

Configuration Manual

MSc Research Project
MSc Data Analytics

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MSc Project Submission Sheet
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Configuration Manual

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1 Introduction

The following configuration manual illustrates the requirements for implementing the system which was designed for detecting the distraction of drivers by using the Deep Learning models. Further, the manual will thoroughly explain the software and hardware requirements that were used for the successful implementation of the project.

2 System Configuration

Following are the hardware and software configuration which were used for the implementation of this Project.

The hardware configurations used for implementation are as follows:

2.1 Hardware Requirements:

Table 1 Hardware Requirements

| Hardware | Configurations |
|------------------|--------------------------|
| System | Lenovo Legion Y740 |
| Operating System | Windows 10 (64bit) |
| RAM | 16 GB |
| Hard Disk | 1 TB (Solid State Drive) |
| Graphics Card | NVIDIA RTX 2060 (6 GB) |
| Processor | Intel Core I7-9750 |

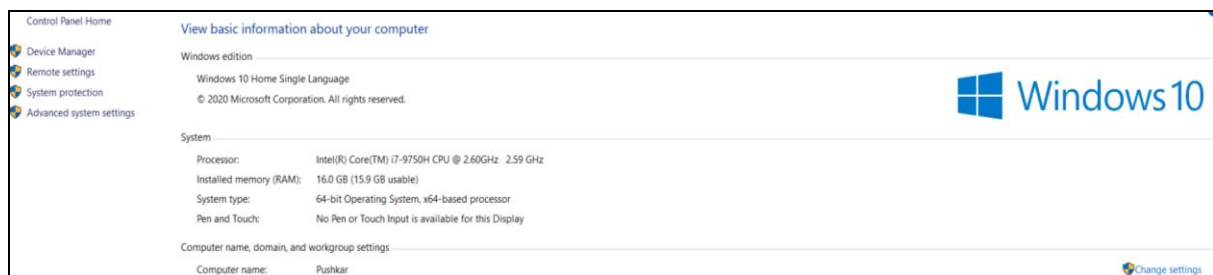


Figure 1 Operating System Configurations

The operating system used for this project was Windows 10 which was 64bit based.

```

:~\Users\Pushkar>nvidia-smi
Sun Aug 16 23:50:28 2020

+-----+
| NVIDIA-SMI 436.50      | Driver Version: 436.50      | CUDA Version: 10.1      |
+-----+-----+
| GPU  Name            | TCC/WDDM | Bus-Id  | Disp.A | Volatile Uncorr. ECC |
| Fan  Temp  Perf  Pwr:Usage/Cap|      Memory-Usage | GPU-Util  Compute M. |
+-----+-----+-----+
|   0  GeForce RTX 2060  | WDDM     | 00000000:01:00.0 Off |          N/A         |
| N/A   47C    P8      3W /  N/A | 164MiB /  6144MiB |      0%    Default   |
+-----+-----+-----+

Processes:
GPU      PID  Type  Process name
=====
No running processes found

```

Figure 2 CUDA Version

The CUDA version used was 10.1.

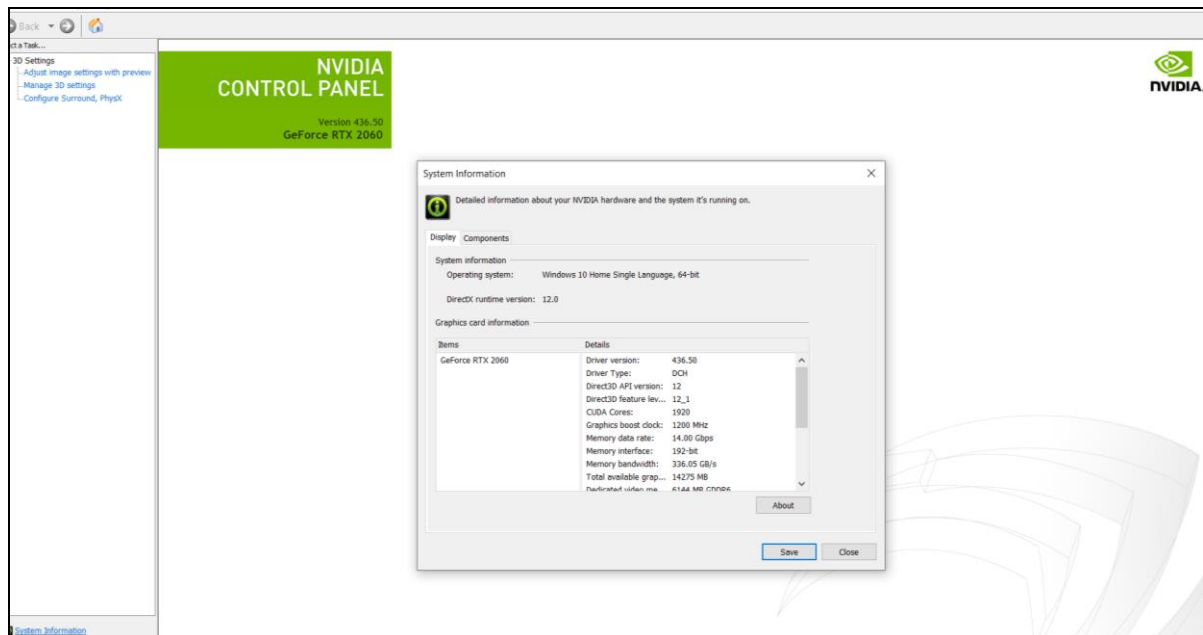


Figure 3 NVIDIA Driver Information

The GPU used for implementing the high-end deep learning models was Nvidia RTX 2060 with a size of 6GB.

