

Configuration Manual

MSc Research Project MSc. in Data Analytics

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Configuration Manual

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1 Introduction

Most of the system setup, hardware and software requirements and the implementation and evaluation along with exploratory data analaysis has been explained in this configuration manual.

2 Exploratory Data Analysis

2.1 Mount the Google Drive

Google Drive is mounted so that the files can be accessed.¹

[] #Mount the google drive: from google.colab import drive drive.mount('/content/drive') C→ Go to this URL in a browser: https://accounts.google.com/o/oauth2/auth?client_id=947318989803-6bn6qk8qdgf4n4g3pfee6. Enter your authorization code: Mounted at /content/drive

Figure 1: Google Drive

[] animals_path = "/content/drive/My Drive/Colab Notebooks/Six_Classes"

Figure 2: Folder directory

The folder directory is set where the dataset is present so that files can be accessed from the directory mentioned.

 $^{^{1} \}rm https://drive.google.com/drive/folders/1Q6kJBWvVC_{D}dSAvg97jp65Cs3KoUjbYO$

2.2 Importing the libraries



Figure 3: Importing libraries

Libraries of tensorflow, ker as, glob, matplotlib, math are imported so that methods and functions are used later on for certain tasks.²

2.3 Distribution of selected classes





²https://www.tensorflow.org/

Pygal library is used to plot the available classes. The plot is done using bar graph. A wrapper is created to render the chart inline and data is passed through it so that it can be displayed.



Figure 5: Class distribution

Figure 5 refers to the class distribution obtained for the classes present in the original dataset. It seems that Red Deer has the highest number of samples making it the majority class and Red Squirrel has the lowest number of samples making it the minority class as compared to other 5 classes.

2.4 Confirm Folder Structure

```
#Confirm Folder Structure
[]
     for root, dirs, files in os.walk(animals_path):
         level = root.replace(os.getcwd(), '').count(os.sep)
         print('{0}{1}/'.format('
                                     ' * level, os.path.basename(root)))
         for f in files[:2]:
            print('{0}{1}'.format('
                                        ' * (level + 1), f))
         if level is not 0:
          print('{0}{1}'.format('
                                      ' * (level + 1), "..."))
   Six_Classes/
C→
        Collared_Peccary/
             SEQ88200 IMG 0003.JPG
             SEQ88200_IMG_0007.JPG
        Ocelot/
             SEQ75294_IMG_0005.JPG
             SEQ75294_IMG_0003.JPG
        White-nosed Coati/
             SEQ84536 IMG 0001.JPG
             SEQ84536_IMG_0008.JPG
        Red_Squirrel/
             SEQ75972_IMG_0002.JPG
             SEQ76082_IMG_0001.JPG
         Red Deer/
             SEQ80452 IMG 0016.JPG
             SEQ80452_IMG_0019.JPG
             . . .
         European_Hare/
             SEQ75140 IMG 0004.JPG
             SEQ75140 IMG 0001.JPG
             . . .
```

Figure 6: Folder Structure

Here, the folder structure is verified so that we can go ahead with applying models to the dataset. The output shows that there are six folders for six different classes. In each folder, there are sequences of different images.

2.5 Create Train, Validation and Test folders

```
[] import math
    import re
    import sys
    #Train and Test Set Variables
    train_val_test_ratio = (.7,.1,.2) # 70/10/20 Data Split
    test_folder = 'test/'
    train_folder = 'train/'
    val folder = 'val/'
    file_names = os.listdir('/content/drive/My Drive/Colab Notebooks/Six_Classes')
    #Remove Existing Folders if they exist
    for folder in [test_folder, train_folder, val_folder]:
        if os.path.exists(folder) and os.path.isdir(folder):
            shutil.rmtree(folder)
    #Remake Category Folders in both Train and Test Folders
     for category in file_names:
        os.makedirs(test_folder + category)
         os.makedirs(train_folder + category)
        os.makedirs(val_folder + category)
```

Figure 7: Creation of training, validation and test folders

```
#Split Data by Train Ratio and copy files to correct directory
for idx, category in enumerate(file_names):
   file_list = os.listdir(animals_path + '/' + category)
   train_ratio = math.floor(len(file_list) * train_val_test_ratio[0])
   val_ratio = math.floor(len(file_list) * train_val_test_ratio[1])
   train list = file list[:train ratio]
   val_list = file_list[train_ratio:train_ratio + val_ratio]
   test_list = file_list[train_ratio + val_ratio:]
   for i, file in enumerate(train_list):
      shutil.copy(animals_path + '/' + category + '/' + file, train_folder + '/' + category + '/' + file)
   sys.stdout.write('Moving %s train images to category folder %s' % (len(train_list), category))
   sys.stdout.write('\n')
   for i, file in enumerate(val_list):
     shutil.copy(animals path + '/' + category + '/' + file, val folder + '/' + category + '/' + file)
   sys.stdout.write('Moving %s validation images to category folder %s' % (len(val_list), category))
   sys.stdout.write('\n')
   for i, file in enumerate(test_list):
     shutil.copy(animals_path + '/' + category + '/' + file, test_folder + '/' + category + '/' + file)
   sys.stdout.write('Moving %s test images to category folder %s' % (len(test_list), category))
   sys.stdout.write('\n')
print("Done.")
```

Figure 8: Data split

The idea is to create three folders, train, validation and test with the data split ratio of 70%, 10% and 20% respectively. The directory where the folders should be created is listed. Also, if there is train, validate and test folder already existing in the listed directory, then they are removed and the folders are recreated after then the data is split in the consecutive folders.

