

# Configuration Manual

MSc Research Project MSc in Cloud Computing

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# Configuration Manual

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## 1 Introduction

Configuration manual is a document that provides all the details related to the downloading, installation, and setup details. In this configuration manual, the steps for installing the NS2 simulator, the detailed steps for downloading and installing the NSG (Network Scenario Generator) tool along with the xgraph tool are provided in detail. The manual is split into 3 sections in which section 1 provides information related to the downloading of the software and tools required for the project, Sections 2 deals with the installation of the tools and Section 3 provides the software setup related details and other implementation details. The project emphasizes on the network simulation using NS2 simulator in combination with NSG2 which is used as tool for building the scenarios related to the simulationIssariyakul and Hossain (2009). To test the setup, a virtual machine with Ubuntu OS is created in Oracle Virtual Boc for simulating the wireless network topology.

# 2 Downloading of Software and Tools

### 2.1 Oracle Virtual Box

The Oracle Virtual Box software is a hosted hypervisor that is installed and executed on the top of the host operating system. The Oracle Virtual Box is a open source software providing high performance and multiple features that are offered to users with a user-friendly graphical user interface Li (2010). It allows the users to create several guest operating system on a single physical machine. Oracle Virtual Box has been used in this project for creating a 64-bit virtual machine with Ubuntu guest operating using the below configuration:

RAM: 4GB vCPU: 1 Storage: 40GB<sup>1</sup>

<sup>&</sup>lt;sup>1</sup>https://www.virtualbox.org/



Figure 1: Oracle Virtual Box Configuration

## 2.2 Network Scenario Generator 2

The NSG2 is a software that can be used for building the simulation scenarios in a userfriendly environment. It was built by Pen-Jung Wu at the National University in Taiwan Huang and Shahnasser (2011). The network scenario generator has been used in our project in combination with the NS2 simulator to generate the wireless topology for testing the customized algorithm using SDN. Instead of manually writing the tcl code, the user can create the .tcl file in an automated manner using the NS2 network scenario generator. The highlighting characteristics of this tool are as follows:

1. The NSG2 is a tool that offers both the simplex and duplex network links for wired as well as wireless topology.

2. It supports different types of application-based traffic like the CBR (Constant Bit Rate, FTP (File transfer Protocol) and UDP (User Datagram protocol).

3. It also provides support for numerous routing protocols like DSR, AODV and DSDV and TORA.

4. It also enables the user to set the total duration of the simulation as per the requirements of the project and to save the generated simulation scenario in the form of a tcl file that can be used along with the ns command to run the simulation.

The NSG2 (Network Simulator 2) tool can be downloaded in the form of a.jar file from the below source:  $^{2}$ 

 $<sup>^{2}</sup> https://ns2 blogger.blogspot.com/2014/04/nsg-21-tcl-script-generator.html$ 



Figure 2: Network Scenario Generator for NS2

### 2.3 Network Simulator 2

NS2 is a simulator that makes use of events to perform the simulation of both wireless and wired networks. It also helps in the simulation of wireless routing protocols and network functions. The NS2 simulator offers users the ability to control and manage the behaviour of these routing algorithms in real-time. The NS2 simulator simulates the network protocols such as the UDP and TCP, traffic patterns like the Telnet, Constant Bit Rate (CBR), and routing protocols like Dynamic Source Routing and Ad-hoc Distance vector Routing. Due to its modular and flexible nature, NS2 has acquired worldwide popularity as a stable network simulator which can be extensively used in the networking and research fields. In our project, NS3 has been used for creating a wireless network topology to demonstrate the use of the SDN in combination of link weight routing algorithm. The network topology mainly comprises of the wireless sensor nodes in which the wireless sensor nodes generate the IoT traffic and pass the traffic to the SDN controller which receives the packet and sends the traffic to the destination node using the best available path. NAM is an animation tool that is used for viewing the NS2 simulation traces and events that are created with help of the Network Scenario Generator tool. The NAM window is activated upon the execution of the Tcl script. The url for downloading NS2 is given as a footnote.  $^3$ 