2.2 Software Requirements

The software's used were as follows:

Table 2 Software Requirements

| Software | Version |
|-------------------|-----------------|
| Python | 3.7 (64 bit) |
| PyCharm Community | 2020.2 (64 bit) |
| Microsoft Excel | 2020 Edition |

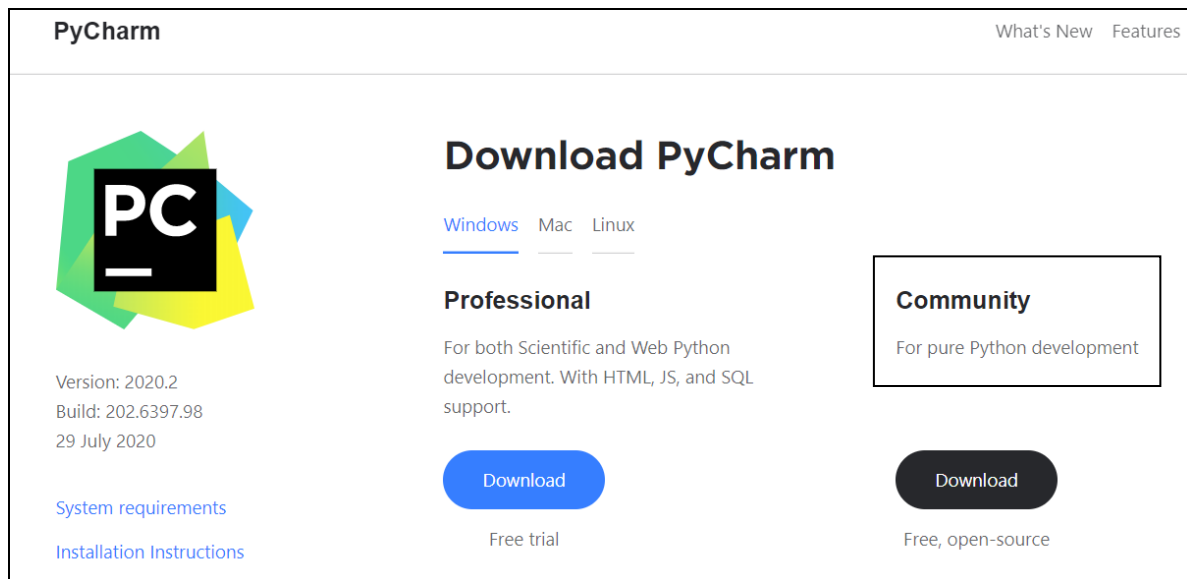


Figure 4 Downloading PyCharm

PyCharm can be downloaded from <https://www.jetbrains.com/>. There are two versions available namely Professional and Community. We will be using the Community. The IDE used for implementing the whole project was PyCharm. The Community version was used which is pure python-based development. The latest version 2020.2 was used. The steps involved in installing the software will be discussed further.