□→ Moving 348 train images to category folder Collared Peccary Moving 49 validation images to category folder Collared Peccary Moving 101 test images to category folder Collared Peccary Moving 384 train images to category folder Ocelot Moving 54 validation images to category folder Ocelot Moving 111 test images to category folder Ocelot Moving 906 train images to category folder White-nosed Coati Moving 129 validation images to category folder White-nosed_Coati Moving 260 test images to category folder White-nosed_Coati Moving 261 train images to category folder Red_Squirrel Moving 37 validation images to category folder Red_Squirrel Moving 76 test images to category folder Red Squirrel Moving 1980 train images to category folder Red Deer Moving 283 validation images to category folder Red Deer Moving 567 test images to category folder Red Deer Moving 489 train images to category folder European Hare Moving 70 validation images to category folder European Hare Moving 141 test images to category folder European Hare Done.

Figure 9: Output for data split

2.6 Data Augmentation

This step is carried out to tackle the issue of class imbalance. Minority classes are augmented with a shift of 45 degrees so that the number of images for the minority class to train increases.

A check is carried out after the first 45 degrees shift of data augmentation to see the increase in the number of images for the minority class. The minority classes are again augmented to balance the classes.

Firstly, an example image is taken to observe the effect of augmentation. Then the image is displayed. A number of 4 augmentations is done to each image of the minority class. The augmentation is completed randomly on the minority class images. It is carried out for the training data only in order to stop the class bias. The validation and testing images remains the same as passes on originally after segregation.

```
[] import random
import numpy as np
from keras.preprocessing.image import ImageDataGenerator, array_to_img, img_to_array, load_img
```

□→ Using TensorFlow backend.

Figure 10: Importing the library for data augmentation

[]	<pre>#Select a random image and fo datagen = ImageDataGenerator(</pre>	random image and follow the next step ImageDataGenerator(rotation range=45,				
		<pre>width_shift_range=0.2, height_shift_range=0.2,</pre>				
		<pre>zoom_range=0.3, vertical_flip=True, horizontal_flip=True, fill_mode="nearest")</pre>				

Figure 11: Image Data Generator



Figure 12: Sample image

```
[ ] img = img_to_array(img)
    img = img.reshape((1,) + img.shape)
```

Figure 13: Image to array







Figure 15: Augmentation example

```
[] #Oversampling Minority Classes in Training Set
    def data_augment(data_dir):
        list of images = os.listdir(data dir)
        datagen = ImageDataGenerator(rotation_range=45,
            horizontal_flip=True,
            fill_mode="nearest")
         for img_name in list_of_images:
            tmp_img_name = os.path.join(data_dir, img_name)
            img = load_img(tmp_img_name)
            img = img_to_array(img)
            img = img.reshape((1,) + img.shape)
            batch = datagen.flow(img,
                batch_size=1,
                seed=21,
                save to dir=data dir,
                save_prefix=img_name.split(".JPG")[0] + "augmented",
                save_format="JPG")
            batch.next()
```

Figure 16: Oversampling minority class



Figure 17: Classes to augment

Currently Augmenting: Red_Squirrel Currently Augmenting: European_Hare Currently Augmenting: Ocelot Currently Augmenting: Collared_Peccary Currently Augmenting: White-nosed_Coati

Figure 18: Classes augmenting

Hansson (2002) augmented images before calculating top-1 and top-5 values.

2.7 Resizing of images

[]	from pydrive.auth import GoogleAuth from pydrive.drive import GoogleDrive from google.colab import auth from oauth2client.client import GoogleCredentials
[]	auth.authenticate_user() gauth = GoogleAuth()
Ċ	WARNING:tensorflow: The TensorFlow contrib module will not be included in TensorFlow 2.0. For more information, please see: * https://github.com/tensorflow/community/blob/master/rfcs/20180907-contrib-sunset.md * https://github.com/tensorflow/addons * https://github.com/tensorflow/io (for I/O related ops) If you depend on functionality not listed there, please file an issue.
[]	<pre>gauth.credentials = GoogleCredentials.get_application_default() drive = GoogleDrive(gauth)</pre>
[]	your_module = drive.CreateFile({"id": "1SLIjmWVYhFEQ6ImUlOzv5rZa4eV35eE5"}) # "your_module_file_id" is the part after "id=" in the shareable link your_module.GetContentFile("six_classes_utils.py") # Save the .py module file to Colab VM
	Figure 19: File access on google drive

[] import six_classes_utils
[] from multiprocessing import Pool

Figure 20: Importing the functions from an external file

Files from google drive are accessed by setting up the gauth function. Shareable link is used to import functions from a different file. The external file six_classes_utils includes resizing function for the images.