<sup>&</sup>lt;sup>3</sup>https://www.absingh.com/ns2

# 3 Installation of Software Tools and Packages

Once all the required tools and softwares are downloaded for our project, the next step involves installation of all the tools. The installation of the tools is performed as below:

- 1. Installation of NS2 Package
- 2. Installation of Network Scenario Generator
- 3. Installation of xgraph

#### 3.1 Installation of NS2 package

The below steps are used for installing the Network Simulator 2 on Ubuntu 64-bit operating system:

**Step1:** The prerequisite for installing the NS2 package is to update the Ubuntu repositories using the below command:

shantanu@shaan:~\$ sudo apt-get update
[sudo] password for shantanu:
Hit:1 http://ie.archive.ubuntu.com/ubuntu bionic InRelease
Get:2 http://ie.archive.ubuntu.com/ubuntu bionic-updates InRelease [88.7 kB]
Get:3 http://ie.archive.ubuntu.com/ubuntu bionic-backports InRelease [74.6 kB]
Get:4 http://security.ubuntu.com/ubuntu bionic-security InRelease [88.7 kB]
Get:5 http://ie.archive.ubuntu.com/ubuntu bionic-updates/main amd64 Packages [1
,022 kB]
Get:6 http://ie.archive.ubuntu.com/ubuntu bionic-updates/main i386 Packages [71
9 kB]
Get:7 http://ie.archive.ubuntu.com/ubuntu bionic-updates/main amd64 DEP-11 Meta
data [295 kB]
Get:8 http://ie.archive.ubuntu.com/ubuntu bionic-updates/universe i386 Packages
[1,026 kB]

Figure 3: Updating the Ubuntu Operating system

Step2: The Network Simulator 2 package can be installed using the below command.



Figure 4: NS2 Package Installation

**Step3:** Once NS2 is installed, the NAM package is installed for graphically representing the network simulation traces.



Figure 5: Network Animator Installation

# 3.2 Network Scenario Generator Execution

After installing OpenJDK, the Network Scenario Generator is executed as a jar file. The NSG2 jar file can be executed using the below command

· · · · ·	haan:~\$ cd Demo/ haan:~/Demo\$ ls			
delay.awk		NSG2.1.jar	pdf.awk	wireless1.nam
•	EfficientTrafficMgmt.tcl		PDR.tr	wireless1.tcl
	genthroughput.awk	out.tr	Throughput.tr	wireless1.tr
shantanu@s	haan:~/Demo\$ java -jar NSG	2.1.jar		
shantanu@s	haan:~/Demo\$			

Figure 6: Network Scenario Generator Execution



Figure 7: Network Scenario Generator Main Window

## 3.3 Wireless Topology Setup

In order to create a wireless topology, the "New wireless scenario" option is selected. On clicking new wireless scenario, a window is opened with all the options for creating wireless topology.

			indow <u>A</u> bou	ıt		 		
		cenario					⊏ ⊠	$\ge$
<u>File D</u>								
Hand	Node	Agent	Application	Parameters	TCL			
Single		-						
Locatio	1 . ( 22	3 26)	Trans	mission rang	eInterfer	Set Zoom -		

Figure 8: Network Scenario Generator Wireless Scenario

The wireless scenario can be generated by creating the wireless sensor nodes by clicking on the option called as "Node". The nodes will be numbered as n0, n1...so on.



Figure 9: NSG2 Topology creation

Next, a TCP agent and a TCP Sink agent is attached to the source node and the Sink node so as to establish a TCP connection between the wireless node(n0) and the Sink node(n3).



Figure 10: TCP agent and Sink Agent

For transferring the data through the TCP connection a cbr or ftp agent is attached to the TCP agent.

In the next step, the simulation time can be defined by entering the Start Time as 1sec and Stop time as 15sec.