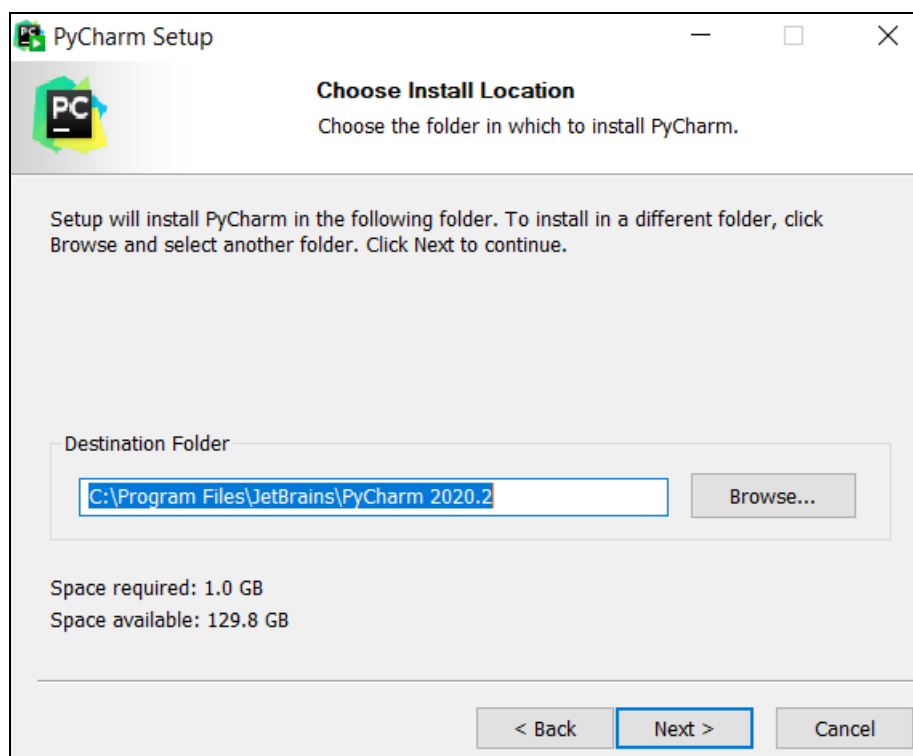


Figure 5 Installation folder for PyCharm

Choose the destination folder where you want to install the software and make sure you have enough space i.e. 1.0 GB required by the software.

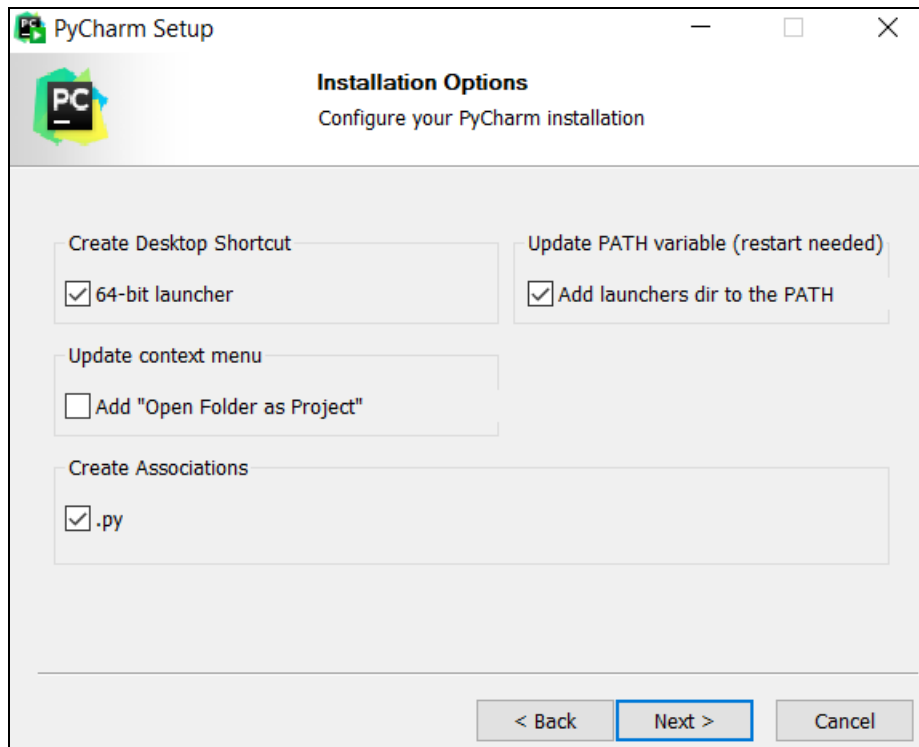


Figure 6 Installing Options

Choose the 64-bit launcher and also create associations with .py files. In addition to this, tick the Update PATH variable which will further add the launcher directory to the PATH.