[]	from functools import partial
	<pre>#Resize Images ifname == 'main': pool = Pool() image_list = glob.glob(train_folder + "/*/*") func = partial(six_classes_utils.resize_image, size=299) pool.map(func, image_list) pool.close()</pre>
	<pre>six_classes_utils.display_images(train_folder)</pre>

Figure 21: Resize of the images

six_classes_utils is the file used from google drive to resie the images. Libraries like cv2, random, glob are used and a function for resizing is written in the file.³

³https://opencv.org/

```
import random
import matplotlib.pyplot as plt
import matplotlib.image as mpimg
import glob
from PIL import Image
import cv2
import os
```

Figure 22: Libraries for the util file

```
def resize_image(file, size=299):
    img = Image.open(file)
    img = img.resize((size,size))
    img.save(file)
```

Figure 23: Function for resizing



Figure 24: Sample image after resizing

2.8 Look at Distribution of Selected Classes again

Now, the class imbalance issue has been resolved as all the classes are more likely similar in the number of images that each class possess. Pygal barchart is used for plotting the distribution graph.

Figure 25: Class Distribution after augmentation



Figure 26: Bar chart after augmentation

3 Deep Learning Architectures

3.1 Data Generator

[]	from keras.preprocessing.image import ImageDataGenerator
Ľ→	Using TensorFlow backend.
[]	<pre>from keras.applications.inception_v3 import preprocess_input, decode_predictions</pre>
[]	#Mount the google drive: from google.colab import drive drive.mount('/content/drive')
¢	Go to this URL in a browser: https://accounts.googleusercontent.com&redirect Enter your authorization code:
	4
[]	#Check the directory: cd /content/drive/My Drive/Colab Notebooks/Six_Classes

C→ /content/drive/My Drive/Colab Notebooks/Six_Classes

Figure 27: Importing ImageGenerator

```
[ ] WIDTH=299
HEIGHT=299
BATCH_SIZE=64
test_dir = 'test/'
train_dir = 'train/'
val_dir = 'val/'
```

Figure 28: Resizing as per InceptionV3



Figure 29: Resizing as per VGG16 and MobileNet

Nguyen et al. (2018) resized the images before applying the deep learning architectures.

Training Data Set Found 11209 images belonging to 6 classes.

Figure 30: Train Dataset Generator

Verma and Gupta (2018) applied DCNN architectures after training and testing dataset using generator.

C→

Validation Data Set Found 622 images belonging to 6 classes.

Figure 31: Validation Dataset Generator

```
Test Data Set
Found 1256 images belonging to 6 classes.
```

Figure 32: Test Dataset Generator

The data from the Keras ImageDataGenerator class has been ingested for training purposes.⁴ This will assist in reading the directory structured as per the category of classes which was done during the training in the exploration phase.

For InceptionV3, the height and width requirement is 299x299. For VGG-16 and MobileNet, the height and width requirement is 224x224. The generator also resizes the images as per the architecture before feeding the data into the network so that the training, test and validation phase works successfully. Chen et al. (2014) and Chung et al. (2018) resized the images before applying the DCNN algorithms.

3.2 Optimization for CPU

[] from keras.models import Sequential, Model, load_model from keras.callbacks import ModelCheckpoint, EarlyStopping, TensorBoard, CSVLogger from keras import optimizers, models from keras.layers import Dense, Dropout, GlobalAveragePooling2D from keras import applications from keras import backend as K import tensorflow as tf import os

Figure 33: Libraries for optimizers and modelst

⁴https://keras.io/



Figure 34: Optimization setup

3.3 Selecting Hyperparameters



Figure 35: Model for InceptionV3

[]	# add a global spatial average pooling layer x = base_model.output
[]	<pre>x = GlobalAveragePooling2D()(x) # and a dense layer x = Dense(1024, activation='relu')(x) predictions = Dense(len(train_flow.class_indices), activation='softmax')(x)</pre>
[]	<pre># this is the model we will train model = Model(inputs=base_model.input, outputs=predictions)</pre>
[]	<pre># first: train only the top layers (which were randomly initialized) # i.e. freeze all convolutional InceptionV3 layers for layer in base_model.layers: layer.trainable = False</pre>
[]	<pre># compile the model (should be done *after* setting layers to non-trainable) model.compile(optimizer=optimizers.Adam(lr=0.001), metrics=['accuracy', 'top_k_categorical_accuracy'], loss='categorical_crossentropy') model.summary()</pre>

Figure 36: Layers for InceptionV3

Model: "model_1"

Layer (type)	Output	Shape	Param #	Connected to
input_1 (InputLayer)	(None,	299, 299, 3)	0	
conv2d_1 (Conv2D)	(None,	149, 149, 32)	864	input_1[0][0]
batch_normalization_1 (BatchNor	(None,	149, 149, 32)	96	conv2d_1[0][0]
activation_1 (Activation)	(None,	149, 149, 32)	0	<pre>batch_normalization_1[0][0]</pre>
conv2d_2 (Conv2D)	(None,	147, 147, 32)	9216	activation_1[0][0]
batch_normalization_2 (BatchNor	(None,	147, 147, 32)	96	conv2d_2[0][0]
activation_2 (Activation)	(None,	147, 147, 32)	0	<pre>batch_normalization_2[0][0]</pre>
conv2d_3 (Conv2D)	(None,	147, 147, 64)	18432	activation_2[0][0]
batch_normalization_3 (BatchNor	(None,	147, 147, 64)	192	conv2d_3[0][0]
activation_3 (Activation)	(None,	147, 147, 64)	0	<pre>batch_normalization_3[0][0]</pre>
<pre>max_pooling2d_1 (MaxPooling2D)</pre>	(None,	73, 73, 64)	0	activation_3[0][0]
conv2d_4 (Conv2D)	(None,	73, 73, 80)	5120	<pre>max_pooling2d_1[0][0]</pre>
batch_normalization_4 (BatchNor	(None,	73, 73, 80)	240	conv2d_4[0][0]
activation_4 (Activation)	(None,	73, 73, 80)	0	<pre>batch_normalization_4[0][0]</pre>
conv2d_5 (Conv2D)	(None,	71, 71, 192)	138240	activation_4[0][0]