Figure 11: FTP agent attach to the TCP agent



Figure 12: Simulation Time

Lastly, the simulation parameters like the total simulation time, name of the trace file and name of the Nam output file are defined.



Figure 13: Simulation Setup

Before saving the simulation, wireless routing protocol like AODV, DSDV and DSR can be set by clicking on a tab named wireless.

Simulation pa	rameters setup	<u>e</u>
Simulation Wireless Channel		
Channel type	Channel/WirelessChannel	-
Propagation model	Propagation/TwoRayGround	-
Phy type	Phy/WirelessPhy	-
Mac protocol type	Mac/802_11	-
Queue type	Queue/DropTail/PriQueue	-
Link layer type	LL	-
Antenna type	Antenna/OmniAntenna	-
Max packet in queue	50	
Routing protocol	DSDV	-
Agent trace	ON	-
Router trace	ON	-
Mactrace	ON	-
Movement trace	ON	-
Done S	ave as default	

Figure 14: Simulation Parameters

In the final step, the simulation is saved in the form of a .tcl file which can be used with the ns command to display the simulation workflow.

<u>System Scenario W</u> indow	About			
💾 WiredTcl		r 🖂 🛛		් වේ 🗵
Save Save as				
set ftp0 [new Application/FTP	1	<b>A L</b>		
\$ftp0 attach-agent \$tcp0		le 12		
\$ns at 1.0 "\$ftp0 start" \$ns at 12.0 "\$ftp0 stop"				
#======================================		52)	Please select file	
# Termination			r tebbe settete filte	
#=====================================	Save In: 📑 sh	antanu		- R A C 88 E
proc finish { } {			nsg	Dadd.tcl
global ns tracefile namfile \$ns flush-trace	Desktop		Pictures	Delay.t
close \$tracefile	Documents		Project	
close \$namfile exec nam wireless1.nam &	Downloads		Public	🗋 out.nar
exit 0	📑 Music		📑 Templates	D PDR.tr
<pre>} for {set i 0 } {\$i &lt; \$val(nn) }</pre>	📑 netsim_full		📑 Videos	D perform
\$ns at \$val(stop) "\\$n\$i res	•	III		▶
} \$ns at \$val(stop) "\$ns nam-e	File Name:	Demo.tcl		
\$ns at \$val(stop) "finish"	_			
\$ns at \$val(stop) "puts \"don \$ns run	Thes of Type.	Annes		
••••				Save Cancel

Figure 15: TCL Scripting

After saving the simulation as a TCL file, the tcl file can be executed for running the simulation scenarios. For running the simulation, ns command is used followed by the name of the tcl file. The name of the tcl file used in the project is wireless1.tcl. When the tcl file is executed, it calculates the number of nodes that are part of the topology design and generates the corresponding number of wireless nodes as per the topology setup and also labels the nodes and performs the initialization of the tcp, udp or cbr traffic. The simulator runs the simulation as per the time defined in the NSG2 wireless scenario.

shantanu@shaan:~/Demo\$ ns wireless1.tcl
When configured, ns found the right version of tclsh in /usr/bin/tclsh8.6
but it doesn't seem to be there anymore, so ns will fall back on running the fi
rst tclsh in your path. The wrong version of tclsh may break the test suites. R
econfigure and rebuild ns if this is a problem.
num_nodes is set 15
INITIALIZE THE LIST xListHead
channel.cc:sendUp - Calc highestAntennaZ_ and distCST_
highestAntennaZ_ = 1.5, distCST_ = 550.0
SORTING LISTSDONE!
shantanu@shaan:~/Demo\$

Figure 16: NS2 TCL script Execution

When the TCL script is executed, it transfers the call to a .nam file and displays the simulation output. As seen in the below figure, the topology consists of wireless nodes.

				na	m: wireless	s1.nam			• • •
<u>F</u> ile	<u>V</u> iews	<u>A</u> nalysis				wireles	s1.nam		
	44		◄		<b></b>		**	0.000000	Step: 2.0ms
4									
			•	O		6	6		
			-					ø	
			۲	٩	O	•	ø	_	
								G	
			~	0	_		Ø	U	
			9		6		0		