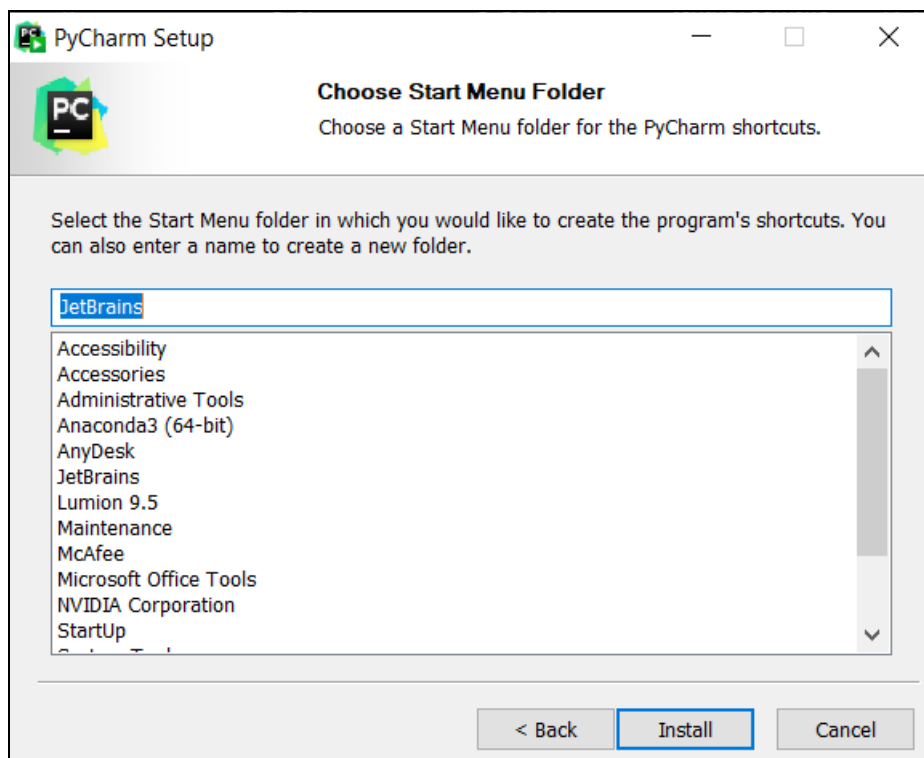


Figure 7 Choosing Start Menu Folder

Choose the folder for Start Menu

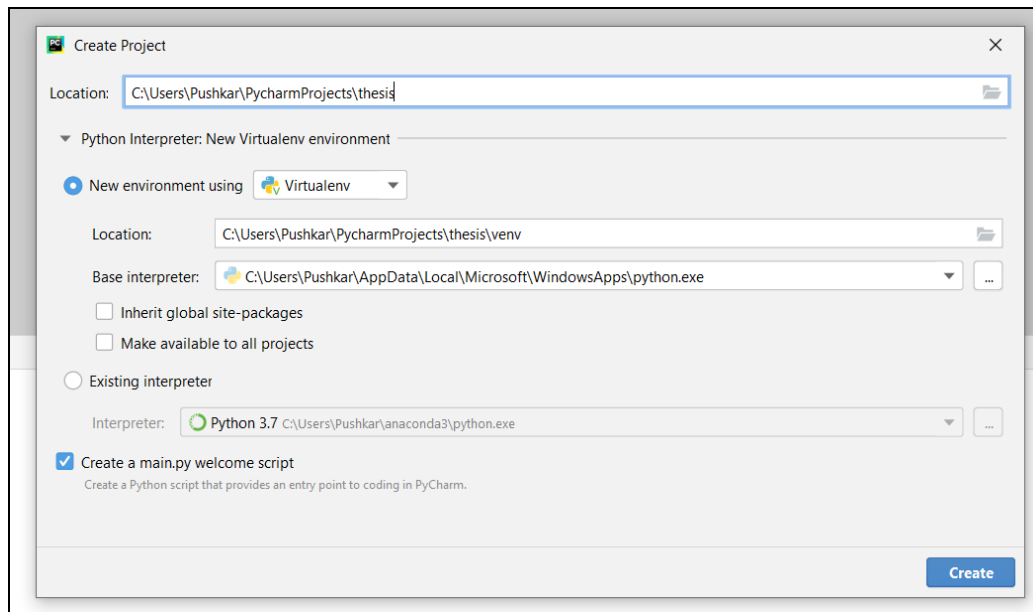


Figure 8 Project creation

The project will be created in this step where the environment will be created for the further implementation of the project. All the required libraries by the project will be stored in this environment.



Figure 9 CUDA 10.1

The GPU needs to have a CUDA installed on the system, thus the CUDA with version 10.1 was installed from the official website of NVIDIA developers¹. Further, the cuDNN version 7.6.5 was all installed which is compatible with the CUDA 10.1². Later the CUDA, cuDNN was configured with the windows along with TensorFlow³.

¹ <https://developer.nvidia.com/cuda-downloads>

² <https://developer.nvidia.com/rdp/cudnn-archive#a-collapse765-101>

³ <https://towardsdatascience.com/installing-tensorflow-with-cuda-cudnn-and-gpu-support-on-windows-10-60693e46e78>

3 Project Implementation

3.1 Data Collection

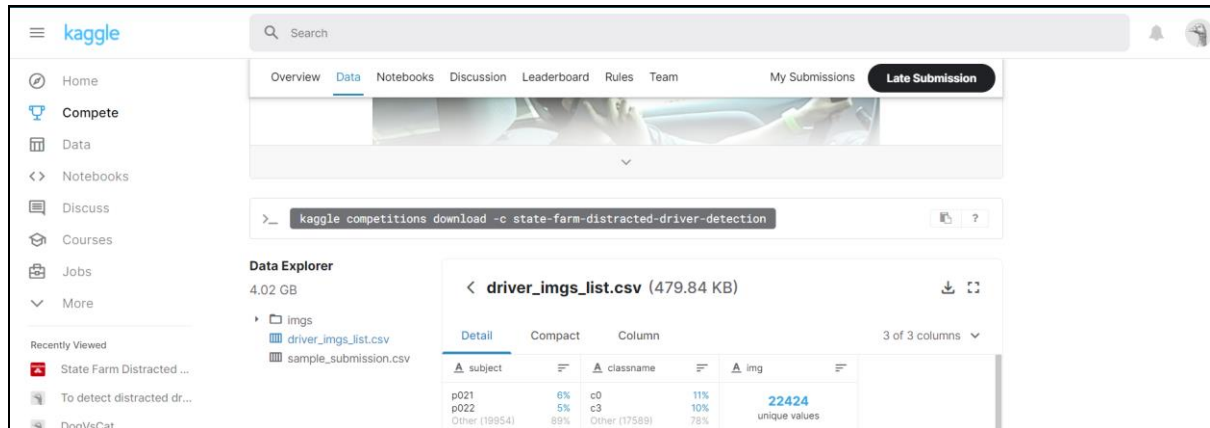


Figure 10 Website for data collection

The data which was used for the implementation was picked from Kaggle. The dataset was named as State Farm Distracted Driver Detection which was available under Kaggle competition.