Figure 37: Model summary for InceptionV3 (1)

activation_93 (Activation)	(None,	8,	8,	384)	0	<pre>batch_normalization_93[0][0]</pre>
batch_normalization_94 (BatchNo	(None,	8,	8,	192)	576	conv2d_94[0][0]
activation_86 (Activation)	(None,	8,	8,	320)	0	<pre>batch_normalization_86[0][0]</pre>
mixed9_1 (Concatenate)	(None,	8,	8,	768)	0	activation_88[0][0] activation_89[0][0]
concatenate_2 (Concatenate)	(None,	8,	8,	768)	0	activation_92[0][0] activation_93[0][0]
activation_94 (Activation)	(None,	8,	8,	192)	0	<pre>batch_normalization_94[0][0]</pre>
mixed10 (Concatenate)	(None,	8,	8,	2048)	0	activation_86[0][0] mixed9_1[0][0] concatenate_2[0][0] activation_94[0][0]
global_average_pooling2d_3 (Glo	(None,	20	48)		0	mixed10[0][0]
dense_2 (Dense)	(None,	10	24)		2098176	global_average_pooling2d_3[0][0]
dense_3 (Dense)	(None,	6)			6150	dense_2[0][0]

Total params: 23,907,110 Trainable params: 2,104,326 Non-trainable params: 21,802,784

Figure 38: Model summary for InceptionV3 (2)

Figure 39: Model summary for MobileNet (1)

conv_pw_12_relu (ReLU)	(None,	7, 7, 1024)	0
conv_dw_13 (DepthwiseConv2D)	(None,	7, 7, 1024)	9216
conv_dw_13_bn (BatchNormaliz	(None,	7, 7, 1024)	4096
conv_dw_13_relu (ReLU)	(None,	7, 7, 1024)	0
conv_pw_13 (Conv2D)	(None,	7, 7, 1024)	1048576
conv_pw_13_bn (BatchNormaliz	(None,	7, 7, 1024)	4096
conv_pw_13_relu (ReLU)	(None,	7, 7, 1024)	0
global_average_pooling2d_1 ((None,	1024)	0
dense_1 (Dense)	(None,	1024)	1049600
dense_2 (Dense)	(None,	6)	6150
Total params: 4,284,614 Trainable params: 1,055,750 Non-trainable params: 3,228,8	====== 864		

Figure 40: Model summary for MobileNet (2)

[]	# Initialize VGG16 with transfer	r learning
	<pre>base_model = applications.VGG16</pre>	(weights='imagenet',
		<pre>include_top=False,</pre>
		<pre>input_shape=(WIDTH, HEIGHT,3))</pre>

Figure 41: Model summary for VGG16 (1)

block5_conv1 (Conv2D)	(None,	14, 14, 512)	2359808
block5_conv2 (Conv2D)	(None,	14, 14, 512)	2359808
block5_conv3 (Conv2D)	(None,	14, 14, 512)	2359808
<pre>block5_pool (MaxPooling2D)</pre>	(None,	7, 7, 512)	0
<pre>global_average_pooling2d_1 (</pre>	(None,	512)	0
dense_1 (Dense)	(None,	1024)	525312
dense_2 (Dense)	(None,	6)	6150
Total params: 15,246,150 Trainable params: 531,462 Non-trainable params: 14,714	,688		

Figure 42: Model summary for VGG16 (2)

InceptionV3, VGG16 and MobileNet are the three architectures used for the classification of animals. Here, transfer learning is used with the weights of imagenet and top layer is removed as 1001 classes are not predicted in this dataset. The learning rate is set to 0.001 and therefore, the dataset takes a longer time to train for each of the algorithms. Adam optimizer is used as it adapts to the learning rate according to the parameters. Batch size of 32 is used and hence, 32 images are used in training the dataset in one iteration.

GlobalAveragePooling2D layer is added to the base model and the Dense layer is added with a softmax activation to predict the number of classes in the dataset. Layer trainables is set to False so that the new layers are trained that are added in this dataset. Since, we have multiclass classification, we have added loss of categorical crossentropy is used.

3.4 Training Callbacks

Keras Fit Generator Method is used for training. Here, training and validation dataset is used in order to check if the model is performing well rather than directly working on the test dataset. Four different callbacks such as ModelCheckkpoint, TensorBoard, EarlyStopping and CSVLogger. Checkpoints are used to minimize the disk space that is being used. Also, overtraining and overutilizing the compute is taken care of by callbacks.

```
[] import math
top_layers_file_path="top_layers.iv3.hdf5"
[] checkpoint = ModelCheckpoint(top_layers_file_path, monitor='loss', verbose=1, save_best_only=True, mode='min')
tb = TensorBoard(log_dir='./logs', batch_size=val_flow.batch_size, write_graph=True, update_freq='batch')
early = EarlyStopping(monitor="loss", mode="min", patience=5)
csv_logger = CSVLogger('./logs/iv3-log.csv', append=True)
```