Figure 17: NS2 NAM Output

# 4 Plotting Simulation Traces on XGraph

For evaluation of results, a tool known as xgraph is used which helps to plot the information related to different performance like Throughput, response time and average end-to-end delay in a graphical format. xgraph can downloaded in the form of a tar ball using the below link:





In order to use xgraph, the contents of the tar gzip file are extracted. For extracting the contents of the gzip tar file, -xvf option is used in the tar command where x stands for extract, v stands for verbose and f stands for the name of the tar file. Xgraph is a tool that is used to present the graphical output of the simulation scenarios. Xgraph plots the graph using a X11 window by capturing the data from either the simulation trace files or through the standard input. It annotates the graphical display with axis labels, tables and tick marks or grid lines legend and grid labels Patel et al. (2019). There are several alternatives to regulate the appearance of the components of the Xgraph. The graphical interface used to indicate the size and location and volume of the window is dependent on the window manager which is being used. As soon as the X window is opened, all the points in the data set or the simulation trace file are graphically displayed

```
shantanu@shaan:~$ tar -xvf xgraph_4.38_linux64.tar.gz
XGraph4.38_linux64/
XGraph4.38_linux64/data/
XGraph4.38_linux64/data/pptxdata.scz
XGraph4.38_linux64/data/pptx/
XGraph4.38_linux64/data/pptx/
XGraph4.38_linux64/data/pptx/trels
XGraph4.38_linux64/data/pptx/thumbnail.jpeg
XGraph4.38_linux64/data/oofficedata.scz
XGraph4.38_linux64/bin/
XGraph4.38_linux64/bin/
XGraph4.38_linux64/bin/xgraph
XGraph4.38_linux64/testxy.dat
shantanu@shaan:~$
```

Figure 19: Xgraph

along with a legend. The trace file generated after the completion of the simulation is used as an input to the xgraph command for generating the graphical representation of the simulation events.  $^4$ 

shantanu@shaan:~/Demo\$ xgraph Delay.tr
XGraph v4.38
Gtk-Message: 11:42:36.742: Failed to load module "canberra-gtk-module"
Window (440 x 465)
50 points read.
WindowSize = (500, 465)
WindowSize = (500, 432)
WindowSize = (500, 401)

Figure 20: Xgraph-Command

 $<sup>^{4} \</sup>rm https://www.xgraph.org/linux/index.html$ 

Cased	100000		XGRAPH			• • •
File Edit	View	Options	Help		XGrap	oh (Vers 4.38)
Zoom: +Z In -z Ou	E	0.12				
Pan:		0.19		_		
$\leftarrow$ $\rightarrow$		0.08	_	_		
Display:		0.05		_		
🗹 Lines 🗹 Text		0.04		_		
History:		0.02				
Reset		0	5	10	15	20 25
Quit						

The output of the xgraph command is as follows:

Figure 21: XGraph Sample Output

# 5 Implementation

The .tcl file built for creating the wireless topology is used along with the ns command to run the simulation. The TCL script consists of 28 wireless nodes that communicate with each other using the wireless links. The wireless nodes communicate with each other by exchanging the ftp and cbr traffic over a TCP connection.

## 5.1 Code for Simulator Object Declaration:

#define options						
set val(chan)	Channel/Wireles					
set val(prop)		RayGround	;# radio-propagation model			
set val(netif)			;# network interface type			
set val(mac)	Mac/802_11		;# MAC type			
set val(ifq)	Queue/DropTail/R	PriQueue	;# interface queue type			
set val(ll)	LL		;# link layer type			
set val(ant)	Antenna/OmniAnte	enna	;# antenna model			
set val(ifqlen)	100		;# max packet in ifq			
set val(nn)	29		;# number of mobilenodes			
set val(rp)	AODV		;# routing protocol			
set val(x)	1000		;# X dimension of topography			
set val(y)	1000		;# Y dimension of topography			
set val(stop)	25					
set val(energymodel)	) EnergyModel	;# Ene	rgy Model			
set val(initialener	y) 100	;# val	ue			
Mac/802_11 set CTSThreshold_ 2000						
Mac/802_11 set RTSThreshold 4000						