3.2 Data Preparation

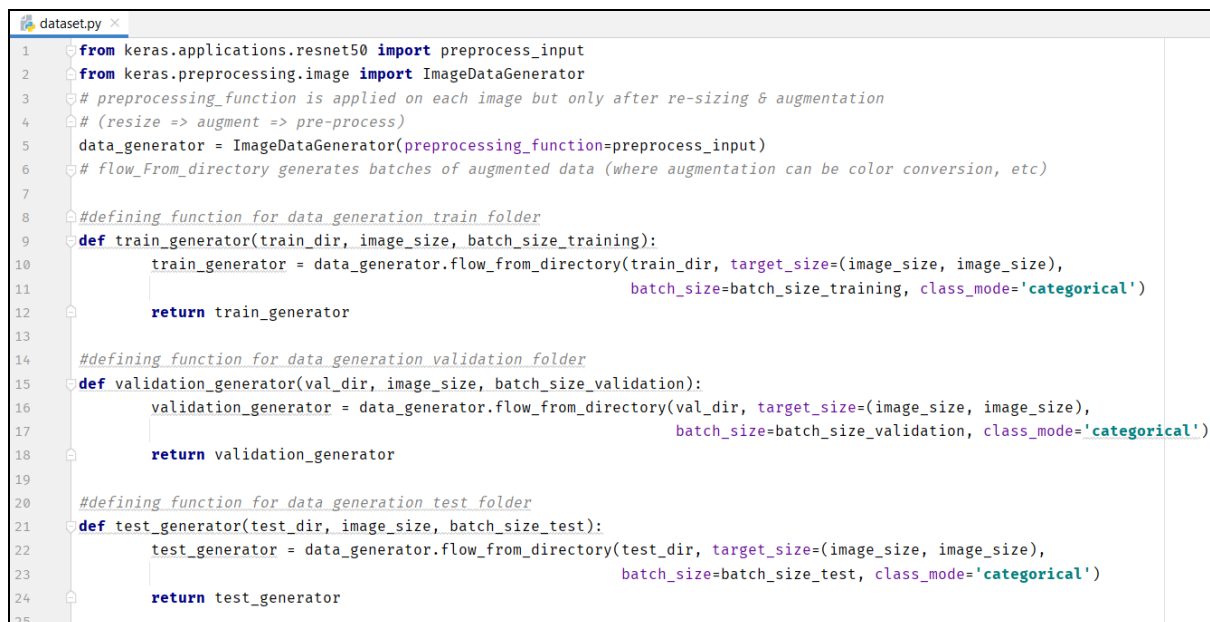


Figure 11 Data Preparation

The data preparation process where the data generators were created in the dataset.py file. The train, test, and validation generators for respective folders were called.

3.3 Data Pre-Processing

```
1 import os
2 import glob, shutil
3 #creating directories for binary classification
4 safe_path = "C:/Users/Pushkar/Desktop/imgs/train/safe-driving"
5 distracted_path = "C:/Users/Pushkar/Desktop/imgs/train/distracted-driving"
6 os.mkdir(safe_path)
7 print("Safe Driving Directory Created Successfully")
8 os.mkdir(distracted_path)
9 print("Distracted Driving Directory Created Successfully")
10 preprocessing_path = "C:/Users/Pushkar/Desktop/imgs/after-preprocessing"
11 os.mkdir(preprocessing_path)
12 logfile_path = "C:/Users/Pushkar/Desktop/imgs/logs"
13 os.mkdir(logfile_path)
14 aug_path = "C:/Users/Pushkar/Desktop/imgs/aug_safe_driving"
15 os.mkdir(aug_path)
16 print("aug_safe_driving Folder Created Successfully")
17 aug_path = "C:/Users/Pushkar/Desktop/imgs/saved_weights"
18 os.mkdir(aug_path)
19 print("saved_weights Folder Created Successfully")
20 print("#####")
21 #moving the images from the different class folder c0-c9 to safe-driving and distracted-driving folder.
22 for file in glob.glob('C:/Users/Pushkar/Desktop/imgs/train/c0/img*'):
23     shutil.move(file, safe_path)
24 print("c0 Files moved successfully")
25 for file in glob.glob('C:/Users/Pushkar/Desktop/imgs/train/c1/img*'):
26     shutil.move(file, distracted_path)
27 print("c1 Files moved successfully")
28 for file in glob.glob('C:/Users/Pushkar/Desktop/imgs/train/c2/img*'):
29     shutil.move(file, distracted_path)
30 print("c2 Files moved successfully")
```

