

# Configuration Manual

MSc Research Project MSc. Data Analytics

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# Configuration Manual

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# **1** System Configuration

This configuration manual is build to describe the research work execution and make it readily replicate for a further study or future projects. All steps have been described in this manual that were performed to execute this research work. Two deep learning techniques have been implemented on google colab pro cloud environment. Minimum hardware configuration that are required.

- 1. Processor: Intel Core i5 or above.
- 2. GPU: Intel HD Graphics 6000 1536 MB
- 3. RAM: memory:8 GB 1600 MHz DDR3

# 2 Environmental Setup

This section provides insight into the use of data mining to segment driving images in detail. While training the network, deep learning models take longer to process the pictures. The experiment is conducted on a Google Co-lab PRO cloud machine with a 100 GB hard drive, 12.72 GB RAM as well as 48.97 GB run-time GPU. Once the hardware requirements are met, necessary software packages are installed and imported.

```
!pip install git+https://github.com/qubvel/segmentation_models.pytorch
!pip install imgaug==0.2.7
!pip install —force-reinstall albumentations==1.0.3
!pip install matplotlib==3.1.3
import torch
import cv2
import matplotlib.pyplot as plt
import segmentation_models_pytorch as smp
import os
import numpy as np
from torch.utils.data import DataLoader
from torch.utils.data import Dataset as BaseDataset
Listing 1: Necessary Libraries
```

PyTorch segmentation models are used to build the deep learning model. For performing augmentation imgaug library is installed. Albumentation library is install to perfrom augumentation on the dataset by targeting the data on various aspects. Matplotlib library is used for visualisation of the data and output. Utils.data is used for data loader to flexibly use the image dataset.

# 3 Data Modeling

Data selected for this research work is Camvid (Cambridge-driving Labeled Video Database) dataset. CamVid dataset is publicly available. Here are the links from where dataset can be downloaded and used for future study.

- 1. http://mi.eng.cam.ac.uk/research/projects/VideoRec/CamVid/
- 2. mi.eng.cam.ac.uk/research/projects/VideoRec/CamSeq01/
- 3. kaggle datasets download -d carlolepelaars/camvid

## 3.1 Loading and reading the Dataset

initially the data is uploaded on the google cloab notebook and combined to read using python package 'OS' and thereby using data given in camvid dataset. Thus import os and os.path.join function are used to for accessing the train test and validation data stored in directory for further analysis.





0	class Dataset(BaseDataset):	
	CLASSES = ['sky', 'building', 'pole', 'road', 'pavement', 'tree', 'signsymbol', 'fence', 'car', 'pedestrian', 'bicyclist', 'unlabelled']	
	<pre>definit(     self,     images_dir,     masks_dir,     classes=None,     augmentation=None,     preprocessing=None,</pre>	
	<pre>):     self.ids = os.listdir(images_dir)     self.images_fps = [os.path.join(images_dir, image_id) for image_id in self.id     self.masks_fps = [os.path.join(masks_dir, image_id) for image_id in self.ids]     self.class_values = [self.CLASSES.index(cls.lower()) for cls in classes] </pre>	s]

Figure 2: data loading

### 3.2 Defining pre-processing Transformation Parameters

Once the data is ready. It is called and class dataset is defined with various measures such as setting path to image directory, path to segmentation mask folder, values and ids of class and images to extract from segmentation mask. Data transformation pipeline is defined using albumentation. Compose function for performing various necessary transformation of images such as horizontal flip, padding, scale rotation etc. Then pre-processing function is defined for resizing and normalisation of the data.



Figure 3: data preprocessing

Once necessary functions has been defined, data visualisation is performed on data set to check the segmented mask associated with class images.

def	<pre>get_training_augmentation(): train_transform = [</pre>	
	<pre>alb.HorizontalFlip(p=0.5),</pre>	
	<pre>alb.ShiftScaleRotate(scale_limit=0.5, rotate_limit=0, shift_limit=0.1, p=</pre>	1, border_mode=0),
	<pre>alb.PadIfNeeded(min_height=320, min_width=320, always_apply=True, border_ alb.RandomCrop(height=320, width=320, always_apply=True),</pre>	mode=0),
alk INAdditiveCounciesNaice/w=0 2)		
	(p - 0.2)	
	alb. TAAPerspective(p=0.5),	
	alb.OneOf(	
	alb.CLAHE(p=1),	
	alb.RandomBrightness(p=1),	
	alb.RandomGamma(p=1),	

Figure 4: data augumentation

Since image data is small, data loaded is augmented and transformed using albumentation library for training and testing purpose.

```
def get_validation_augmentation():
    test_transform = [
        alb.PadIfNeeded(384, 480)
    ]
    return alb.Compose(test_transform)

def to_tensor(x, **kwargs):
    return x.transpose(2, 0, 1).astype('float32')

def get_preprocessing(preprocessing_fn):
    _transform = [
        albu.Lambda(image=preprocessing_fn),
        albu.Lambda(image=to_tensor, mask=to_tensor),
    ]
    return albu.Compose(_transform)
```

Figure 5: data loading

## 3.3 Data modeling for training and testing

after pre-processing and transformation of data. The augmented data is used for model training and testing purpose. Here is segmentation model based on U-Net architecture is modelled. That will process segmentation on camvid dataset and provide segmented mask results based on classes.



Figure 6: Defining Parameters

Once encoder and encoder weights are initialised in the architecture model is trained and tested on the data set. The Evaluation parameters are also defined in order to check the model performance on segmentation task.

Once model is tested, the results are analysed and visualised based on evaluation metrics and segmentation mask results based on random selection of images and results of test data are compared with segmentation mask generated for particular class from training the model.



Figure 7: training

# evaluate model on test set
<pre>test_epoch = smp.utils.train.ValidEpoch(</pre>
<pre>model=best_model,</pre>
loss=loss,
metrics=metrics,
device=DEVICE,
logs = test_epoch.run(test_dataloader)
valid: 100%  233/233 [00:07<00:00, 32.03it/s, dice_loss - 0.2835, iou_score - 0.7518]

Figure 8: Testing phase

References