2360/2360 [===========] - 2195 93ms/step - loss: 0.7273 - accuracy: 0.8256 - precision_3: 0.9034 - recall
_3: 0.7237 - val_loss: 1.0068 - val_accuracy: 0.7182 - val_precision_3: 0.8133 - val_recall_3: 0.6473
Epoch 50/50
```

## 12 Models Comparison