Figure 12 Folder Structuring

The folders structuring was done in this file named folder_automation.py where the 10 data folders ranging from c0 to c9 were transformed into two folders namely safe-driving and distracted-driving.

```
1 import cv2 as cv
2 import glob
3 import imageio
4 import os
5 from imgaug import augmenters as iaa
6 # get images
7 images = []
8 files = glob.glob("C:/Users/Pushkar/Desktop/imgs/train/safe-driving/*.jpg")
9
10 # stacking images
11 for myFile in files:
12     image = cv.imread(myFile)
13     image_rgb = cv.cvtColor(image, cv.COLOR_BGR2RGB) # change from BRG to RGB
14     images.append(image_rgb)
15
16 sometimes = lambda aug: iaa.Sometimes(0.5, aug)
17
18 # defining sequence of augmentation steps that will be applied to every image.
19 seq = iaa.Sequential(
20     [
21         #
22         # Apply the following augmenters to images.
23         iaa.Fliplr(0.4), # horizontally flip 40% of all images
24         iaa.Flipud(0.1), # vertically flip 10% of all images
25         # Apply affine transformations to some of the images
26         sometimes(iaa.Affine(
27             rotate=(-10, 10),
28         )),
29     ],
30 )
```

Figure 13 Image Augmentation (a)

In this step, the `img_aug.py` file was created where the image augmentation was done particularly on a safe driving folder in order to balance the data.

```
# Blur each image with varying strength using
# gaussian blur (sigma between 0 and 3.0),
# average/uniform blur (kernel size between 2x2 and 7x7)
# median blur (kernel size between 3x3 and 11x11).
iaa.OneOf([
    iaa.GaussianBlur((0, 3.0)),
    iaa.AverageBlur(k=(2, 7)),
    iaa.MedianBlur(k=(3, 11)),
]),
random_order=True
)
# specify directory to save your images
write_to_dir = "C:/Users/Pushkar/Desktop/imgs/aug_safe_driving"
# number of augmented images per image
n_augs_per_image = 10
for i, image in enumerate(images):
    image_augs = seq.augment_images([image] * n_augs_per_image)
    for j, image_aug in enumerate(image_augs):
        imageio.imwrite(os.path.join(write_to_dir, "%03d_%02d.jpg" % (i, j)), image_aug)
```

Figure 14 Image Augmentation (b)

The various techniques are used in the code above namely horizontal flip, vertical flip, colour augmentation, and affine transformation.

```
pre_processing.py x
1 import glob
2 import os
3 from random import choice
4 import shutil
5 #Moving images from aug_safe_driving to safe-driving
6 safe_path = "C:/Users/Pushkar/Desktop/imgs/train/safe-driving"
7 for file in glob.glob('C:/Users/Pushkar/Desktop/imgs/aug_safe_driving/*'):
8     shutil.move(file, safe_path)
9
10 # setting up directory names
11 trainPath = 'C:/Users/Pushkar/Desktop/imgs/after-preprocessing/train'
12 valPath = 'C:/Users/Pushkar/Desktop/imgs/after-preprocessing/val'
13 testPath = 'C:/Users/Pushkar/Desktop/imgs/after-preprocessing/test'
14 #directory where the images are stored
15 crsPath = 'C:/Users/Pushkar/Desktop/imgs/train'
16
17 # splitup ratio into 70:15:15
18 train_ratio = 0.7
19 val_ratio = 0.15
20 test_ratio = 0.15
21
22 # To get number of classes
23 num_classes = len(list(os.walk(crsPath))[0][1])
24
25 files_count = {}
26 # To keep track of classes, count and dir
27 for i in range(num_classes):
28     fc = 0
29     files = list(os.walk(crsPath))[0][0] + "/" + list(os.walk(crsPath))[0][1][i]
30     dataset_name = os.path.split(files)[-1]
```

Figure 15 Pre-processing (a)

```

# cycle for Test directory
for k, v in files_count.items():
    imgs = []
    for img in glob.glob(v[1] + "/" + "*.jpg"):
        img = os.path.split(img)[-1]
        imgs.append(img)

    for x in range(countForTest):
        fileJpg = choice(imgs) # get name of random image from origin directory
        z = os.path.join(crsPath, k, fileJpg)
        if not os.path.exists(os.path.join(testPath, k)):
            os.makedirs(os.path.join(testPath, k))
        try:
            # move both files into test directory
            shutil.move(os.path.join(crsPath, k, fileJpg), os.path.join(testPath, k, fileJpg))

        except Exception as e:
            print(e)
        # remove files from arrays
        imgs.remove(fileJpg)

for dir in glob.glob("C:/Users/Pushkar/Desktop/imgs/aug_safe_driving"):
    os.rmdir(dir)

for dir in glob.glob("C:/Users/Pushkar/Desktop/imgs/train"):
    shutil.rmtree(dir)

```

Figure 16 Pre-processing (b)

The data was split into the ratio of 70:15:15 for the created for the train, validation, and test folder. The data balancing was done in this file named pre_processing.py.