Figure 43: Model checkpoint for InceptionV3

[]	history = model.fit_generator(train_flow,			
		epochs=3,		
		verbose=1,		
validation_data=val_flow,		validation_data=val_flow,		
		validation_steps=math.ceil(val_flow.samples/val_flow.batch_size),		
steps_per_epoch=math.ceil(train_flow.samples/train_fl		<pre>steps_per_epoch=math.ceil(train_flow.samples/train_flow.batch_size),</pre>		
		callbacks=[checkpoint, early, tb, csv_logger])		



Epoch 1/3

1/176 [.....] - ETA: 2:18:17 - loss: 1.8698 - acc: 0.1406 - top_k_categorical_accuracy: 0.7812WARNING:tensorflow:From /usr/local/lib/p 176/176 [=========] - 3637s 21s/step - loss: 0.6026 - acc: 0.7977 - top_k_categorical_accuracy: 0.9909 - val_loss: 1.0850 - val_acc: 0.6929 Epoch 00001: loss improved from inf to 0.60256, saving model to top_layers.iv3.hdf5

176/176 [========] - 3661s 21s/step - loss: 0.2026 - acc: 0.9321 - top_k_categorical_accuracy: 0.9999 - val_loss: 1.4542 - val_acc: 0.6913 Epoch 00002: loss improved from 0.60256 to 0.20270, saving model to top_layers.iv3.hdf5

Epoch 3/3 176/176 [-------] - 3426s 19s/step - loss: 0.1347 - acc: 0.9563 - top_k_categorical_accuracy: 1.0000 - val_loss: 1.6536 - val_acc: 0.6849 Epoch 00003: loss improved from 0.20270 to 0.13483, saving model to top layers.iv3.hdf5

Figure 45: Output for training and validation of InceptionV3

[] import math top_layers_file_path="top_layers.mn.hdf5"

Figure 46: Model checkpoint for MobileNet (1)

[] checkpoint = ModelCheckpoint(top_layers_file_path, monitor='loss', verbose=1, save_best_only=True, mode='min')
tb = TensorBoard(log_dir='./logs', batch_size=val_flow.batch_size, write_graph=True, update_freq='batch')
early = EarlyStopping(monitor="loss", mode="min", patience=5)
csv_logger = CSVLogger('./logs/mn-log.csv', append=True)



[]	history = model.fit_generator	r(train_flow,	
		epochs=3,	
	verbose=1,		
	validation_data=val_flow,		
	validation_steps=math.ceil(val_flow.samples/val_fl		ow.batch_size),
		<pre>steps_per_epoch=math.ceil(train_flow.samples/train callbacks=[checkpoint, early, tb, csv_logger])</pre>	_flow.batch_size),

Figure 48: Training for MobileNet

C≯	Epoch 1/3 176/176 [====================================
	Epoch 00001: loss improved from 0.33142 to 0.05163, saving model to top_layers.mn.hdf5 Epoch 2/3
	176/176 [=======] - 64s 362ms/step - loss: 0.0496 - acc: 0.9838 - top_k_categorical_accuracy: 0.9999 - val_loss: 0.9246 - val_acc: 0.7186
	Epoch 00002: loss improved from 0.05163 to 0.04967, saving model to top_layers.mn.hdf5 Epoch 3/3
	176/176 [====================================
	Epoch 00003: loss improved from 0.04967 to 0.02343, saving model to top_layers.mn.hdf5

Figure 49: Output for training and validation of MobileNet

[] import math
 top_layers_file_path="top_layers.vgg16.hdf5"

Figure 50: Model checkpoint for VGG-16 (1)

[] checkpoint = ModelCheckpoint(top_layers_file_path, monitor='loss', verbose=1, save_best_only=True, mode='min')
tb = TensorBoard(log_dir='./logs', batch_size=val_flow.batch_size, write_graph=True, update_freq='batch')
early = EarlyStopping(monitor="loss", mode="min", patience=5)
csv_logger = CSVLogger('./logs/vgg16-log.csv', append=True)

Figure 51: Model checkpoint for VGG-16 (2)

[]	history = model.fit_generator	<pre>'(train_flow, epochs=3, verbose=1, validation_data=val_flow, validation_steps=math.ceil(val_flow.samples/val_fl steps_per_epoch=math.ceil(train_flow.samples/train callbacks=[checkpoint, early, tb, csy logger])</pre>	ow.batch_size), _flow.batch_size),
		callbacks=[checkpoint, early, tb, csv_logger])	

Figure 52: Training for VGG-16

Epoch 1/3 1/176 [] - ETA: 2:39:42 - loss: 4.8683 - acc: 0.1562 - top_k_categorical_accuracy: 0.8281WARNING:tensorflow:From /usr/local/lib/p
176/176 [======] - 6063s 34s/step - loss: 0.4321 - acc: 0.8970 - top_k_categorical_accuracy: 0.9899 - val_loss: 1.9332 - val_acc: 0.5193
Epoch 00001: loss improved from inf to 0.43310, saving model to top_layers.vgg16.hdf5 Epoch 2/3 176/176 [====================================
Epoch 00002: loss improved from 0.43310 to 0.05128, saving model to top_layers.vgg16.hdf5 Epoch 3/3 176/176 [====================================
Epoch 00003: loss improved from 0.05128 to 0.04000, saving model to top_layers.vgg16.hdf5