Figure 22: Code for Simulator object Declaration

### 5.2 TCL Code for Node Generation:

The wireless topology in our project consists of 28 wireless nodes attached with RFID tags. The experiment is carried out by performing 5 iterations and varying the count of nodes in each of the iterations. The position for the wireless nodes is set by defining the position relative to the X, Y axis. These values are set by using the Network Scenario Generator whereby the user drags the node to a particular position and the scenario generator sets the position of the wireless node in the respective tcl file.

for {set i 0 set node_(\$i }	} {\$i < \$val(nn) } { incr i } { ) [\$ns node]
<pre>\$node_(0) se \$node_(0) se \$node_(0) se</pre>	t Y_ 192
<pre>\$node_(1) se \$node_(1) se \$node_(1) se</pre>	t Y_ 272
<pre>\$node_(2) se \$node_(2) se \$node_(2) se</pre>	t Y_ 213
<pre>\$node_(3) se \$node_(3) se \$node_(3) se</pre>	t Y_ 113
<pre>\$node_(4) se \$node_(4) se \$node_(4) se</pre>	t Y_ 248
\$node_(5) se \$node_(5) se	

Figure 23: TCL for Node generation

### 5.3 Code for Link Weight Routing Algorithm



Figure 24: Code for Link Weight Routing Algorithm

# 6 Scripts for Recording the Performance Statistics

The performance of the NS2 simulation is recorded by making the use of a performance script. The scripting language for capturing the performance statistics is known as the awk script. The awk is a language that is used for recording the below performance parameters:

- Packet Delivery Ratio
- Average end-to-end Delay
- Throughput

### 6.1 Packet Delivery Ratio

The packet delivery ratio is the count of packets that were successfully received to the count of the packets that were sent. The packet delivery ratio is measured in the form of percentage. The results are captured by varying the number of nodes used in the topology for the existing as well as the proposed algorithm. The awk script used for measuring the packet delivery ratio is as follows:



Figure 25: AWK script for Packet Delivery Ratio

## 6.2 Average End-to-End Delay

The average end-to-end delay is the additional amount of time taken by a packet to reach the destination after leaving the source node. It is computed as the difference between the time taken by the packet and the expected time to reach the destination. The average end-to-end delay is computed by using an awk script. The delay is captured based on the count of the number used in the topology. The awk script used for analysing the end-to-end is as follows:

```
for(i=0; i<=seqno; i++) {
    if(end_time[i] > 0) {
        delay[i] = end_time[i] - start_time[i];
        count++;
    }
    else
    {
        delay[i] = -1;
    }
    for(i=0; i<=seqno; i++) {
        if(delay[i] > 0) {
            n_to_n_delay = n_to_n_delay + delay[i];
        }
    }
    n_to_n_delay = n_to_n_delay/count;
    print "\n";
    # print "GeneratedPackets = " seqno+1;
    # print "GeneratedPackets = " receivedPackets;
    # print "Packet Delivery Ratio = "
    receivedPackets/(seqno+1)*100
    #"%";
    # print "Total Dropped Packets = " droppedPackets;
    print "Average End-to-End Delay = " n_to_n_delay * 1000 ", ms";
    print "\n";
    shantanu@shaan:~/Demo$
```

Figure 26: AWK script for Average End-to-End Delay

#### 6.3 Throughput

The throughput of a network is measured by the rate at which the packets were transferred from the source to the destination node. Whenever there is congestion in the network, it results in packet loss and network congestion. The delay time can be calculated with use of an awk script. The awk script used for analysing the throughput is as follows:



Figure 27: AWK script for Throughput

## References

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