3.4 Model Building

The snippets in this section will be all about the different models that were used for implementing the driver distraction detection system

```

import argparse

def parse_arguments(*args):
    parser = argparse.ArgumentParser()

    parser.add_argument('-model_type', '--model_type', default='mycnn', type=str, choices=['vgg19', 'mycnn', 'thinmobilenet', 'xception'],
                        help='vgg19|mycnn|thinmobilenet|xception')

    ##### Dataset options #####

    parser.add_argument('-tr_dir', '--train_dir', default='C:/Users/Pushkar/Desktop/imgs/after-preprocessing/train', type=str,
                        help='Path to the train directory')

    parser.add_argument('-vl_dir', '--val_dir', default='C:/Users/Pushkar/Desktop/imgs/after-preprocessing/val', type=str,
                        help='Path to the val directory')

    parser.add_argument('-tst_dir', '--test_dir', default='C:/Users/Pushkar/Desktop/imgs/after-preprocessing/test', type=str,
                        help='Path to the test directory')

    parser.add_argument('-cls', '--num_classes', default=2, type=int,
                        help='Number of dataset classes')

    parser.add_argument('-res', '--image_resize', default=224, type=int,
                        help='Image Resize value')

    ##### Model options #####

    parser.add_argument('-lr', '--learning_rate', default=1e-5, type=float,
                        help='Learning rate for the generator')

    parser.add_argument('-of', '--objective_function', default='binary_crossentropy', type=str,

```

Figure 17 Calling Hyperparameters

The options.py file obtains the values for different hyper-parameters which are essential for the model building phase.

```
model.py
1 from keras.models import Sequential
2 from keras.layers.convolutional import Convolution2D, MaxPooling2D
3 import warnings
4 warnings.filterwarnings("ignore")
5 from keras.layers.core import Dense, Dropout, Flatten, Activation
6 from keras.layers.normalization import BatchNormalization
7 from keras.layers import Conv2D, MaxPooling2D
8
9 #defining MyModel class for all the pretraining models which include base model.
10 class MyModel():
11     def __init__(self, baseModel, classes, D):
12         self.baseModel = baseModel
13         self.classes = classes
14         self.D = D
15
16     def build(self):
17         """
18         It takes baseModel , number of classes, and number of hidden units as a input.
19         And return a new CNN architecture.
20
21         """
22         headModel = self.baseModel.output
23         headModel = Flatten(name="Flatten")(headModel)
24         headModel = Dense(self.D, activation='relu')(headModel)
25         headModel = Dropout(0.5)(headModel)
26         headModel = Dense(self.classes, activation='softmax')(headModel)
27         return headModel
28
```

Figure 18 Model Building MyModel

```
#defining MyCNN class for the CNN model.
1 class MyCNN():
2     def __init__(self, classes):
3         self.classes = classes
4
5     def build(self):
6         model = Sequential()
7         model.add(Convolution2D(32, (3, 3), input_shape=(224, 224, 3)))
8         model.add(BatchNormalization())
9         model.add(MaxPooling2D(pool_size=(2, 2)))
10        model.add(Dropout(0.5))
11        model.add(Convolution2D(64, (3, 3)))
12        model.add(BatchNormalization())
13        model.add(MaxPooling2D(pool_size=(2, 2)))
14        model.add(Dropout(0.5))
15        model.add(Convolution2D(128, (3, 3)))
16        model.add(MaxPooling2D(pool_size=(2, 2)))
17        model.add(Dropout(0.5))
18        model.add(Flatten())
19        model.add(Dense(2))
20        model.add(Activation('softmax'))
21        return model

```

Figure 19 Model Building MyCNN

The model.py file consists of the MyModel and the CNN model. Both of these models were defined in this file.

```

def main(args):

    NUM_CLASSES = args.num_classes
    IMAGE_RESIZE = args.image_resize
    OBJECTIVE_FUNCTION = args.objective_function

    train_dir = args.train_dir
    val_dir = args.val_dir
    test_dir = args.test_dir

    # Common accuracy metric for all outputs, but can use different metrics for different output
    LOSS_METRICS = ['accuracy']
    NUM_EPOCHS = args.num_epochs

    # These steps value should be proper FACTOR of no.-of-images in train & valid folders respectively
    # Training images processed in each step would be no.-of-train-images / STEPS_PER_EPOCH_TRAINING
    STEPS_PER_EPOCH_TRAINING = args.steps_per_epoch_train
    STEPS_PER_EPOCH_VALIDATION = args.steps_per_epoch_val

    # These steps value should be proper FACTOR of no.-of-images in train & valid folders respectively
    # NOTE that these BATCH* are for Keras ImageDataGenerator batching to fill epoch step input
    BATCH_SIZE_TRAINING = args.train_batch
    BATCH_SIZE_VALIDATION = args.val_batch
    BATCH_SIZE_TESTING = args.test_batch

```

Figure 20 Main function ()