Figure 53: Output for training and validation of VGG-16

3.5 Evaluate Model

```
[ ] model.load_weights(top_layers_file_path)
loss, acc, top_5 = model.evaluate_generator(
    test_flow,
    verbose = True,
    steps=math.ceil(test_flow.samples/test_flow.batch_size))
```



```
[ ] print("Loss: ", loss)
    Loss: 1.6115237535185116
[ ] print("Acc: ", acc)
    Acc: 0.695859872611465
[ ] print("Top 5: ", top_5)
    Fy Top 5: 0.9976114649681529
```



```
Acc: 0.6791401277681824
Top 5: 0.9976114657274477
```

Figure 56: Loss, accuracy and Top5 confidence for MobileNet

```
[ ] model.load_weights(top_layers_file_path)
    loss, acc, top_5 = model.evaluate_generator(
        test_flow,
        verbose = True,
        steps=math.ceil(test_flow.samples/test_flow.batch_size))
    print("Loss: ", loss)
    print("Acc: ", acc)
    print("Top 5: ", top_5)

C → 20/20 [============] - 835s 42s/step
    Loss: 1.8602820445018209
    Acc: 0.6242038220356984
    Top 5: 0.9992038216560509
```

Figure 57: Loss, accuracy and Top5 confidence for VGG-16

3.6 Write Labels File

Figure 58: Write Label for IV3

Figure 59: Write Label for MobileNet

Figure 60: Write Label for VGG-16

The network uses the numerical value to refer to a particular class. The values are saved in a text file to map the classes to a particular numerical value for future use.

3.7 Test Model with Sample Image

```
[ ] from keras.preprocessing import image
import numpy as np
import glob
import random
```

Figure 61: Test Model for InceptionV3 (1)

```
[ ] file_list = glob.glob("test/*/*")
[ ] img_path = random.choice(file_list)
[ ] img_cat = os.path.split(os.path.dirname(img_path))[1]
[ ] print("Image Category: ", img_cat)
```

[→ Image Category: White-nosed_Coati

Figure 62: Test Model for InceptionV3 (2)

```
[ ] img = image.load_img(img_path, target_size=(299, 299))
```

- [] x = image.img_to_array(img)
- [] x = np.expand_dims(x, axis=0)
- [] x = preprocess_input(x)
- [] preds = model.predict(x)
- [] print("Raw Predictions: ", preds)
- C→ Raw Predictions: [[9.9079716e-01 1.3424299e-10 5.9693298e-06 2.2137892e-06 9.6429358e-05 9.0981722e-03]]

Figure 63: Test Model for InceptionV3 (3)

```
] top x = 3
    top args = preds[0].argsort()[-top x:][::-1]
    preds label = [label[p] for p in top args]
[]
```

Figure 64: Test Model for InceptionV3 (4)

```
[ ] print("\nTop " + str(top_x) + " confidence: " + " ".join(map(str, sorted(preds[0])[-top_x:][::-1])))
C→
     Top 3 confidence: 0.99079716 0.009098172 9.642936e-05
[ ] print("Top " + str(top_x) + " labels: " + " ".join(map(str, preds_label)))
[→ Top 3 labels: Collared_Peccary White-nosed_Coati Red_Squirrel
```

Figure 65: Test Model for InceptionV3 (5)

```
[ ] from keras.preprocessing import image
    import numpy as np
    import glob
    import random
    file_list = glob.glob("test/*/*")
    img path = random.choice(file list)
    img_cat = os.path.split(os.path.dirname(img_path))[1]
    print("Image Category: ", img_cat)
    img = image.load_img(img_path, target_size=(224, 224))
    x = image.img_to_array(img)
    x = np.expand_dims(x, axis=0)
    x = preprocess input(x)
    preds = model.predict(x)
    print("Raw Predictions: ", preds)
    top x = 3
    top_args = preds[0].argsort()[-top_x:][::-1]
    preds_label = [label[p] for p in top_args]
    print("\nTop " + str(top_x) + " confidence: " + " ".join(map(str, sorted(preds[0])[-top_x:][::-1])))
    print("Top " + str(top_x) + " labels: " + " ".join(map(str, preds_label)))
```

Figure 66: Test Model for MobileNet (1)

```
    Image Category: Red_Deer
    Raw Predictions: [[6.9340802e-04 1.1363633e-05 1.0804304e-06 9.9020493e-01 5.6083937e-08
    9.0891048e-03]]

    Top 3 confidence: 0.99020493 0.009089105 0.000693408
    Top 3 labels: Red Deer White-nosed Coati Collared Peccary
```

Figure 67: Test Model for MobileNet (2)

[] from keras.preprocessing import image import numpy as np import glob import random

```
[ ] file_list = glob.glob("test/*/*")
    img_path = random.choice(file_list)
    img_cat = os.path.split(os.path.dirname(img_path))[1]
    print("Image Category: ", img_cat)
    img = image.load_img(img_path, target_size=(224, 224))
    x = image.img_to_array(img)
    x = np.expand_dims(x, axis=0)
    x = preprocess_input(x)
```

[→ Image Category: White-nosed Coati

Figure 68: Test Model for VGG-16 (1)

```
[ ] preds = model.predict(x)
    print("Raw Predictions: ", preds)

□ Raw Predictions: [[9.3152217e-04 5.0856639e-04 1.2653039e-03 5.9000980e-05 8.0474538e-01
    1.9249023e-01]]
```