The first part of train.py file includes the configuration of the model for the training phase.

```

#VGG19 Model
if args.model_type == 'vgg19':
    # load pretrained model:
    baseModel = VGG19(weights='imagenet', include_top=False, input_tensor=Input(shape=(224, 224, 3)))
    # initialize head of network
    my_model = MyModel(baseModel, classes=NUM_CLASSES, D=256)
    headModel = my_model.build()
    # replace the FC with headModel:
    my_model = Model(inputs=baseModel.input, outputs=headModel)
    # # unfreezing some of conv layers:
    for layer in baseModel.layers[15:]:
        layer.trainable = True

# Xception Model
elif args.model_type == 'xception':
    # load pretrained model:
    baseModel = Xception(weights='imagenet', include_top=False, input_tensor=Input(shape=(224, 224, 3)))
    # initialize head of network
    my_model = MyModel(baseModel, classes=NUM_CLASSES, D=256)
    headModel = my_model.build()
    # replace the FC with headModel:
    my_model = Model(inputs=baseModel.input, outputs=headModel)
    # unfreezing some of conv layers:
    for layer in baseModel.layers[15:]:
        layer.trainable = True

```

Figure 21 VGG19 and Xception

```

# Thin MobileNet Model
elif args.model_type == 'thinmobilenet':
    # load pretrained model:
    baseModel = MobileNetV2(weights='imagenet', include_top=False, input_tensor=Input(shape=(224, 224, 3)))
    # initialize head of network
    my_model = MyModel(baseModel, classes=NUM_CLASSES, D=256)
    headModel = my_model.build()
    # replace the FC with headModel:
    my_model = Model(inputs=baseModel.input, outputs=headModel)
    # unfreezing some of conv layers:
    for layer in baseModel.layers[15:]:
        layer.trainable = True

#CNN Model
elif args.model_type == 'mycnn':
    # initialize head of network
    my_model = MyCNN(classes=NUM_CLASSES)
    my_model = my_model.build()

print(my_model.summary())

#SGD Optimizer used for all the models
sgd = optimizers.SGD(lr=args.learning_rate)
my_model.compile(optimizer=_sgd, loss=OBJECTIVE_FUNCTION, metrics=LOSS_METRICS)
image_size = IMAGE_RESIZE

```

Figure 22 Thin MobileNet and CNN

Figure 20 and 21 show the code for different models used in the implementation namely, VGG19, Xception, Thin MobileNet, and CNN.

```

train.py x plot.py x
1  import matplotlib.pyplot as plt
2
3
4  def accuracy_plot(fit_history):
5      plt.figure(1, figsize=(15, 8))
6      plt.subplot(221)
7      plt.plot(fit_history.history['acc'])
8      plt.plot(fit_history.history['val_acc'])
9      plt.title('model accuracy')
10     plt.ylabel('accuracy')
11     plt.xlabel('epoch')
12     plt.legend(['train', 'valid'])
13
14
15  def loss_plot(fit_history):
16     plt.figure(1, figsize=(15, 8))
17     plt.subplot(222)
18     plt.plot(fit_history.history['loss'])
19     plt.plot(fit_history.history['val_loss'])
20     plt.title('model loss')
21     plt.ylabel('loss')
22     plt.xlabel('epoch')
23     plt.legend(['train', 'valid'])

```

Figure 23 Plotting the graphs

The plot.py file plots the graphs to showcase the different model's performance in terms of accuracy and loss against the training done with the total number of epochs.



```
1 import cv2
2 import numpy as np
3 import glob
4 from keras.preprocessing import image
5 from tensorflow.keras.models import load_model
6 import os
7 import matplotlib.pyplot as plt
8 import time
9 import logging
10 import os
11 import warnings
12 logging.disable(logging.WARNING)
13 os.environ["TF_CPP_MIN_LOG_LEVEL"] = "3"
14 warnings.filterwarnings("ignore", category=FutureWarning)
15
16 model = load_model("C:/Users/Pushkar/Desktop/imgs/saved_weights/thinmobilenet_best_weights.h5")
17
18 # print(model.summary())
19
20 TEST_DIR = 'C:/Users/Pushkar/Desktop/imgs/test/'
21 # f, ax = plt.subplots(5, 5, figsize = (15, 15))
22
23 images = []
24 titles = []
25
26 count = 1
27
28 for img in glob.glob(TEST_DIR + "*.jpg"):
```

Figure 24 Testing

The test.py file performs the predictions for each of the model whether a driver is driving the car safe or if he is getting distracted while driving.

References

A. K. Vani, R. N. Raajan, D. Haretha Winmalar. and R. Sudharsan. (2020) 'Using the Keras Model for Accurate and Rapid Gender Identification through Detection of Facial Features' in 2020 Fourth International Conference on Computing Methodologies and Communication (ICCMC), Erode, India, 2020, pp. 572-574, doi: 10.1109/ICCMC48092.2020.ICCMC000106.

H. Shin, K. Lee, and C. Lee. (2020) 'Data Augmentation Method of Object Detection for Deep Learning in Maritime Image' in 2020 IEEE International Conference on Big Data and Smart Computing (BigComp), Busan, Korea (South), 2020, pp. 463-466, doi: 10.1109/BigComp48618.2020.00-25.