Figure 69: Test Model for VGG-16 (2)

```
[] top_x = 3
top_args = preds[0].argsort()[-top_x:][::-1]
preds_label = [label[p] for p in top_args]
print("\nTop " + str(top_x) + " confidence: " + " ".join(map(str, sorted(preds[0])[-top_x:][::-1])))
print("Top " + str(top_x) + " labels: " + " ".join(map(str, preds_label)))

C+
Top 3 confidence: 0.8047454 0.19249023 0.0012653039
Top 3 labels: Red_Squirrel White-nosed_Coati Ocelot
```

Figure 70: Test Model for VGG-16 (3)

The models are first tested on a sample image after the training. A random image is chosen from the test dataset and the model is run through the image. Softmax function returns the confidence values. Top-3 labels and values are predicted by the model. Norouzzadeh et al. (2017) calculated and Gomez Villa et al. (2017) discussed about the confidence values to save human labor.

3.8 Transform Keras Model to Tensorflow

[] from tensorflow.python.framework import graph_util from tensorflow.python.framework import graph_io

Figure 71: Tranformation from Keras to Tensorflow for InceptionV3 (1)

Figure 72: Tranformation from Keras to Tensorflow for InceptionV3 (2)

```
Instructions for updating:
Use `tf.compat.v1.graph_util.extract_sub_graph`
INFO:tensorflow:Froze 380 variables.
INFO:tensorflow:Converted 380 variables to const ops.
```

Figure 73: Tranformation from Keras to Tensorflow for InceptionV3 (3)

_ 'tf_model/top_layers.iv3.pb'

Figure 74: Tranformation from Keras to Tensorflow for InceptionV3 (4)

```
from tensorflow.python.framework import graph util
from tensorflow.python.framework import graph io
input model path = top layers file path
output model name = "top nodes.mn.pb"
output model dir = "tf model"
K.set learning phase(∅)
sess = K.get session()
test model = models.load model(input model path)
orig output node names = [node.op.name for node in test model.outputs]
constant graph = graph util.convert variables to constants(
    sess,
    sess.graph.as_graph_def(),
    orig output node names)
graph io.write graph(
   constant_graph,
    output model dir,
    output_model_name,
    as text=False)
```

Figure 75: Tranformation from Keras to Tensorflow for MobileNet (1)

```
Use `tf.compat.v1.graph_util.extract_sub_graph`
INFO:tensorflow:Froze 139 variables.
INFO:tensorflow:Converted 139 variables to const ops.
'tf_model/top_nodes.mn.pb'
```

Figure 76: Tranformation from Keras to Tensorflow for MobileNet (2)

[] input_model_path = top_layers_file_path output_model_name = "top_layers.vgg16.pb" output_model_dir = "tf_model"

- [] K.set_learning_phase(0)
 sess = K.get_session()
- [] test_model = models.load_model(input_model_path)
 orig_output_node_names = [node.op.name for node in test_model.outputs]

Figure 77: Tranformation from Keras to Tensorflow for VGG-16 (1)

Figure 78: Tranformation from Keras to Tensorflow for VGG-16 (2)

Instructions for updating: Use `tf.compat.v1.graph_util.extract_sub_graph` INFO:tensorflow:Froze 30 variables. INFO:tensorflow:Converted 30 variables to const ops. 'tf_model/top_layers.vgg16.pb'

Figure 79: Tranformation from Keras to Tensorflow for VGG-16 (3)

This step is followed to convert the .hdf5 file format of Keras to .pb file format of Tensor-Flow. The files for all the three architectures are saved so that it can be used in the future if a researcher wants to use TensorFlow instead of Keras.

4 Model Analysis

4.1 Loading the models for evaluation



Figure 80: Load model of InceptionV3 for evaluation

```
[ ] #Test DataSet Generator with Augmentation
test_generator = ImageDataGenerator(preprocessing_function=preprocess_input)
[ ] test_flow = test_generator.flow_from_directory(
    'test',
    shuffle=False,
    target_size=(299, 299),
    batch_size = 32
)
```

[→ Found 1256 images belonging to 6 classes.

Figure 81: Test dataset generator of InceptionV3 for evaluation

[] import math import numpy as np

Figure 82: Importing libraries for InceptionV3 for evaluation

- [] predictions = model.predict_generator(
 test_flow,
 verbose=1,
 steps=math.ceil(test_flow.samples/test_flow.batch_size))
 predicted_classes = np.argmax(predictions, axis=1)
- [→ 40/40 [======] 320s 8s/step

Figure 83: Predict generator of InceptionV3 for evaluation (1)

[] true_classes = test_flow.classes

```
[ ] class_labels = list(test_flow.class_indices.keys())
```

Figure 84: Predict generator of InceptionV3 for evaluation (2)

[] from keras.models import load_model
 model = load_model('top_layers.mn.hdf5')

[] from keras.preprocessing.image import ImageDataGenerator from keras.applications.mobilenet import preprocess_input

[→ Found 1256 images belonging to 6 classes.

Figure 85: Load model of MobileNet for evaluation

Figure 86: Load model of VGG-16 for evaluation

Models for all the three architectures, InceptionV3, MobileNet and VGG-16 are loaded. Predict generator is used to generate predictions and passed onto the dataset which is further used by the analysis functions. Batch size is set to 32 and Target size of the images is 299x299 for InceptionV3 and 224x224 for MobileNet and VGG-16.

4.2 Confusion Matrix

```
[ ] import matplotlib.pyplot as plt
%matplotlib inline
import scikitplot as skplt
```

Figure 87: Code for the confusion matrix (1)

```
[ ] [print(k, ":", v) for k,v in enumerate(class_labels)]
C 0 : Collared_Peccary
1 : European_Hare
2 : Ocelot
3 : Red_Deer
4 : Red_Deer
5 : White-nosed_Coati
```

Figure 88: Code for the confusion matrix (2)

```
[ ] true_map_classes = [class_labels[x] for x in true_classes]
```

[] predicted_map_classes = [class_labels[x] for x in predicted_classes]

Figure 89: Code for the confusion matrix (3)



Figure 90: Code for the confusion matrix (4)



Figure 91: Confusion Matrix for InceptionV3



Figure 92: Confusion Matrix for MobileNet



Figure 93: Confusion Matrix for VGG-16

4.3 Classification Report

C→

```
[ ] from sklearn.metrics import classification_report
[ ] report = classification_report(
    true_classes,
    predicted_classes,
    target_names=class_labels)
```

[] print(report)

Figure 94: Code for the classification report

C→		precision	recall	f1-score	support
	Collared_Peccary European_Hare Ocelot Red_Deer Red_Squirrel	0.45 0.54 0.80 0.86 0.00	0.83 0.28 0.59 0.90 0.00	0.58 0.37 0.68 0.88 0.00	101 141 111 567 76
	White-nosed_Coati	0.61	0.68	0.64	260
	accuracy macro avg weighted avg	0.54 0.68	0.55 0.70	0.70 0.52 0.68	1256 1256 1256

Figure 95: Classification report for InceptionV3

precision	recall	f1-score	support
0.85	0.28	0.42	101
0.59	0.50	0.54	141
0.64	0.81	0.72	111
0.85	0.88	0.86	567
0.12	0.21	0.16	76
0.61	0.57	0.59	260
		0.68	1256
0.61	0.54	0.55	1256
0.71	0.68	0.68	1256
	precision 0.85 0.59 0.64 0.85 0.12 0.61 0.61 0.71	precision recall 0.85 0.28 0.59 0.50 0.64 0.81 0.85 0.88 0.12 0.21 0.61 0.57 0.61 0.54 0.71 0.68	precision recall f1-score 0.85 0.28 0.42 0.59 0.50 0.54 0.64 0.81 0.72 0.85 0.88 0.86 0.12 0.21 0.16 0.61 0.57 0.59 0.68 0.61 0.54 0.61 0.54 0.55 0.71 0.68 0.68

Figure 96: Classification report for MobileNet

C→		precision	recall	f1-score	support
Collar	ed_Peccary	0.67	0.32	0.43	101
Eur	opean_Hare	0.46	0.96	0.62	141
	Ocelot	0.61	0.72	0.66	111
	Red_Deer	0.99	0.66	0.79	567
Re	d_Squirrel	0.05	0.07	0.05	76
White-n	osed_Coati	0.53	0.60	0.57	260
	accuracy			0.62	1256
	macro avg	0.55	0.55	0.52	1256
We	ighted avg	0.72	0.62	0.64	1256

Figure 97: Classification report for VGG-16

Classification report shows the values of precision, recall, f-1 score and support for each of the classes. Also, it shows the overall f-1 score for each of the models.

4.4 Precision-Recall Curve

[] skplt.metrics.plot_precision_recall(
 true_classes,
 predictions,
 figsize=(12,12))

Figure 98: Code for plotting the precision-recall curve



Figure 99: Precision-Recall Curve for InceptionV3



Figure 100: Precision-Recall Curve for MobileNet



Figure 101: Precision-Recall Curve for VGG-16

Precision-Recall curve for the architectures InceptionV3, MobileNet and VGG-16 are plotted.

4.5 Receiver Operating Characteristic (ROC) Curve

A graphical plot which shows the binary classifier system as the threshold is varied. True positive rates is plotted against the fraction of False positive rates from the negatives at different threshold settings. True positive rate (TPR) is called as sensitivity, whereas False positive rate (FPR) is one minus the true negative rate.

```
skplt.metrics.plot_roc(
    true_classes,
    predictions,
    figsize=(12,12))
```

Figure 102: Code for plotting the ROC curve



Figure 103: ROC Curve for InceptionV3



Figure 104: ROC Curve for MobileNet



Figure 105: ROC Curve for VGG-16

ROC curves for InceptionV3, MobileNet and VGG-16 are plotted.

5 Environment Setup

	Hardwara Specific	ation			
System RAM	Function DAM Decomposition Specification				
8 CD	Intel COPF 15	1 80CHg Intel Core			
0 GD	Ath Con	5 925011 CDU and			
	oun Gen	15-82500 CF0 and			
		an AMD Radeon 530			
		GPU			

Table 1: Hardware

10010 - 00101000	Table	2:	Software
------------------	-------	----	----------

Software Specification		
Google Colab,	OpenCV,	MatPlot Lib,
Python3,	NumPy	ScikitPlot,
TensorFlow,		Pygal
Keras		

Figure 106: Environment Setup

References

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